

“The Revolution Will Not Be Supervised!”

(almost) 10 Years Later: A Personal Journey



Photo from Santiago,
ICCV 2015



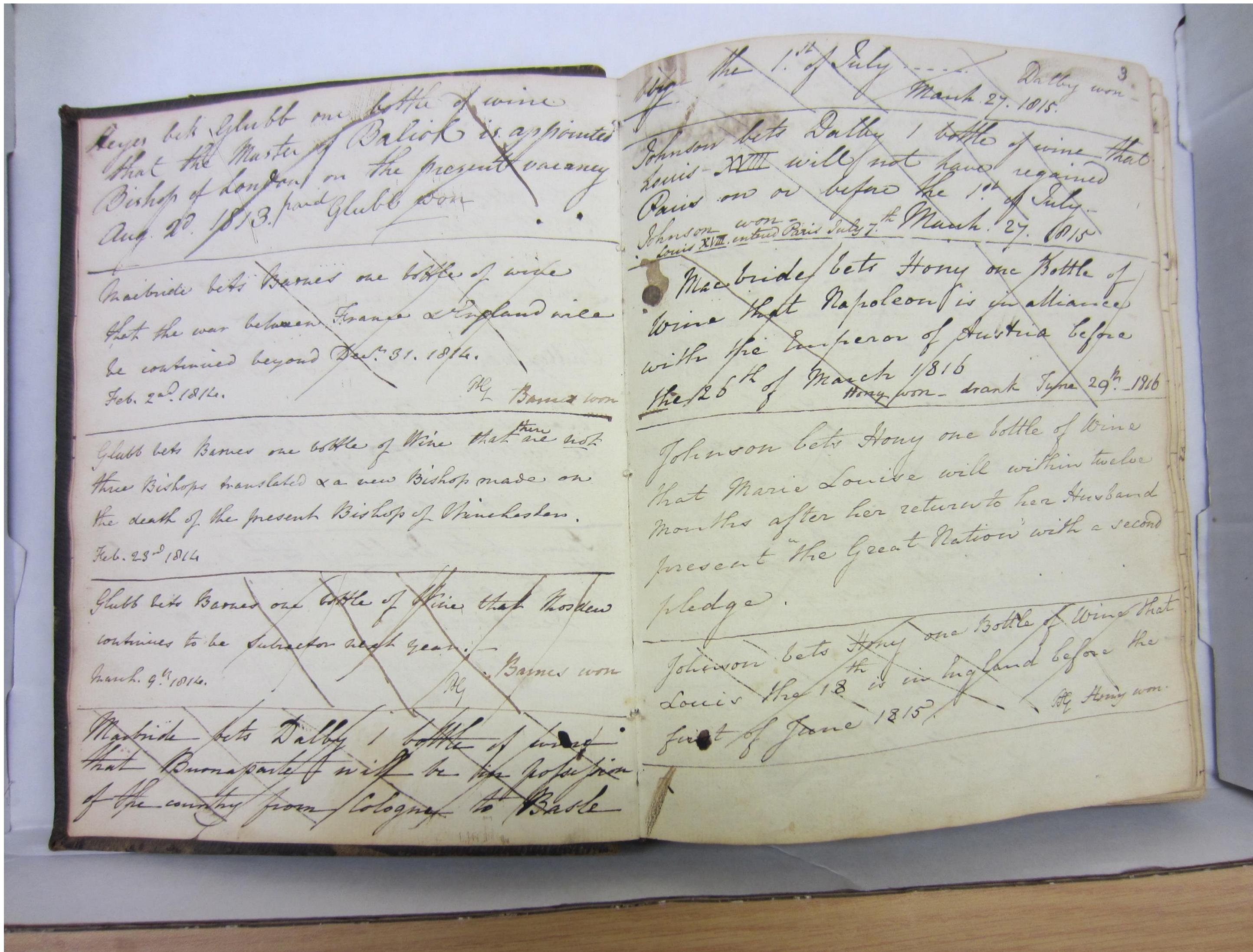
BAIR

BERKELEY ARTIFICIAL INTELLIGENCE RESEARCH

Alexei A. Efros
UC Berkeley

It all started with a bet...

Long Tradition of Scientific Bets



Betting Book
Exeter College
Oxford
1815

The Gelato Bet (2014)

- R-CNN just came out
 - first big success of “Pre-train + Fine-tune” paradigm
- It was surprising (to me), that ImageNet pretraining helped in PASCAL detection
 - Label sets were so different!
- Was it the labels, or just the extra visual data?

The Gelato Bet



Sept 23, 2014

*"If, by the first day of autumn (Sept 23) of 2015, a method will exist that can match or beat the performance of R-CNN on Pascal VOC detection, **without the use of any extra, human annotations** (e.g. ImageNet labels) as pre-training, Mr. Malik promises to buy Mr. Efros one (1) gelato (two scoops: one chocolate, one vanilla)."*

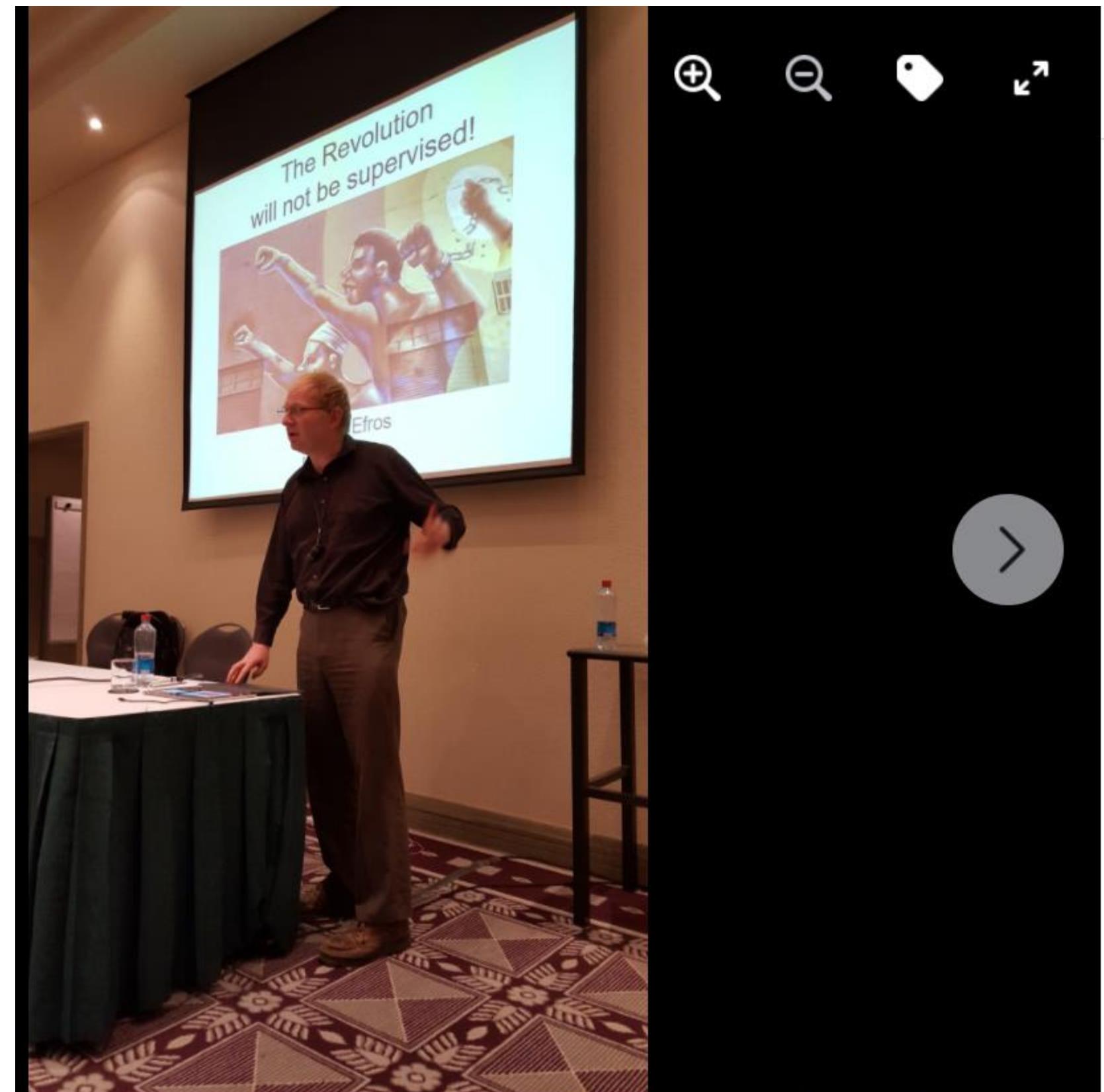
One year later...

- Of course, I lost the bet:



One year later...

- ...but:
 - First 4 self-supervised papers presented at **ICCV 2015**
 - Doersch et al, Agrawal et al, Wang et al, and Jayaraman et al.
 - Yann LeCun liked my talk and posted on FB
 - The rest is history...



 Yann LeCun December 17, 2015 · 

Alyosha Efros tells us the revolution will not be supervised at the ICCV Workshop on Object Understanding from Interactions.

I agree.
— with Alyosha Efros.

 259 25 Comments 13 Shares

 Like  Comment  Share

[View 5 previous comments](#)

 Nando De Freitas What does the slide mean? 

 Write a comment...   

Why do we have vision?

- “To see what is where by looking”
 - Aristotle, Marr, etc
- .
- .
- .
- .
- .
- .
- .
- “To make babies who make babies, etc”
 - Darwin, Dawkins, etc.

Why do we have vision?

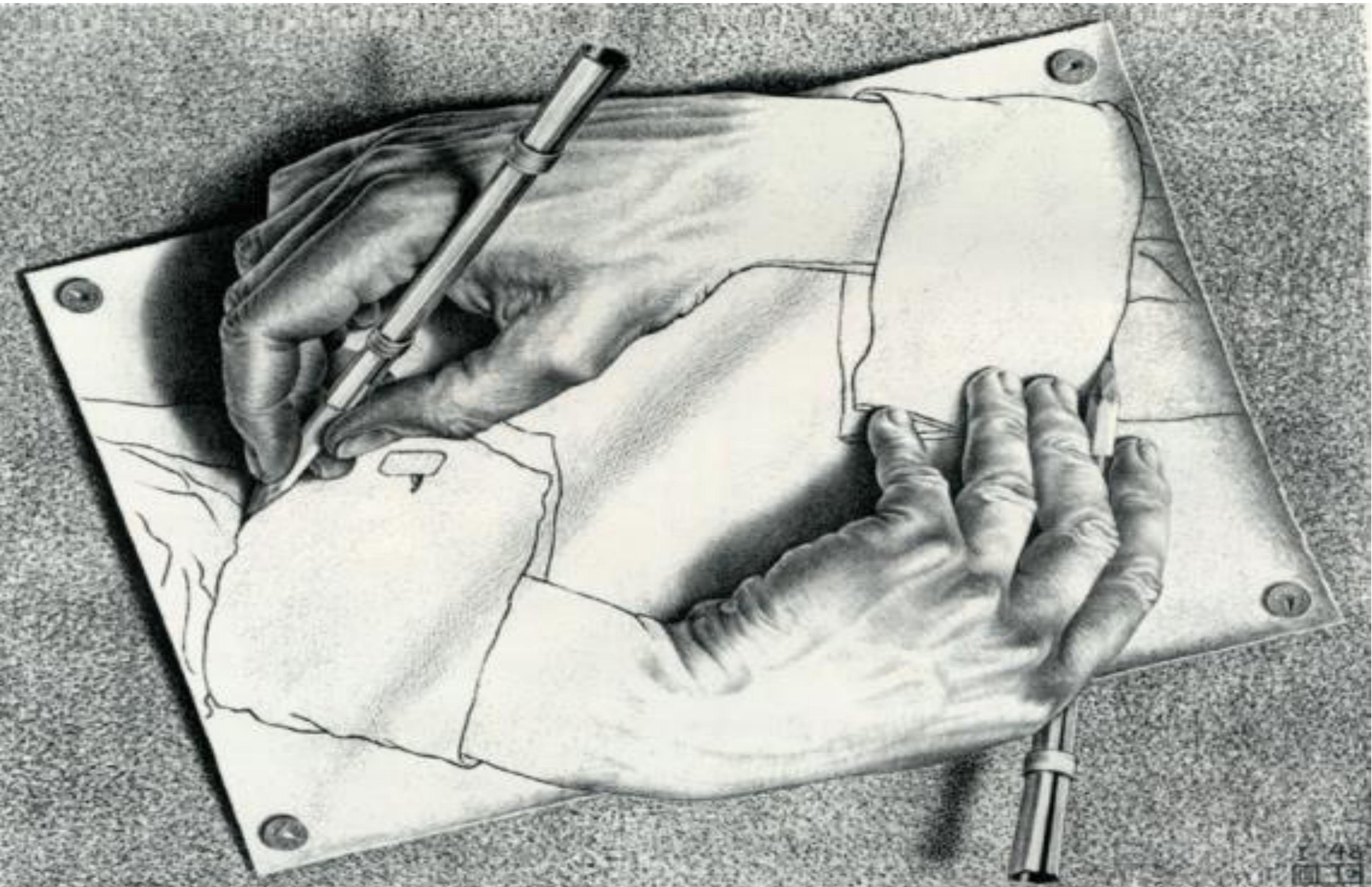
- “To see what is where by looking”
 - Aristotle, Marr, etc.
- .
- “To predict the world”
 - Jakob Uexküll, Jan Koenderink, Moshe Bar, etc.
- .
- “To make babies who make babies, etc”
 - Darwin, Dawkins, etc.

The world as supervision

Try to predict some aspect of the world that we interact with / have effect on:

- What's gonna happen next?
- What's to my left?
- What can I touch?
- What will make a sound?
- Etc.

Self-Supervision



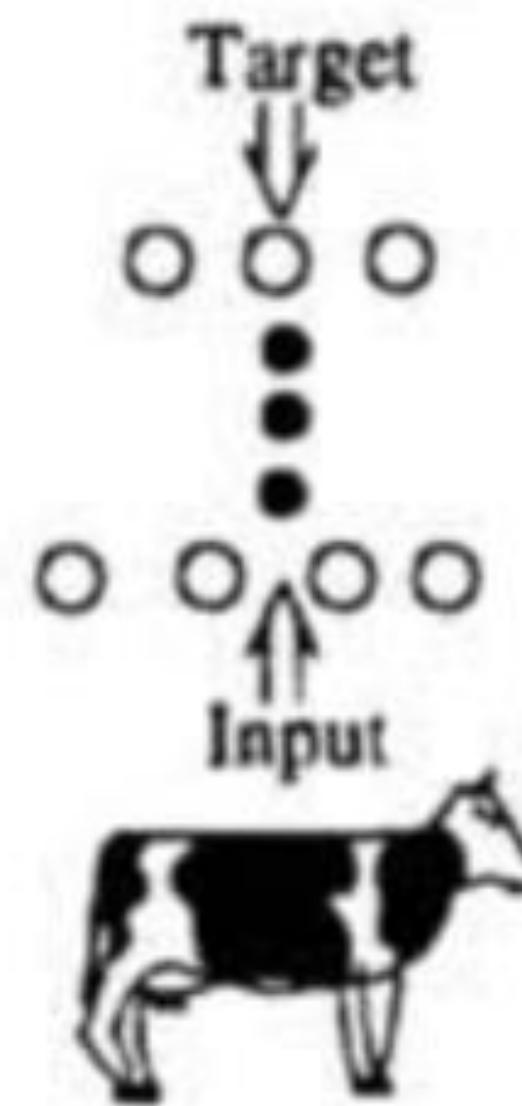
Drawing Hands, M.C. Escher, 1948

Self-Supervision in Multisensory Learning

Supervised

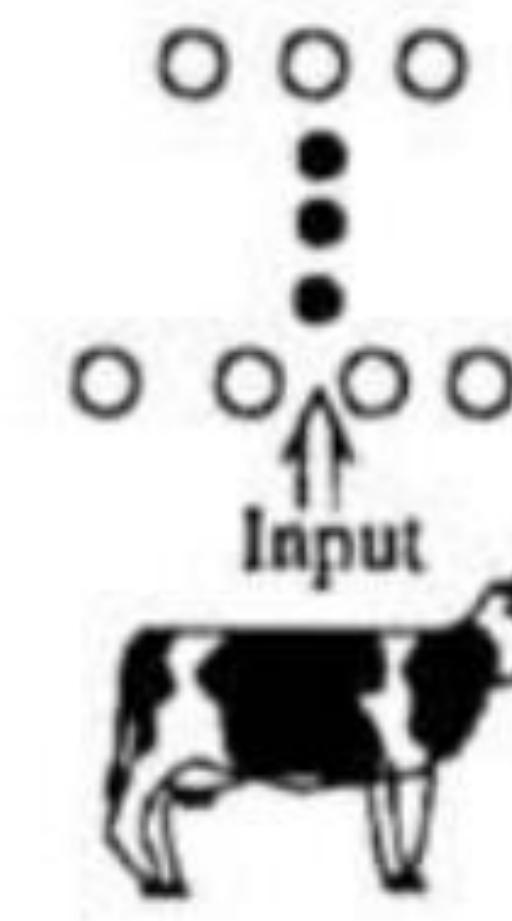
- implausible label

"COW"



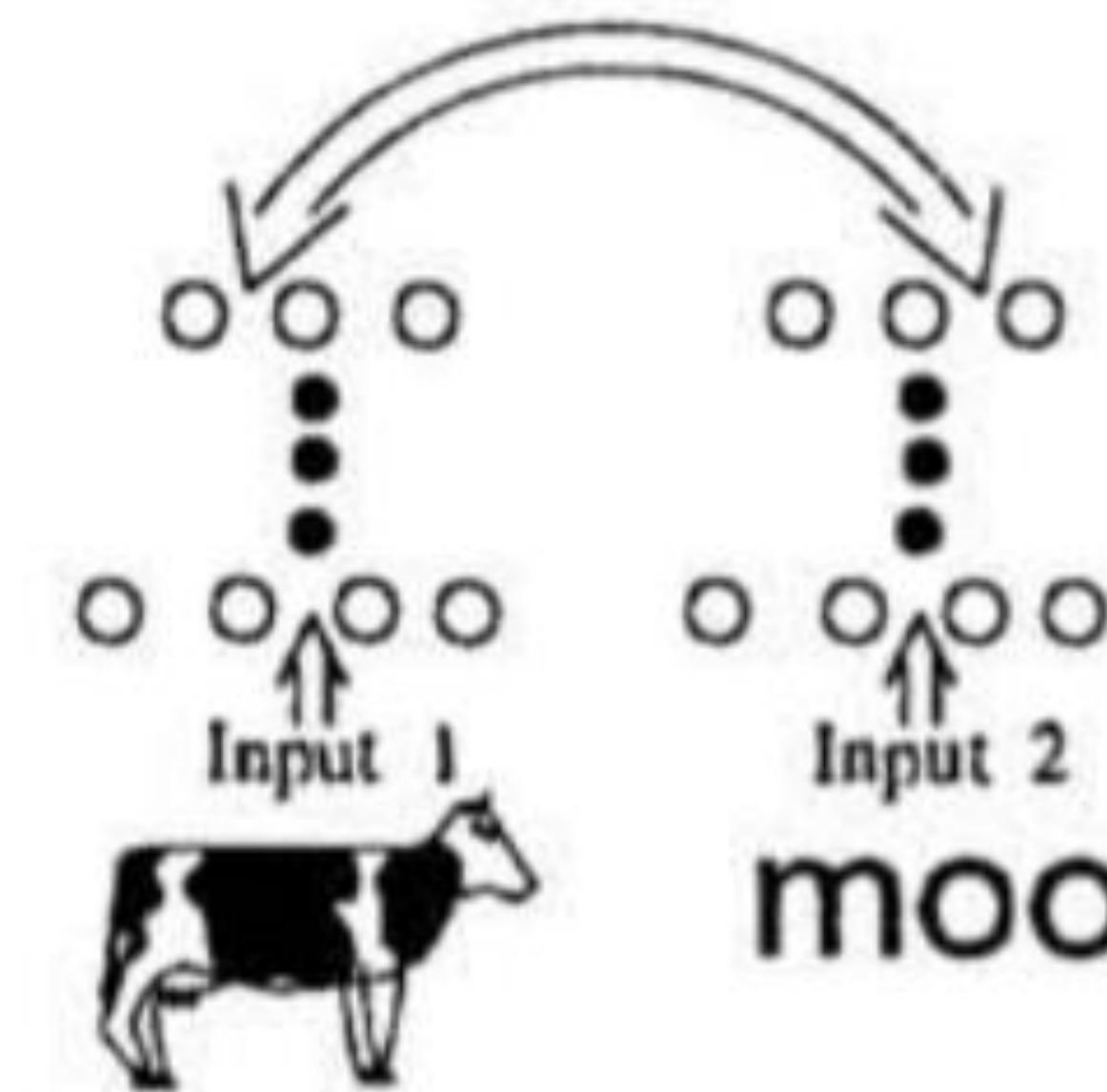
Unsupervised

- limited power



Self-Supervised

- derives label from a co-occurring input to another modality



Context as Supervision

[Collobert & Weston 2008; Mikolov et al. 2013]

house, where the professor lived without his wife and child; or so he said jokingly sometimes: "Here's where I live. My house." His daughter often added, without resentment, for the visitor's information, "It started out to be for me, but it's really his." And she might reach in to bring forth an inch-high table lamp with fluted shade, or a blue dish the size of her little fingernail, marked "Kitty" and half full of eternal milk, but she was sure to replace these, after they had been admired, pretty near exactly where they had been. The little house was very orderly, and just big enough for all it contained, though to some tastes the bric-à-brac in the parlor might seem excessive. The daughter's preference was for the store-bought gimmicks and appliances, the toasters and carpet sweepers of Lilliput, but she knew that most adult visitors would

Deep
Net

(Partial) Taxonomy of Self-Supervision

Data prediction



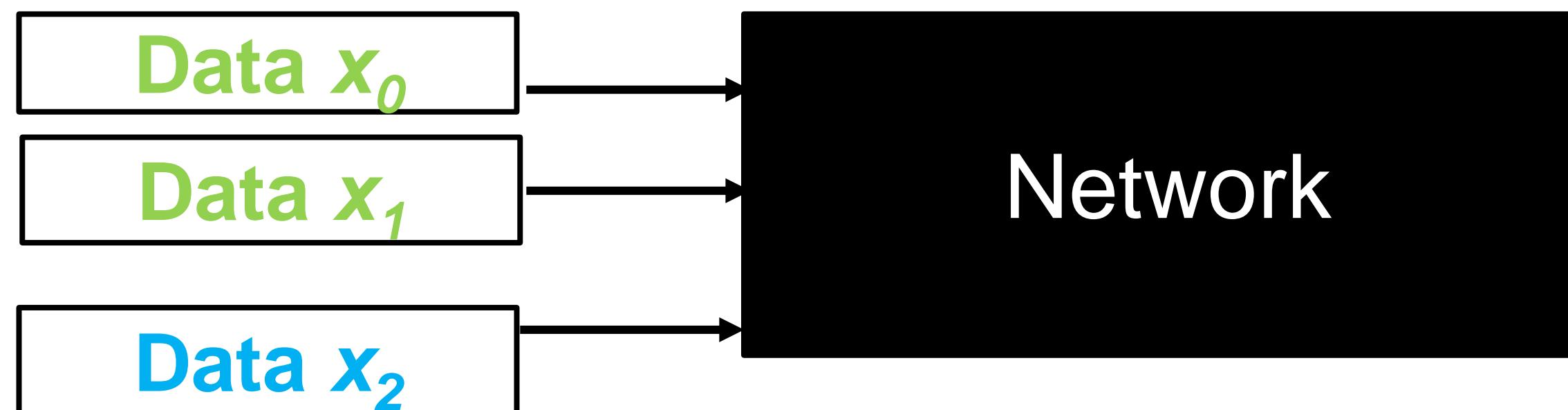
Transformation prediction



Supervision via constraints



Instance Learning

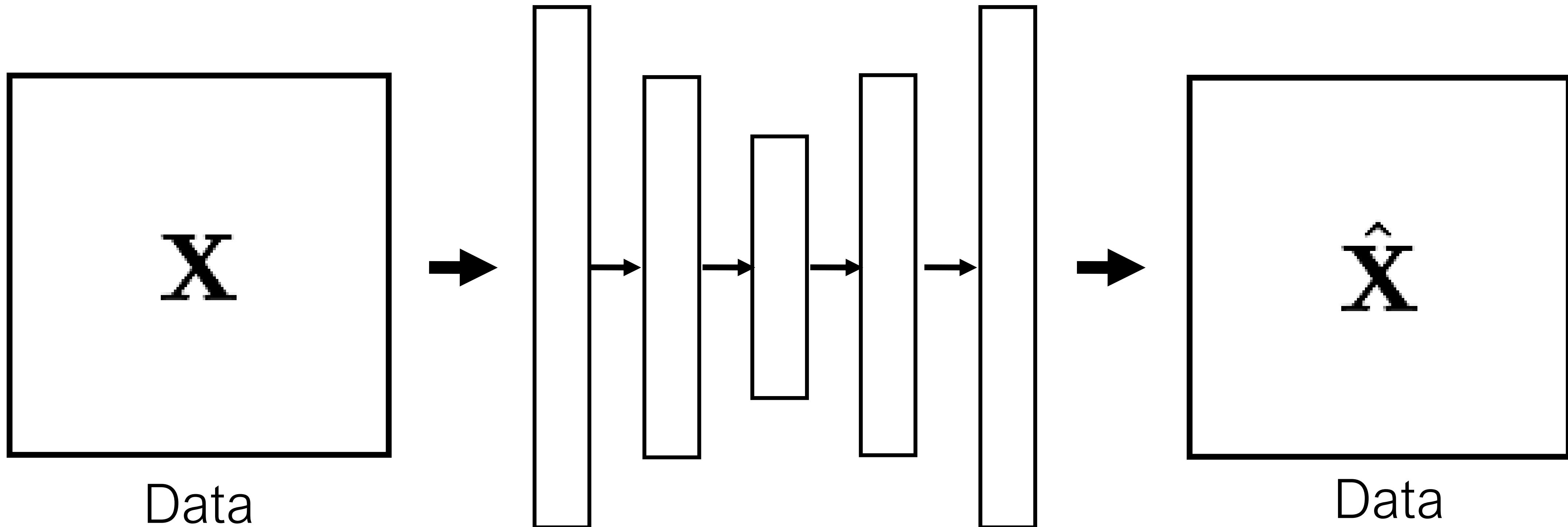


(Partial) Taxonomy of Self-Supervision

Data prediction

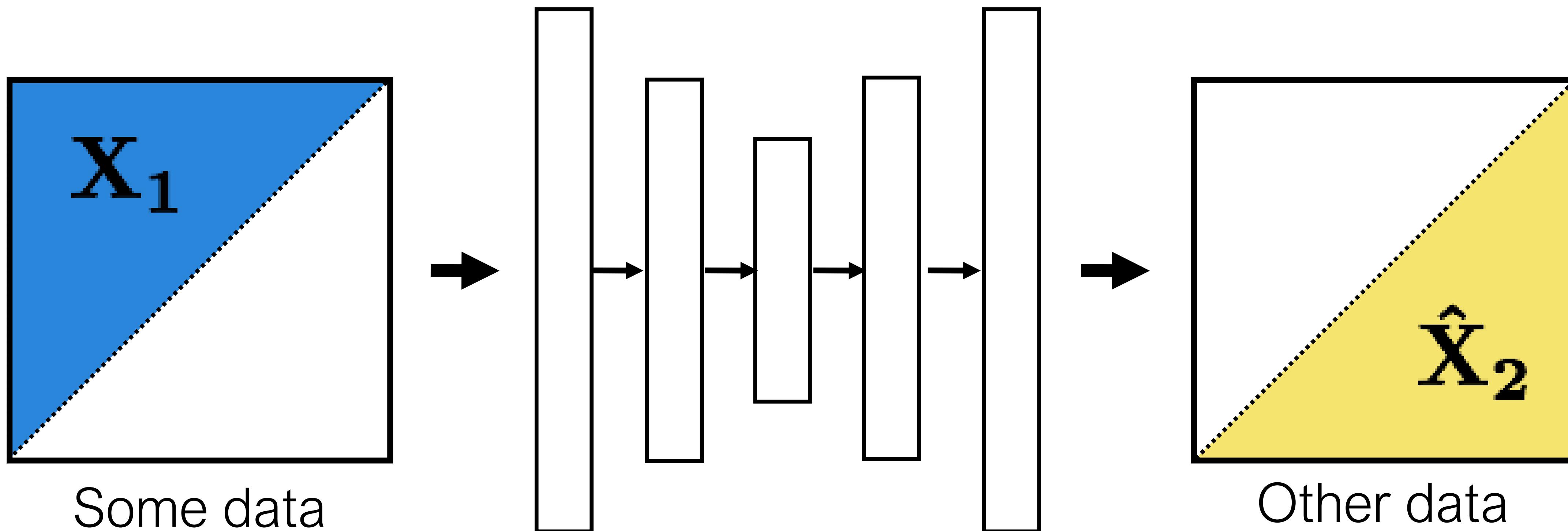


Self-supervision as data compression



Autoencoders [Hinton & Salakhutdinov, Science 2009]

Self-supervision as data prediction





$$\xrightarrow{\mathcal{F}}$$

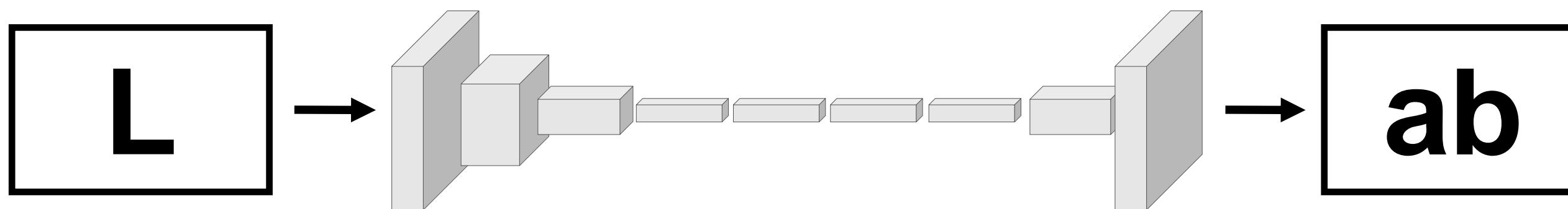


Grayscale image: L channel

$$\mathbf{X} \in \mathbb{R}^{H \times W \times 1}$$

Color information: ab channels

$$\hat{\mathbf{Y}} \in \mathbb{R}^{H \times W \times 2}$$



[Zhang, Isola, Efros, ECCV 2016]



$$\mathcal{F}$$

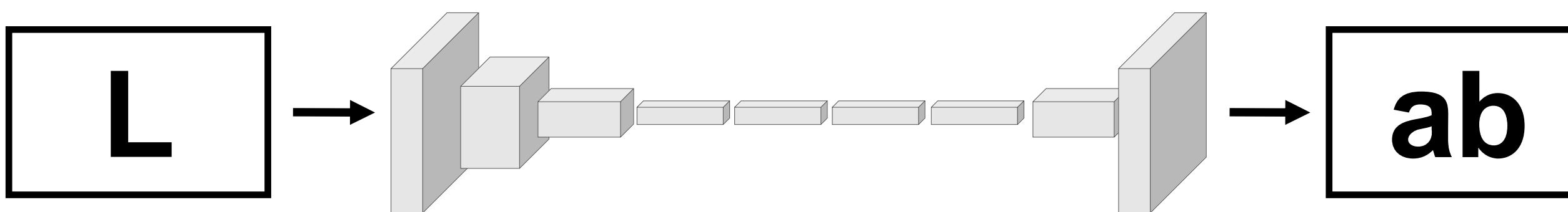


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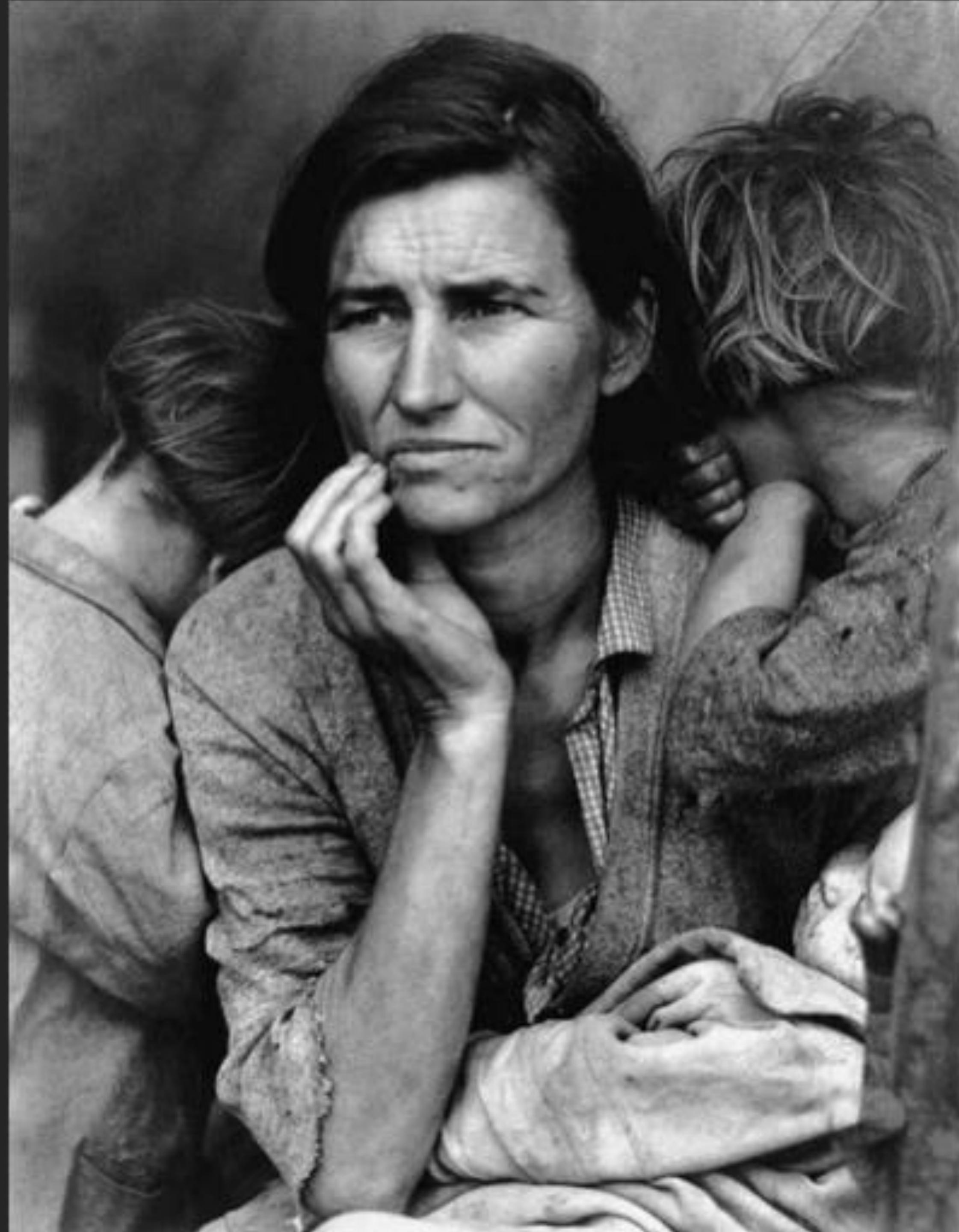
[Zhang, Isola, Efros, ECCV 2016]



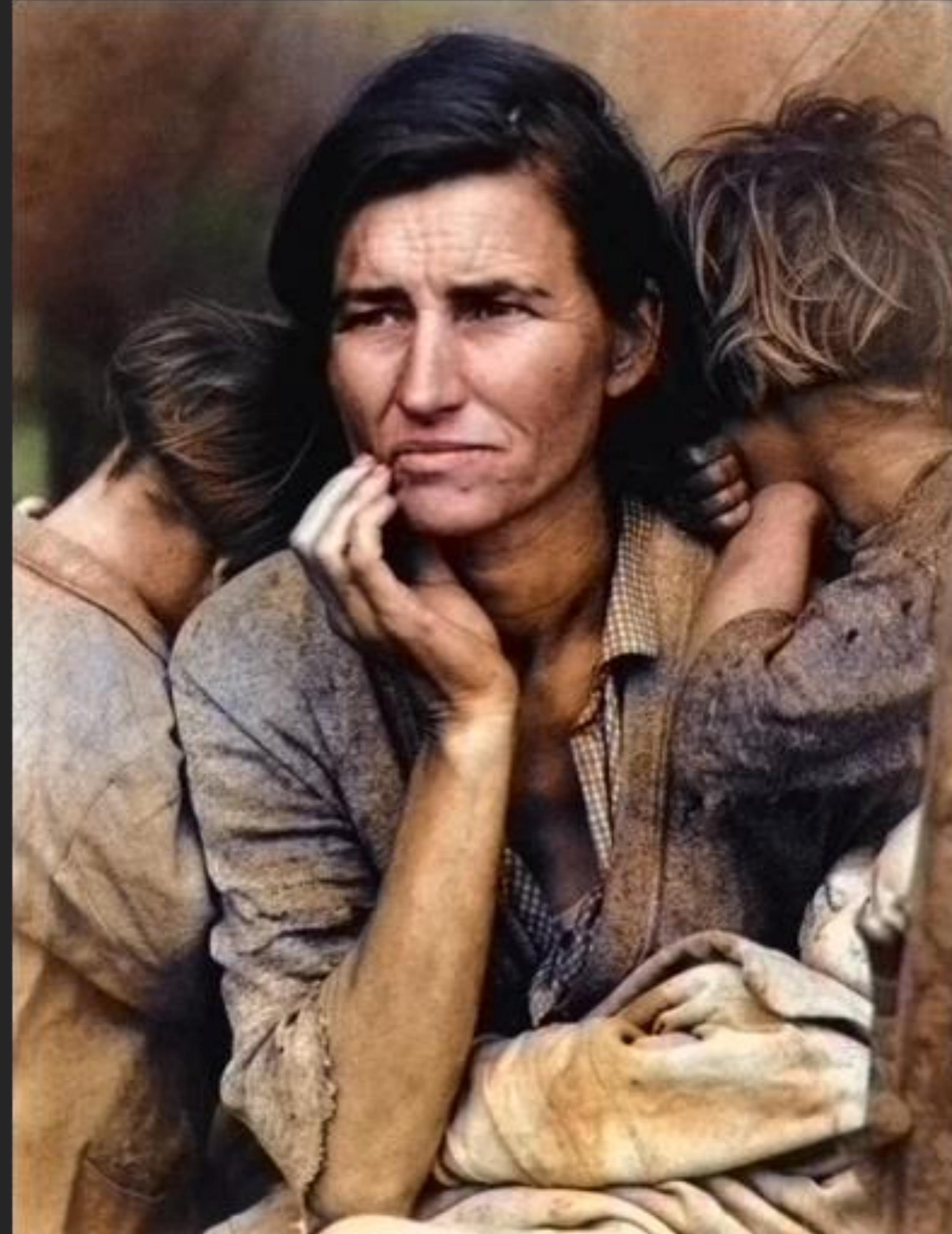
Ansel Adams, Yosemite Valley Bridge



Our result



Migrant Mother
Dorothea Lange
1936



Our result



$$\mathcal{F}$$



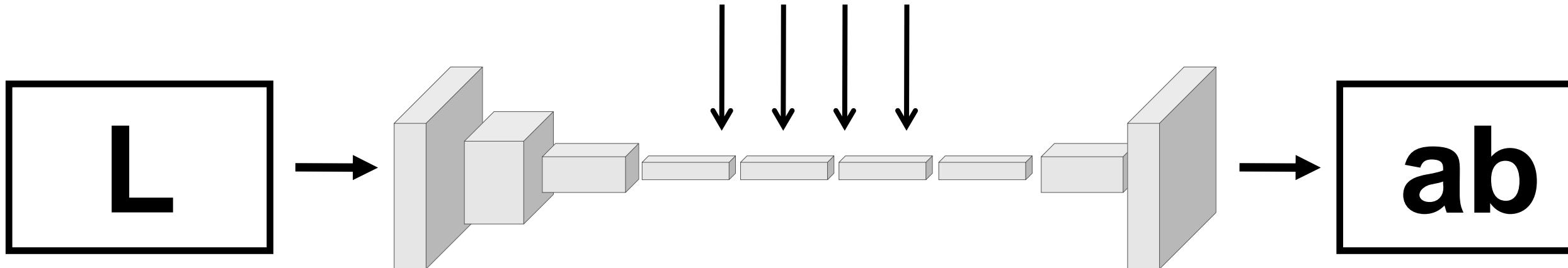
Grayscale image: L chan-

$$\mathbf{X} \in \mathbb{R}^{H \times W \times 1}$$

Semantics? Higher-
level abstraction?

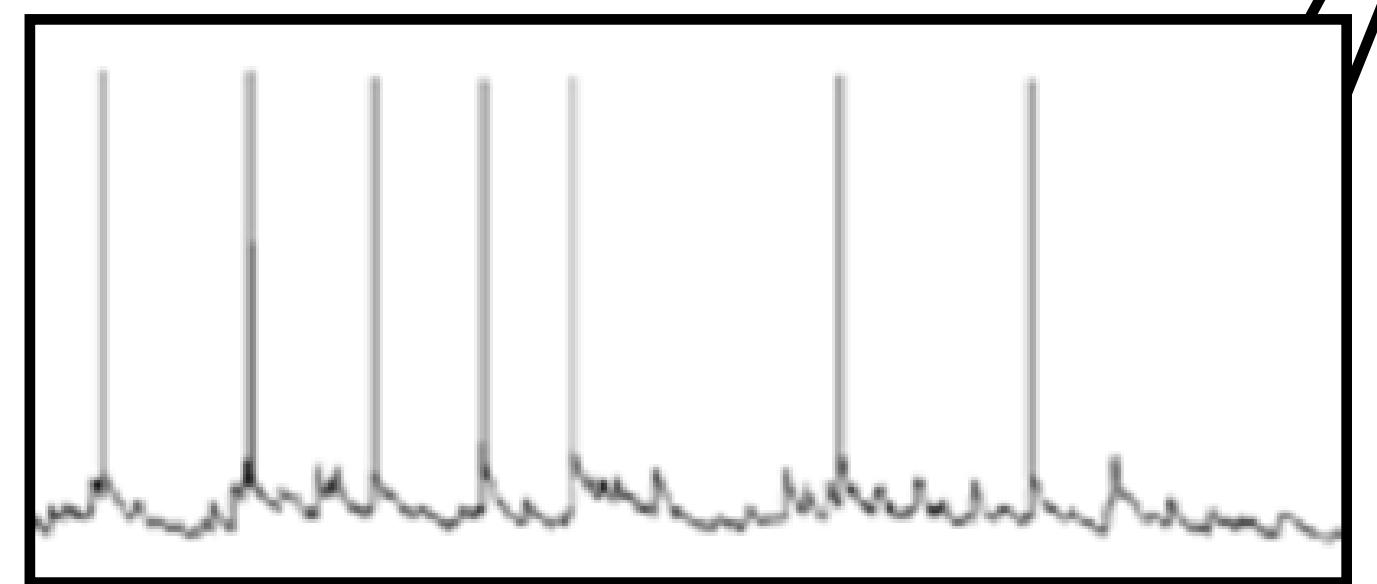
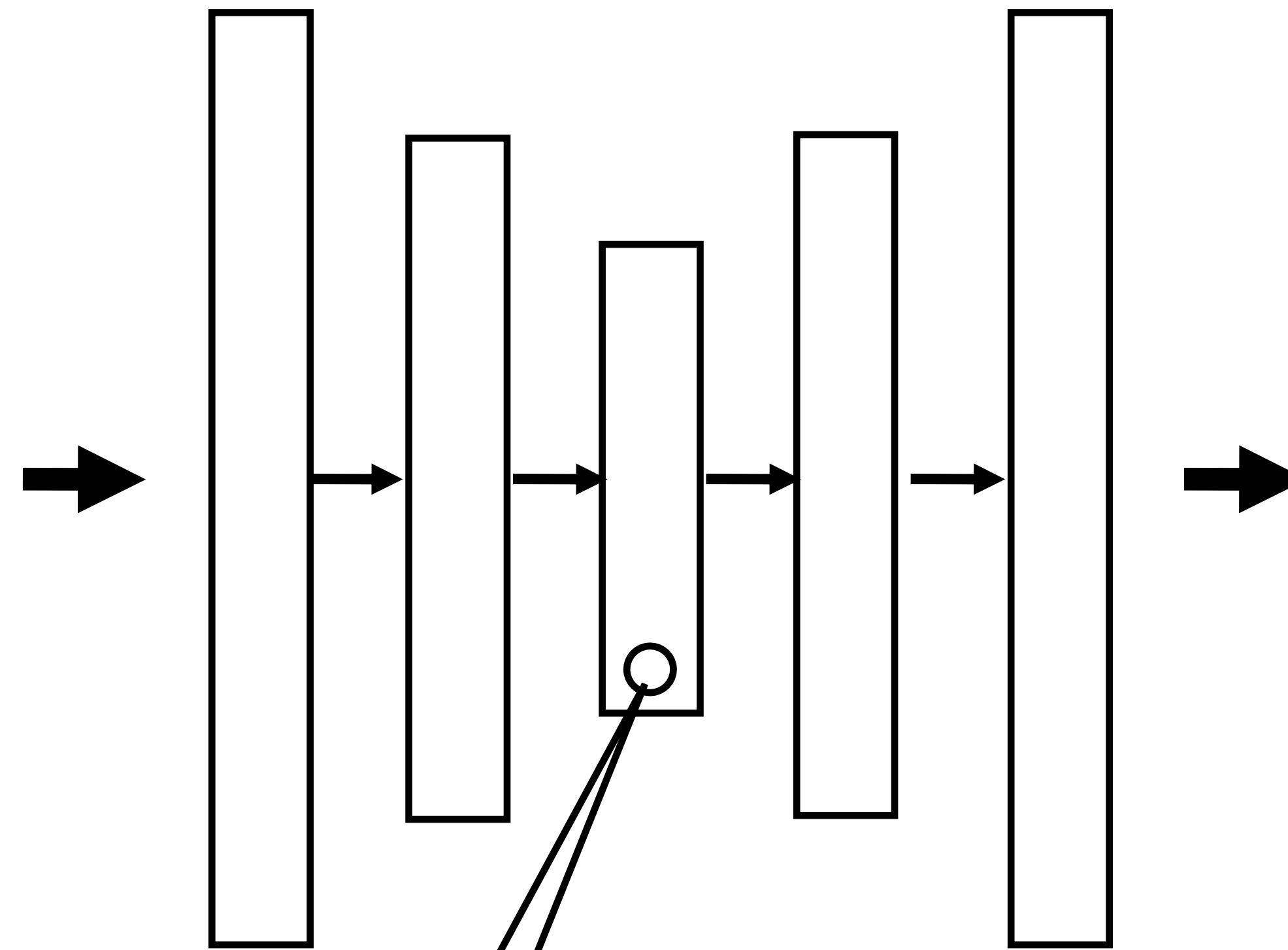
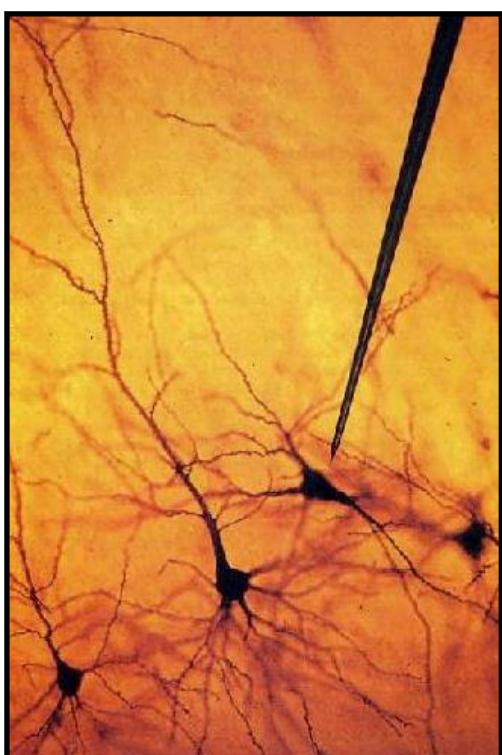
information: ab channels

$$\hat{\mathbf{Y}} \in \mathbb{R}^{H \times W \times 2}$$



[Zhang, Isola, Efros, ECCV 2016]

Deep Net “Electrophysiology”



[Zeiler & Fergus, ECCV 2014]
[Zhou et al., ICLR 2015]

Hidden Unit (conv5) Activations

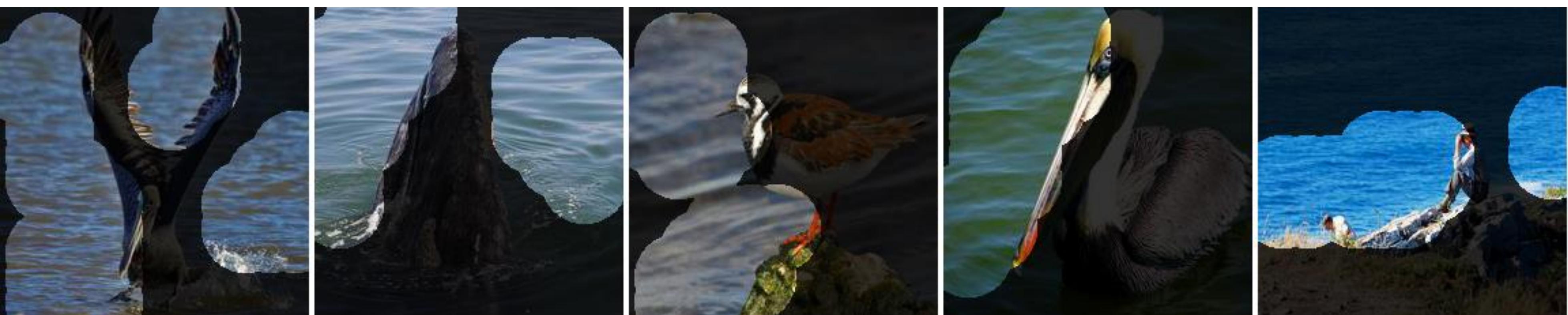
sky



trees

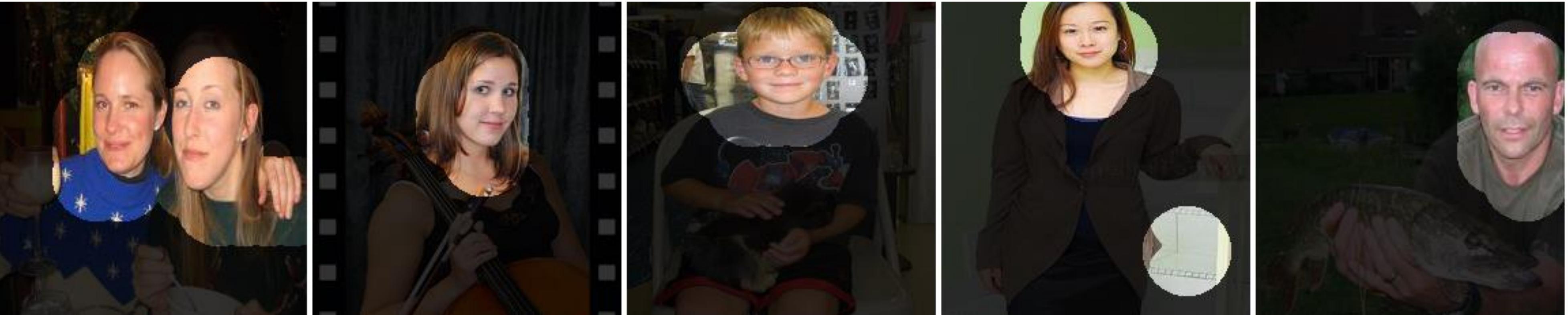


water

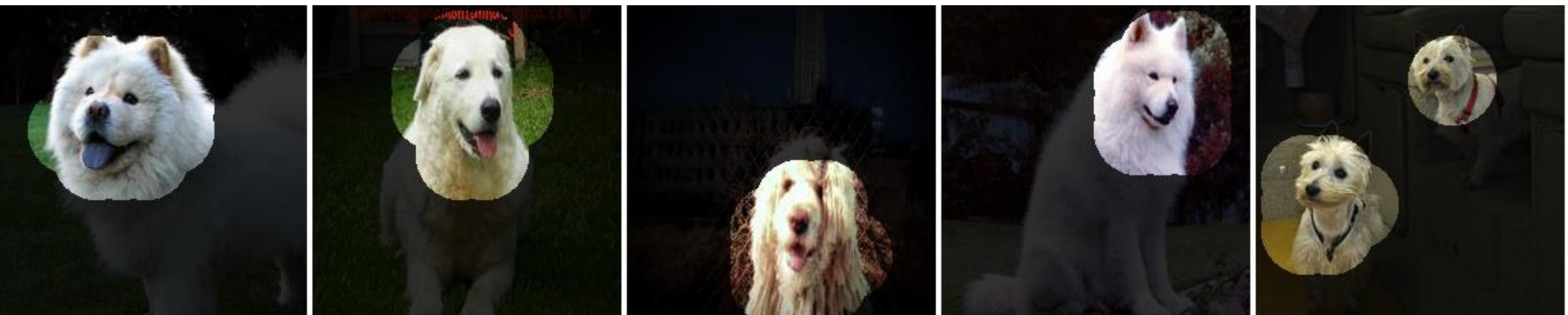


Hidden Unit (conv5) Activations

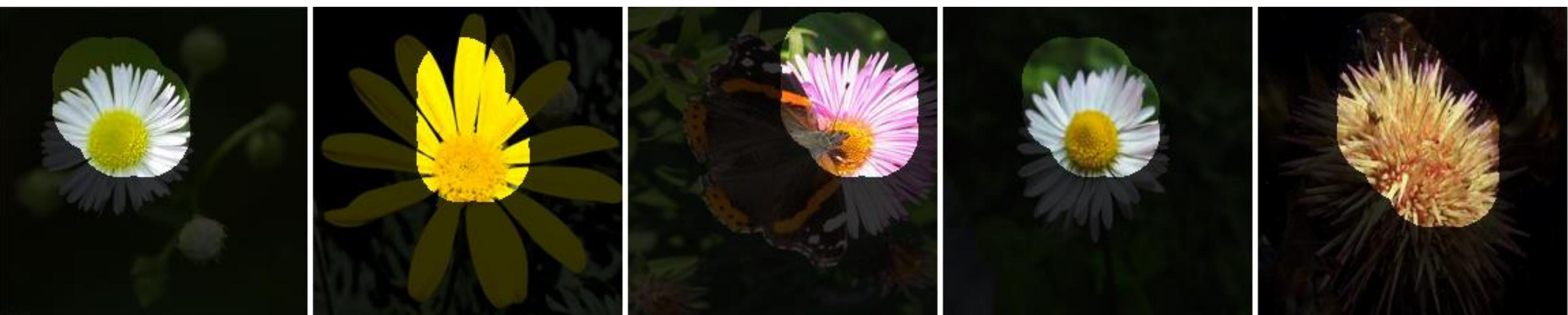
faces



dog
faces



flowers



ImageNet Linear “Probing” – big mistake!

12

Zhang, Isola, Efros

Dataset and Task Generalization on PASCAL [37]								
fine-tune layers	[Ref]	Class.			Det.		Seg.	
		(%mAP)	fc8	fc6-8	all	[Ref]	all	[Ref]
ImageNet [38]	-	76.8	78.9	79.9	[36]	56.8	[42]	48.0
Gaussian	[10]	–	–	53.3	[10]	43.4	[10]	19.8
Autoencoder	[16]	24.8	16.0	53.8	[10]	41.9	[10]	25.2
k-means [36]	[16]	32.0	39.2	56.6	[36]	45.6	[16]	32.6
Agrawal et al. [8]	[16]	31.2	31.0	54.2	[36]	43.9	–	–
Wang & Gupta [15]	–	28.1	52.2	58.7	[36]	47.4	–	–
*Doersch et al. [14]	[16]	44.7	55.1	65.3	[36]	51.1	–	–
*Pathak et al. [10]	[10]	–	–	56.5	[10]	44.5	[10]	29.7
*Donahue et al. [16]	–	38.2	50.2	58.6	[16]	46.2	[16]	34.9
Ours (gray)	–	52.4	61.5	65.9	–	46.1	–	35.0
Ours (color)	–	52.4	61.5	65.6	–	46.9	–	35.6

ion

Table 2. PASCAL Tests

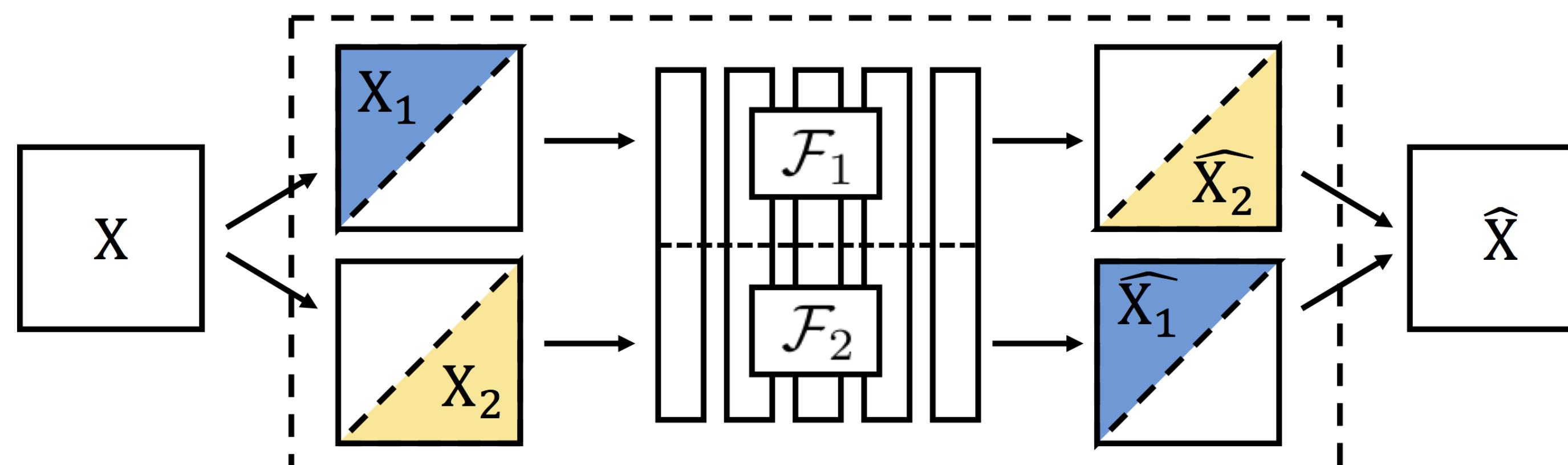
The “probe” has $2000 * 1000 = 2,000,000$ parameters!

[Zhang, Isola, Efros, ECCV 2016]

Self-supervision as data prediction



Context Encoder
Pathak et al. CVPR 2016



Split-brain Autoencoder, Zhang et al, CVPR 2017

Self-supervision as transformation predication



Context Prediction for Images

?

?

?

?

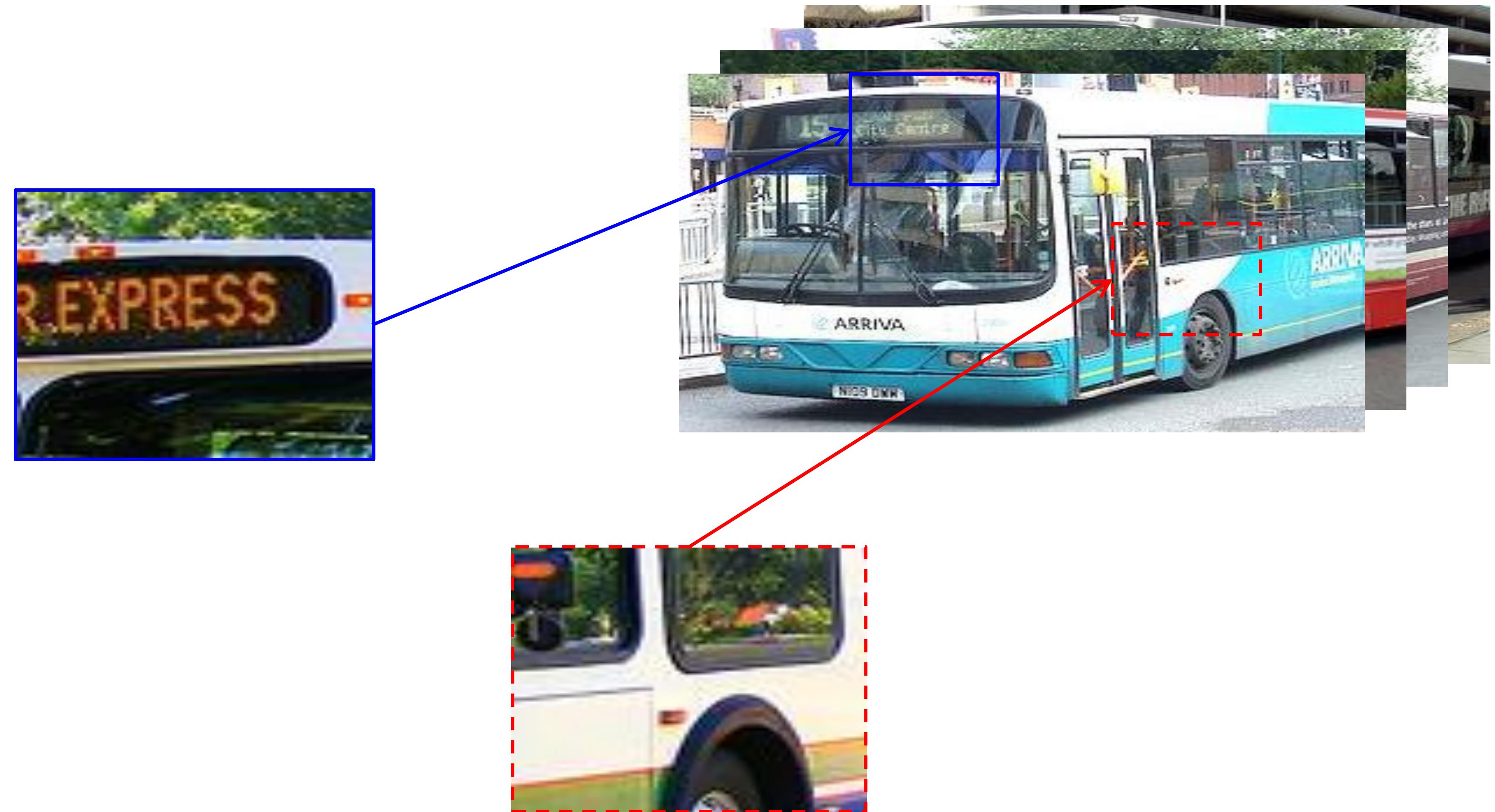


?

A
?

B
?

Semantics from a non-semantic task



Self-Supervision via Constraints



$$F(x) = y$$

- direct supervision

$$F(x) \in Y$$

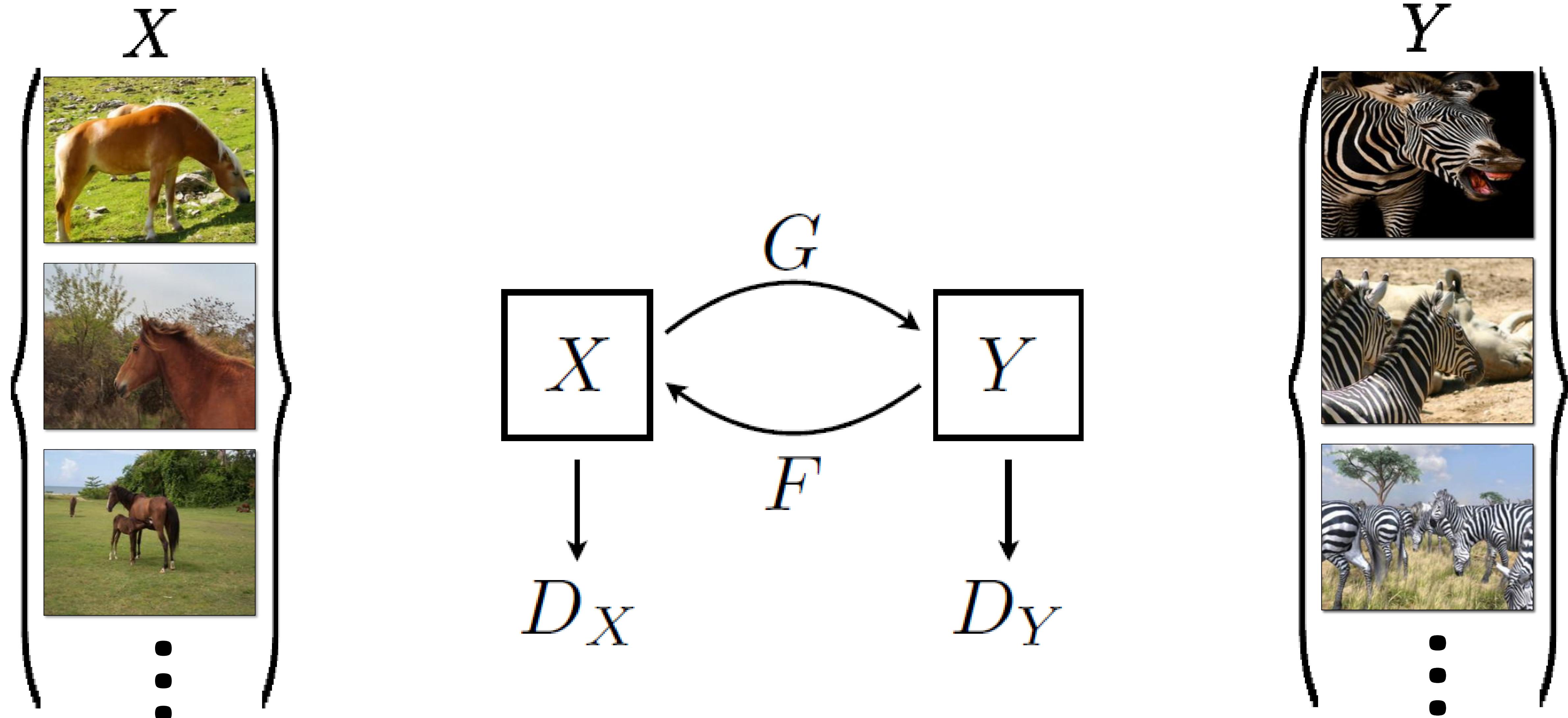
- GANs

$$G(F(x)) = x$$

- cycle-consistency

- ...

CycleGAN, or “there and back aGAN”



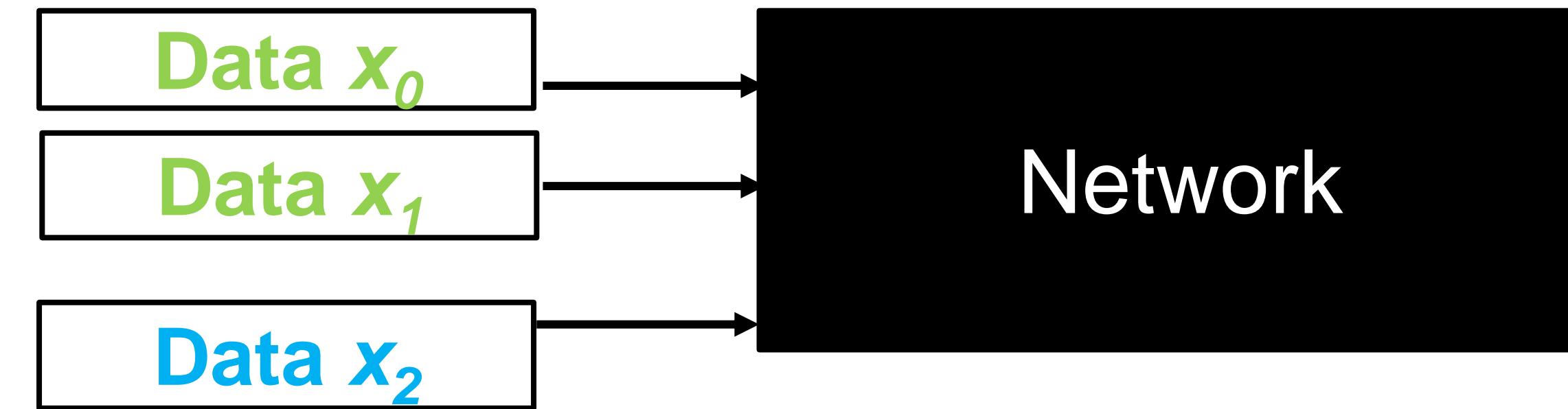
[Zhu*, Park*, Isola, Efros. ICCV 2017]

Video



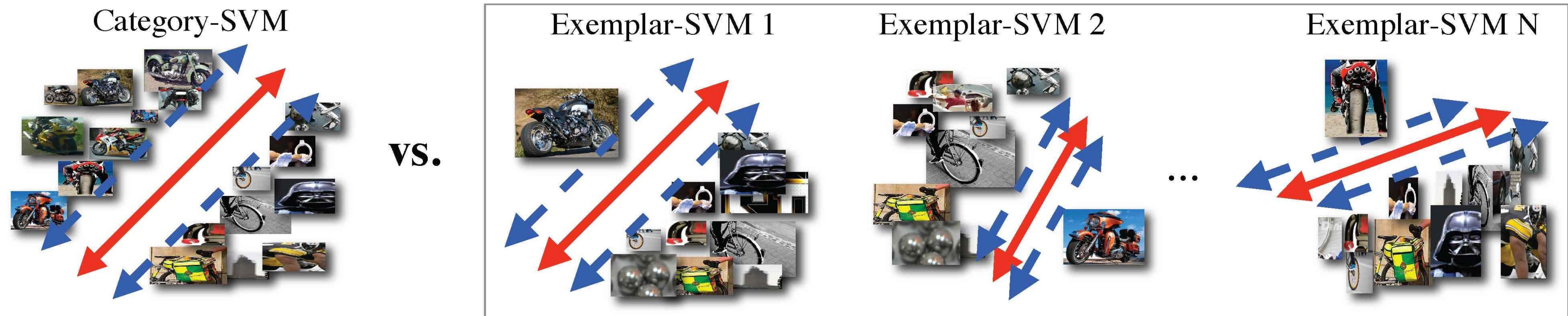
Instance Learning

Instance
Learning

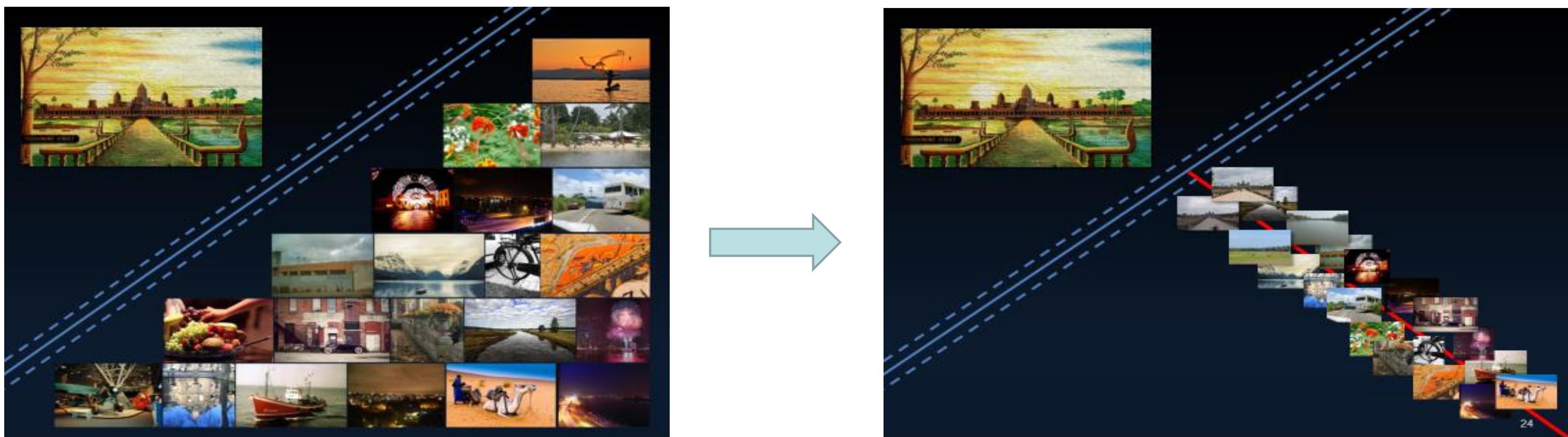


Exemplar-SVM: defining yourself by what you are not

[Malisiewicz, Gupta, Efros, ICCV'11]



One-against-all learning for image retrieval [Srivastava et al, SIGGRAPH'11]



Exemplar-CNN [Dosovitskiy et al, NIPS'14]

- single parametric representation (CNN)
- Data augmentation

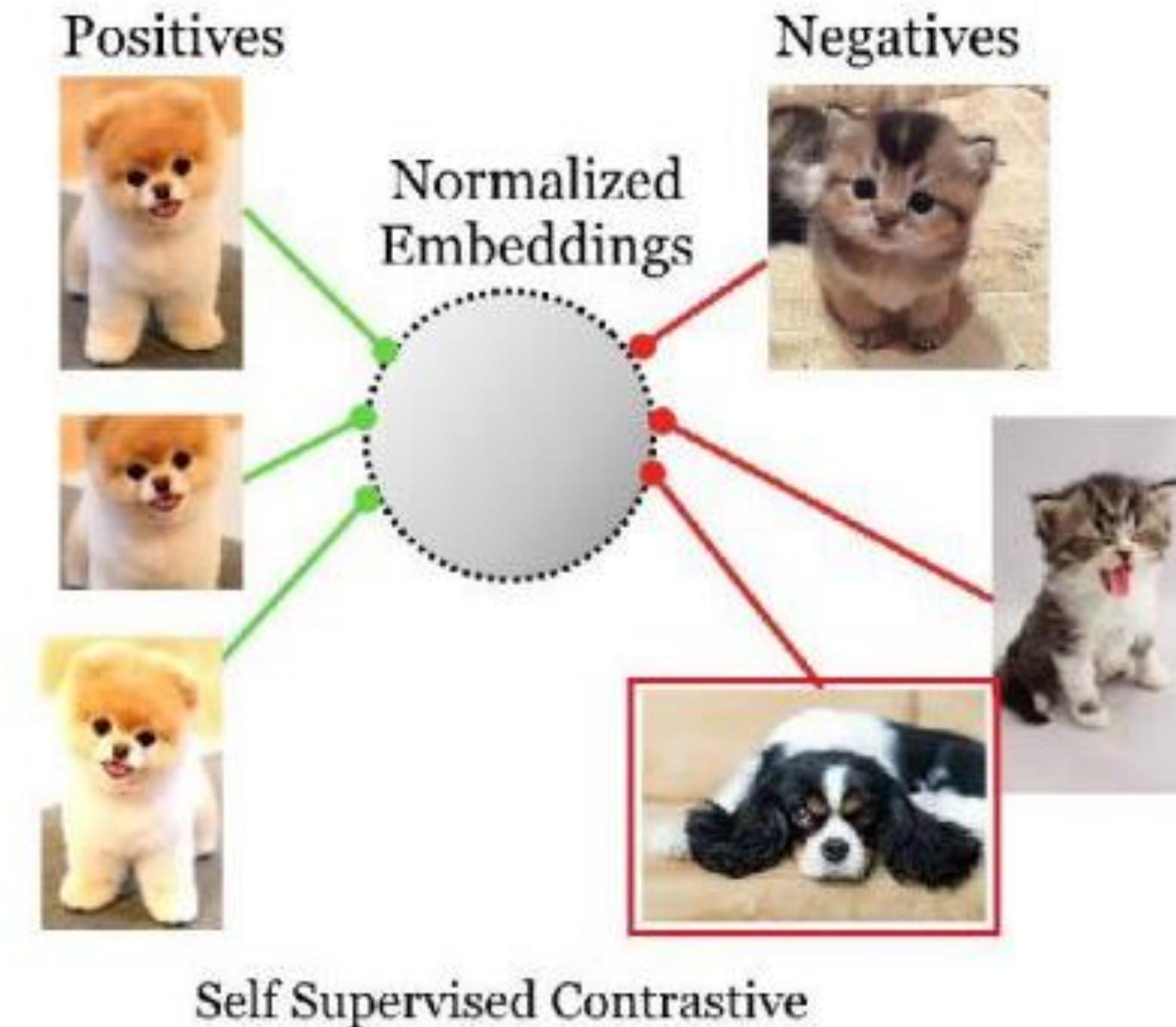


Fig. 2. Several random transformations applied to one of the patches extracted from the STL unlabeled dataset. The original ('seed') patch is in the top left corner.



Modern Day: representations via Similarity Learning

- Metric Learning
 - Siamese Nets
- Contrastive Learning
 - etc



Becker et al (1992)
de Sa (1993)
Bromley et al (1994)
Chopra et al (2005)
Dosovitsky et al (2014)
Bojanowski et al (2017)
Wu et al (2018)
van den Oord et al (2019)
Tian et al (2019)
He et al (2019)
Chen et al (2020)

1. Improvements in representation learning (e.g. Contrastive)
2. Improved Data Augmentations (e.g. cropping)

Data Augmentation



input



color

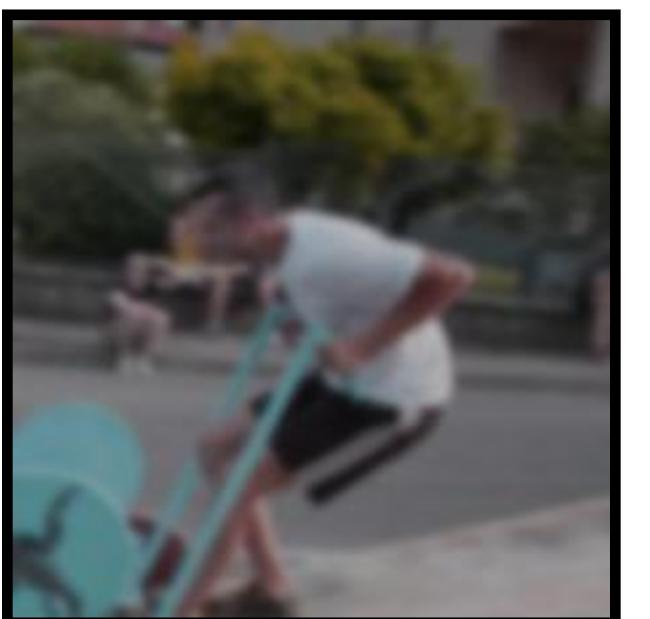
crop

flip

blur

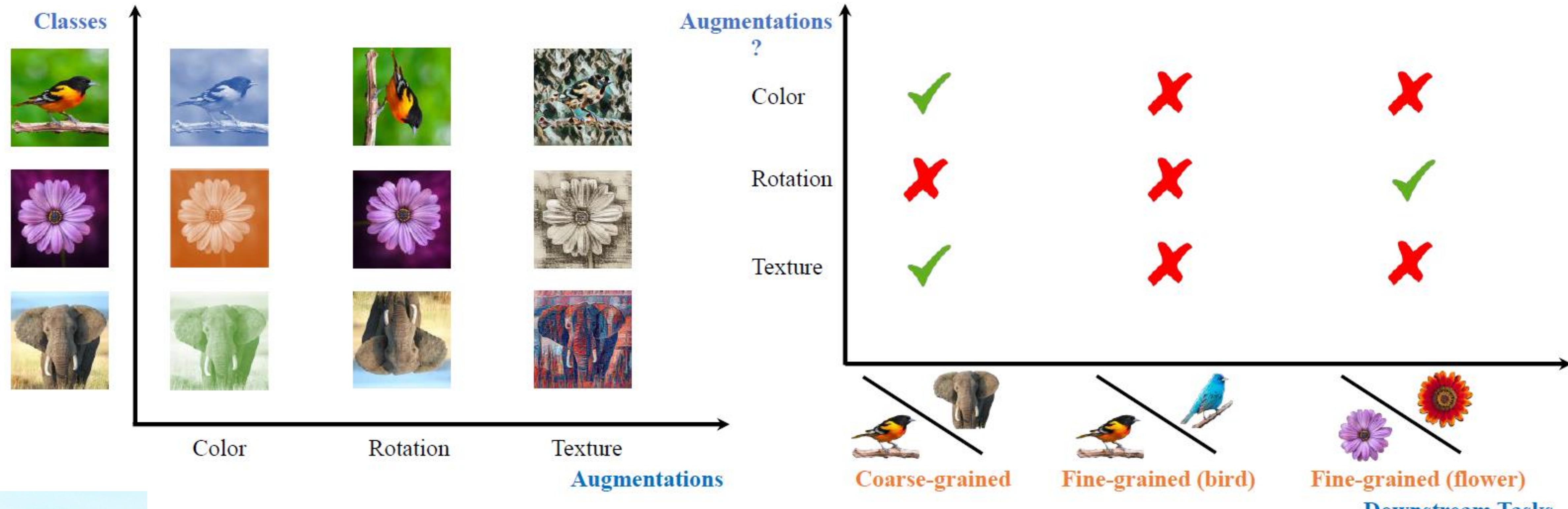


Views



SimCLR augmentations (Chen et al, 2020)

The choice of data augmentation is itself supervision



What should not be contrastive in contrastive learning
T Xiao, X Wang, AA Efros, T Darrell - ICLR 2021



So, where are we now?

(Partial) Taxonomy of Self-Supervision

Data prediction



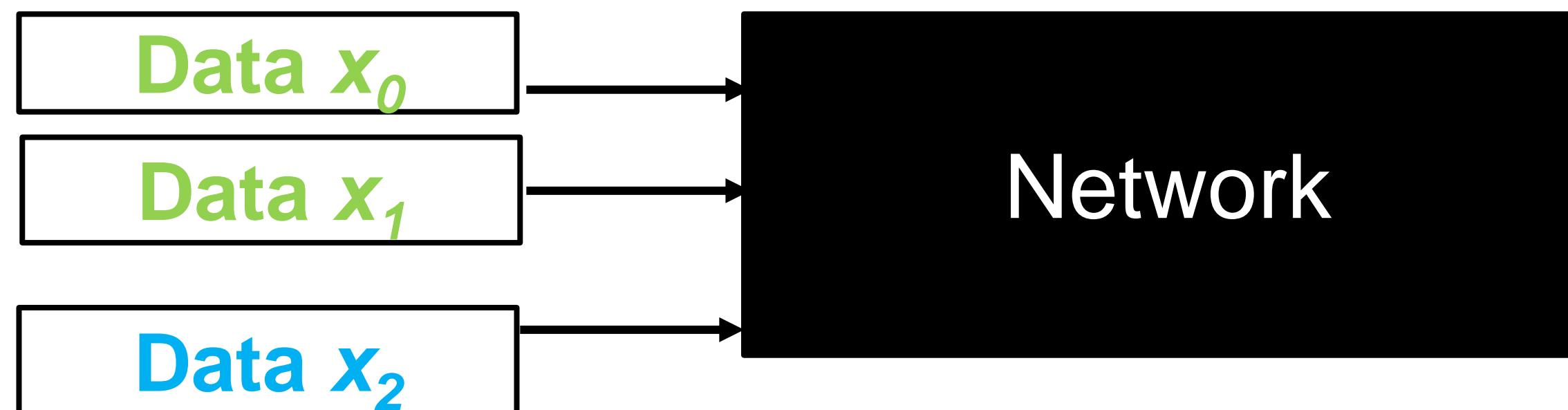
Transformation prediction



Supervision via constraints



Instance Learning



And the current winner is...

Data prediction



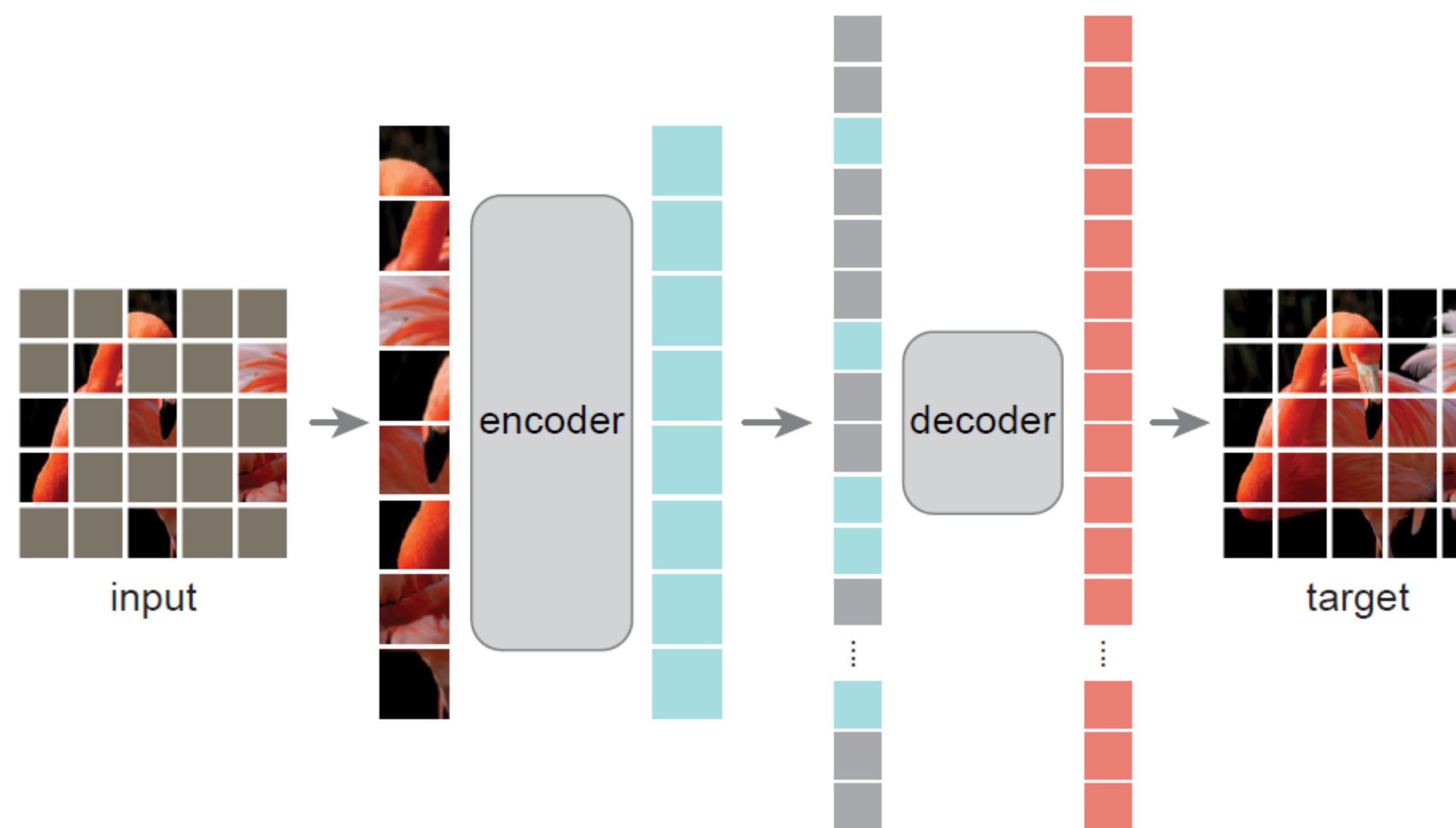
Context Encoder
Pathak et al. CVPR 2016



Masked Autoencoder
He et al. 2021

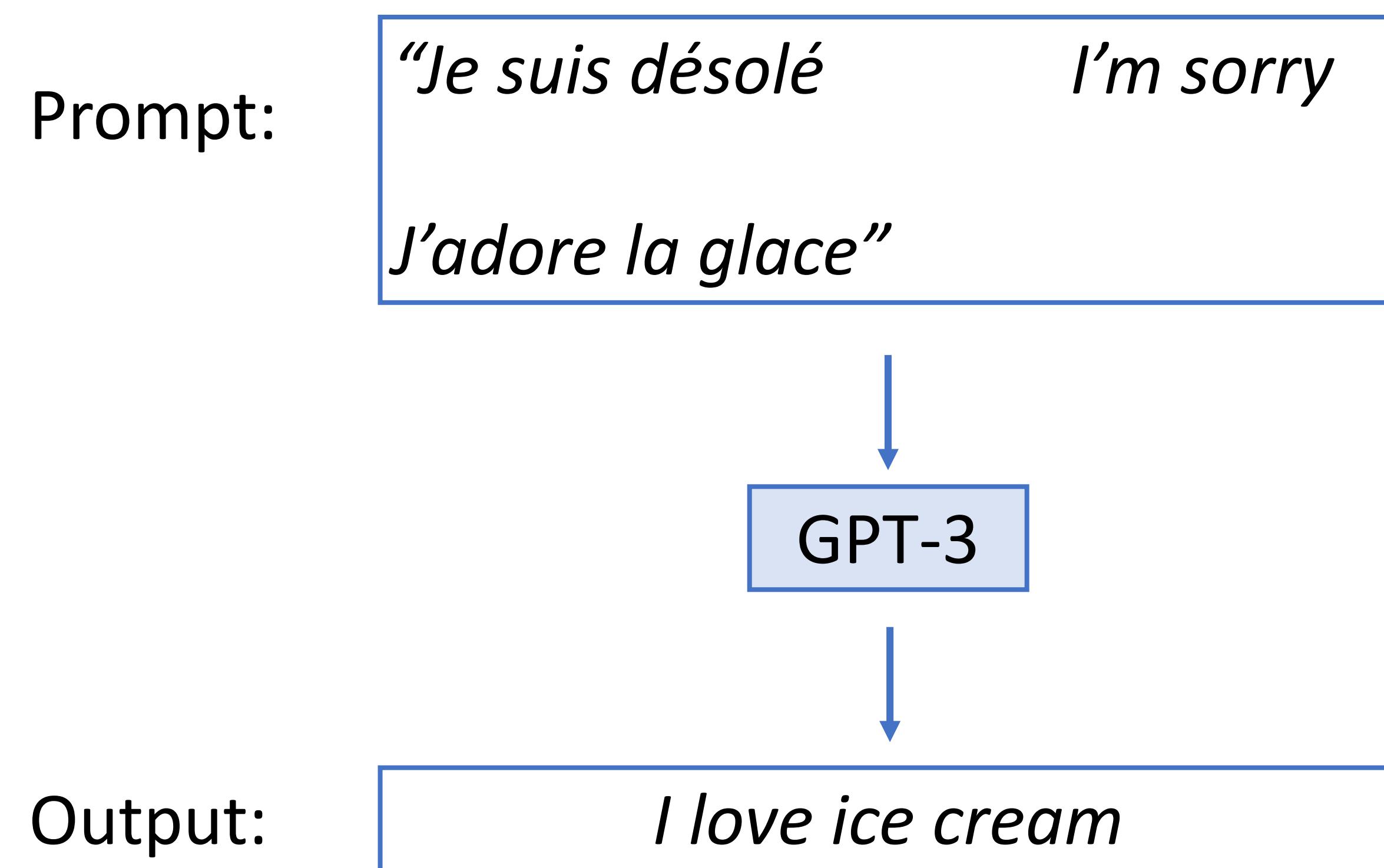
And the current winner is...

Data prediction



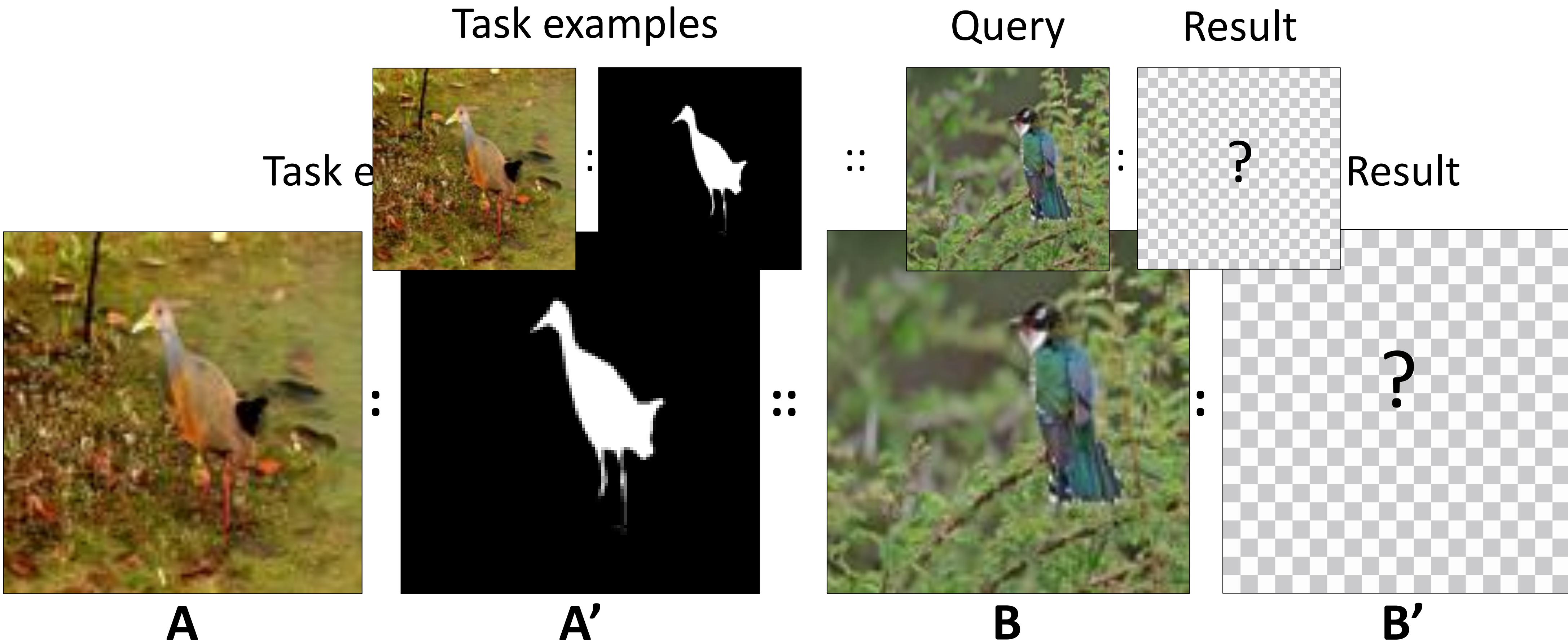
Masked Autoencoder
He et al. 2021

GPT-envy: “prompting” instead of fine-tuning



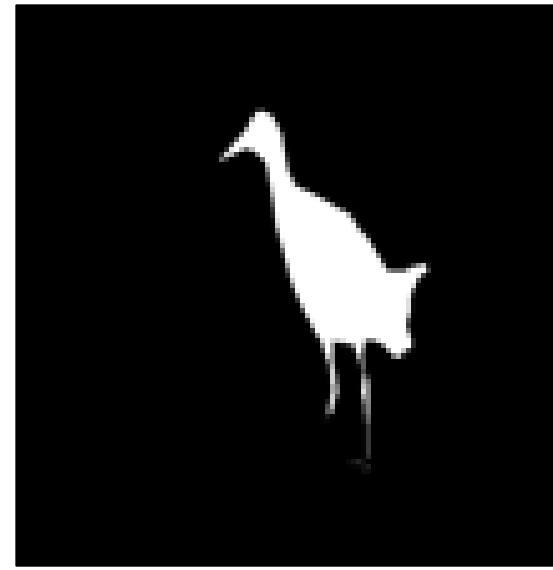
Can we do this for **visual data**?

Visual Prompting

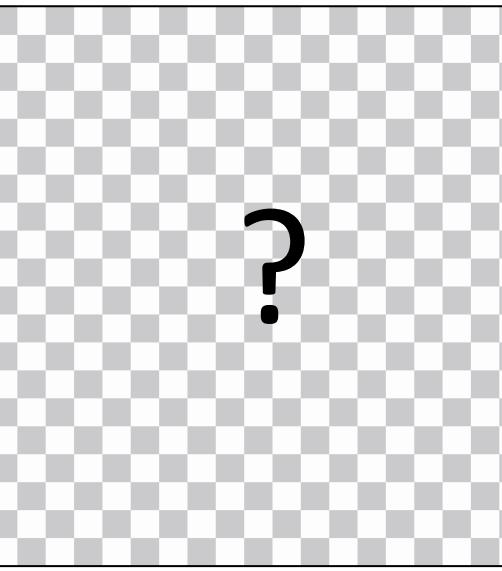
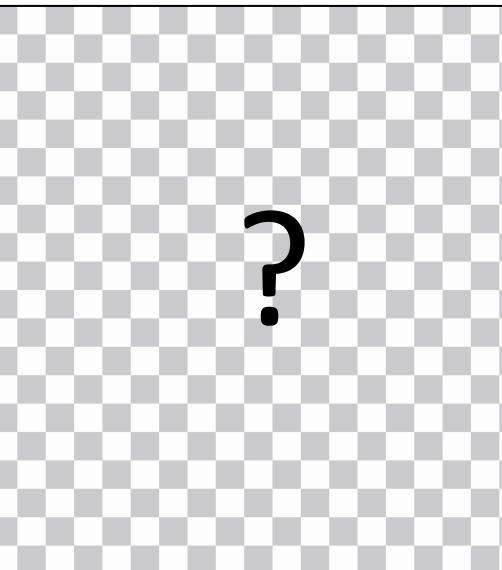
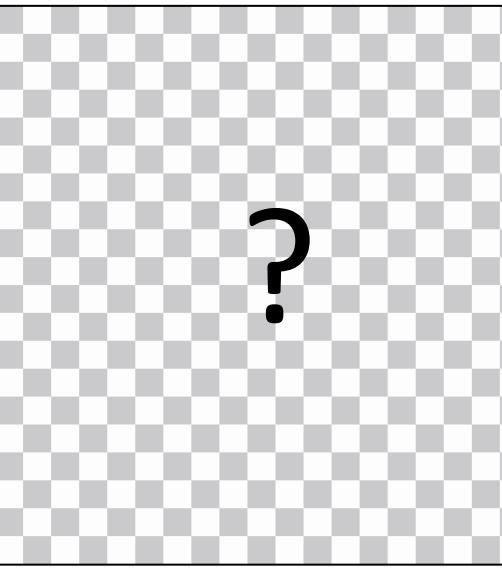


Visual Prompting

Task examples



::



Visual Prompting via Image Inpainting

Amir Bar

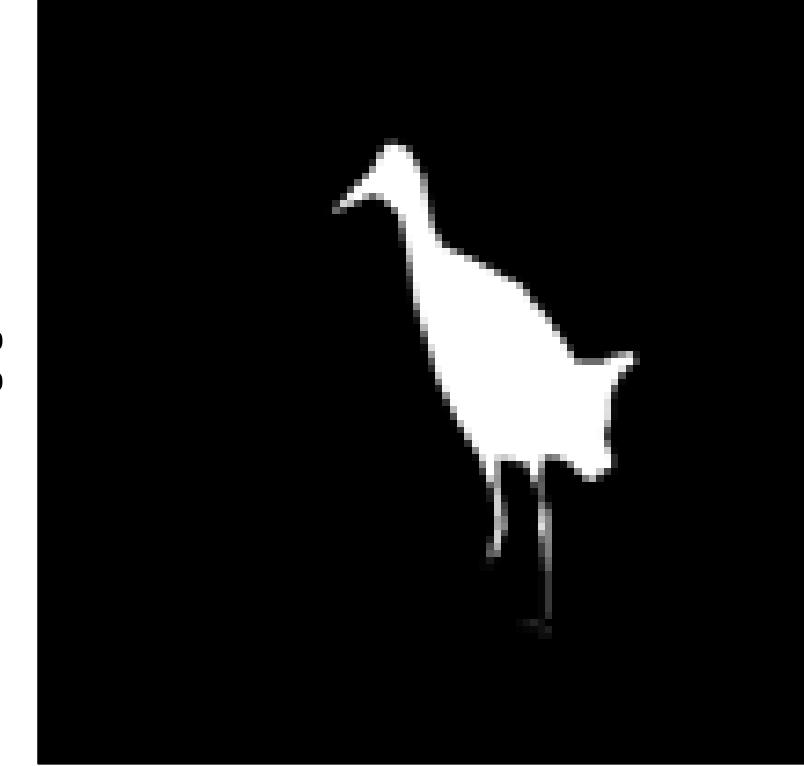
Yossi Gandelsman

Trevor Darrell, Amir Globerson, Alexei A Efros

NeurIPS 2022



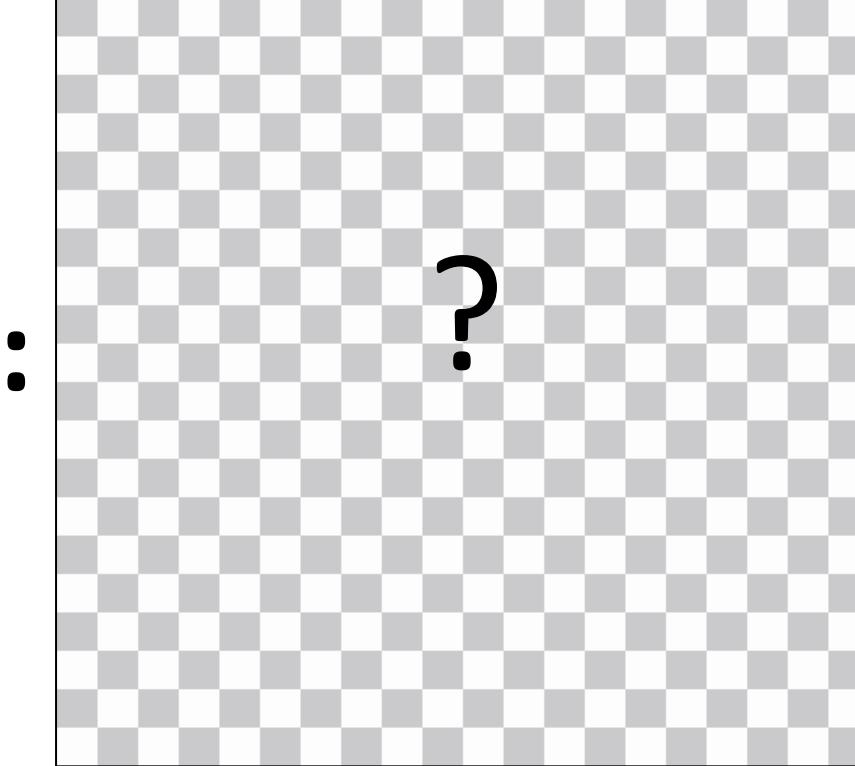
:



::

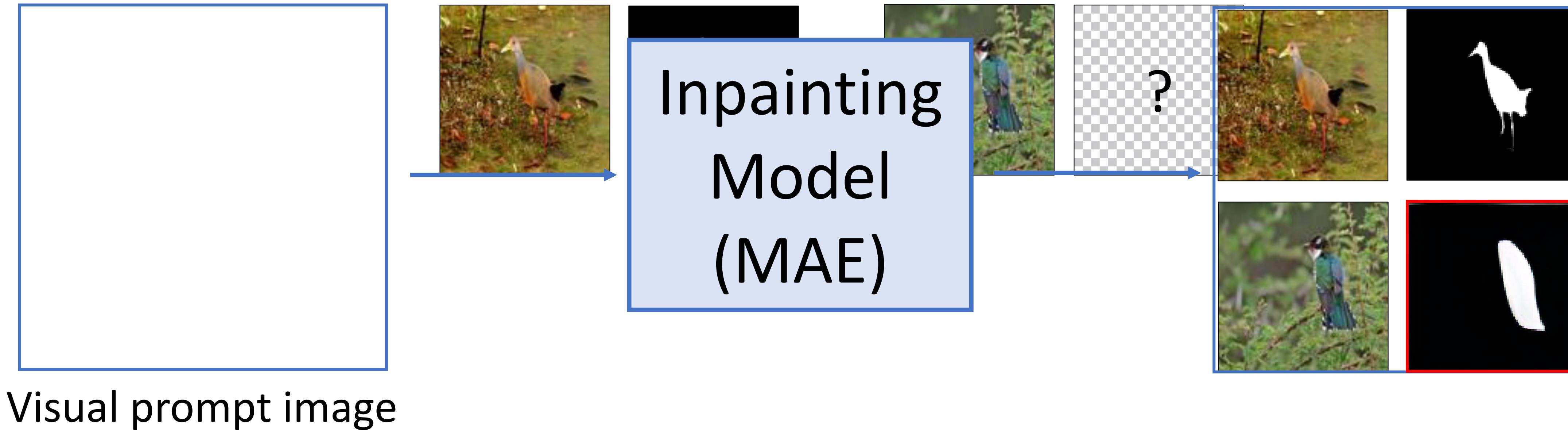


:



* Equal contribution

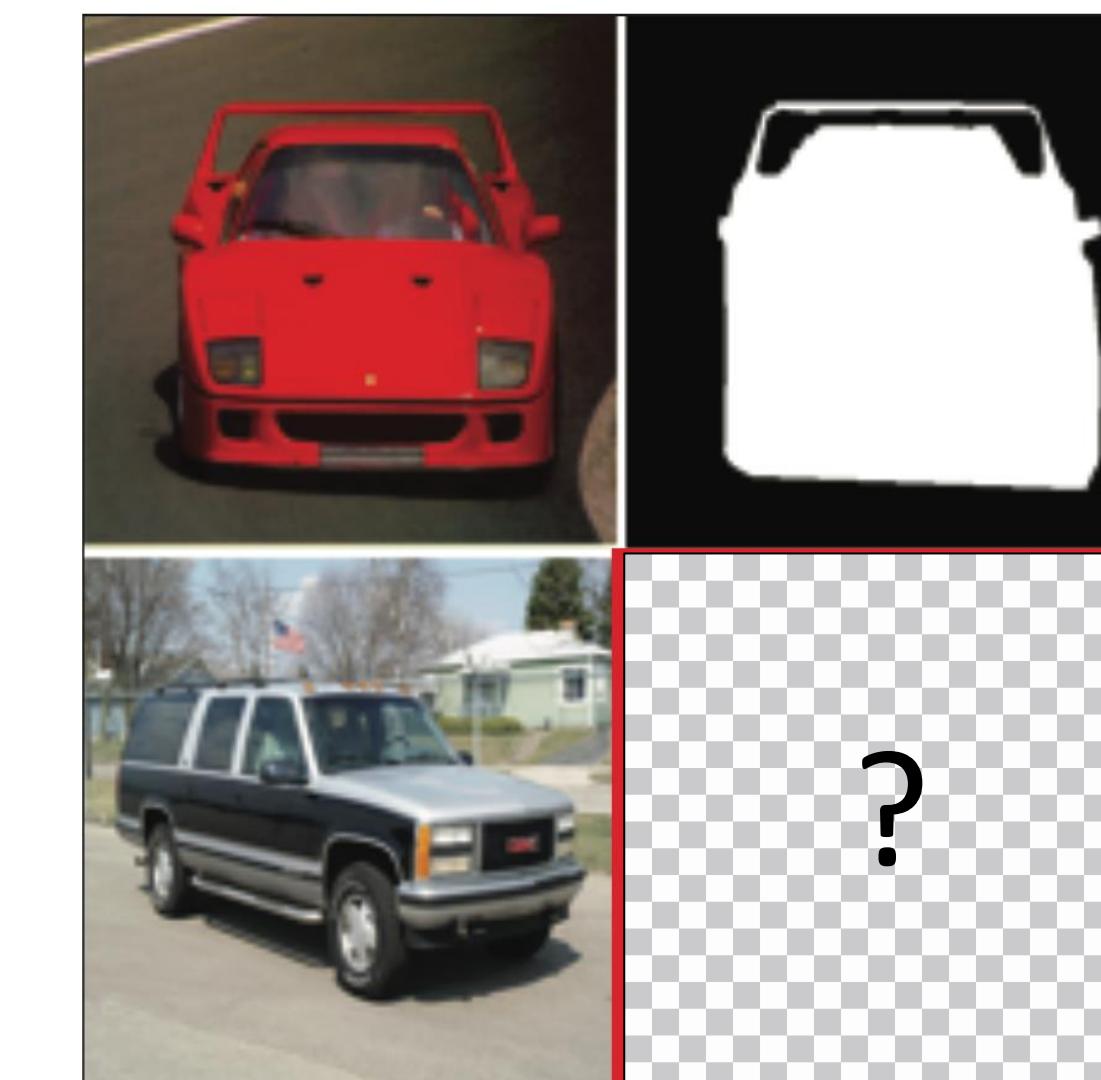
Deep Inpainting to the rescue!



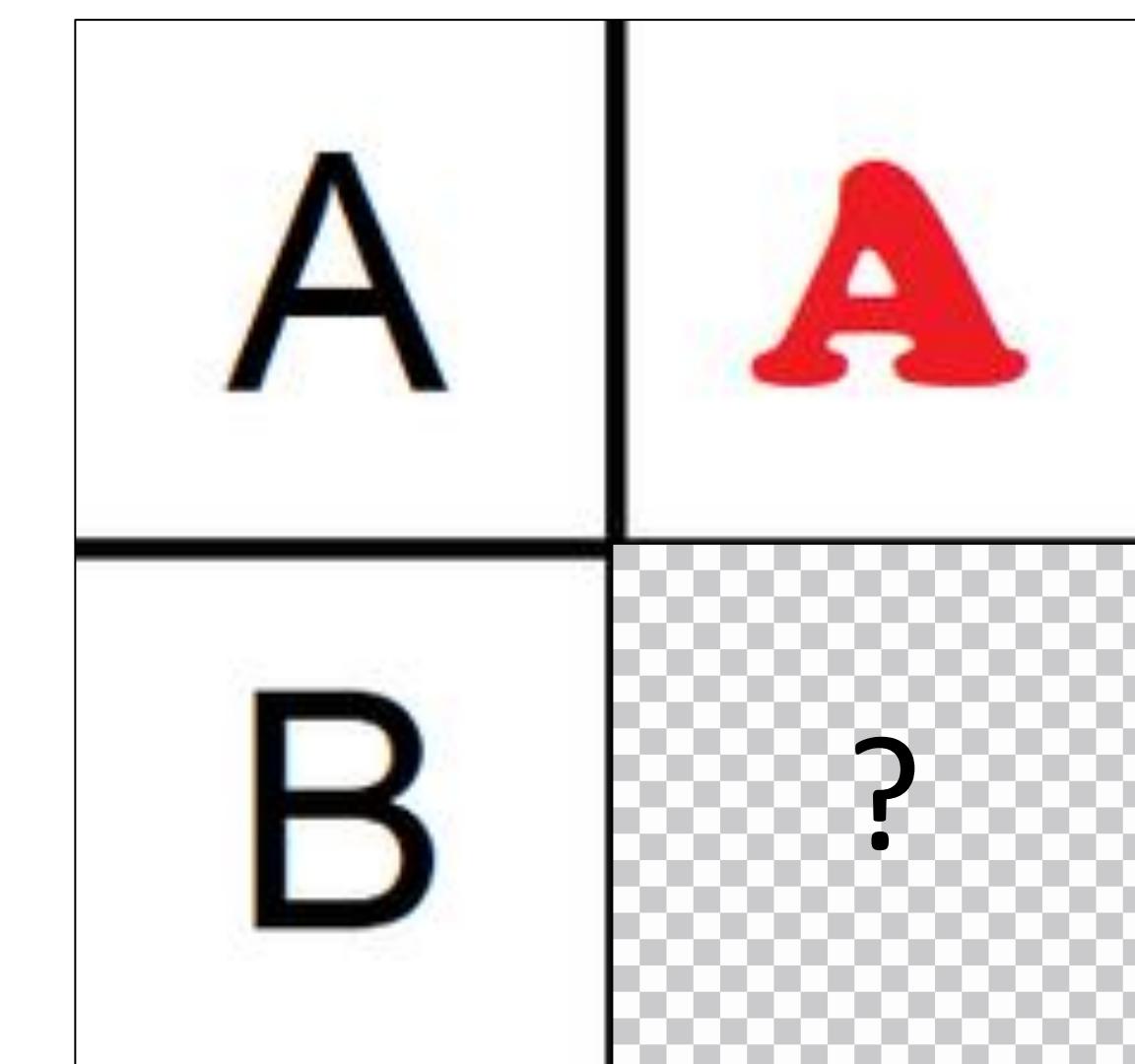
Wide range of tasks



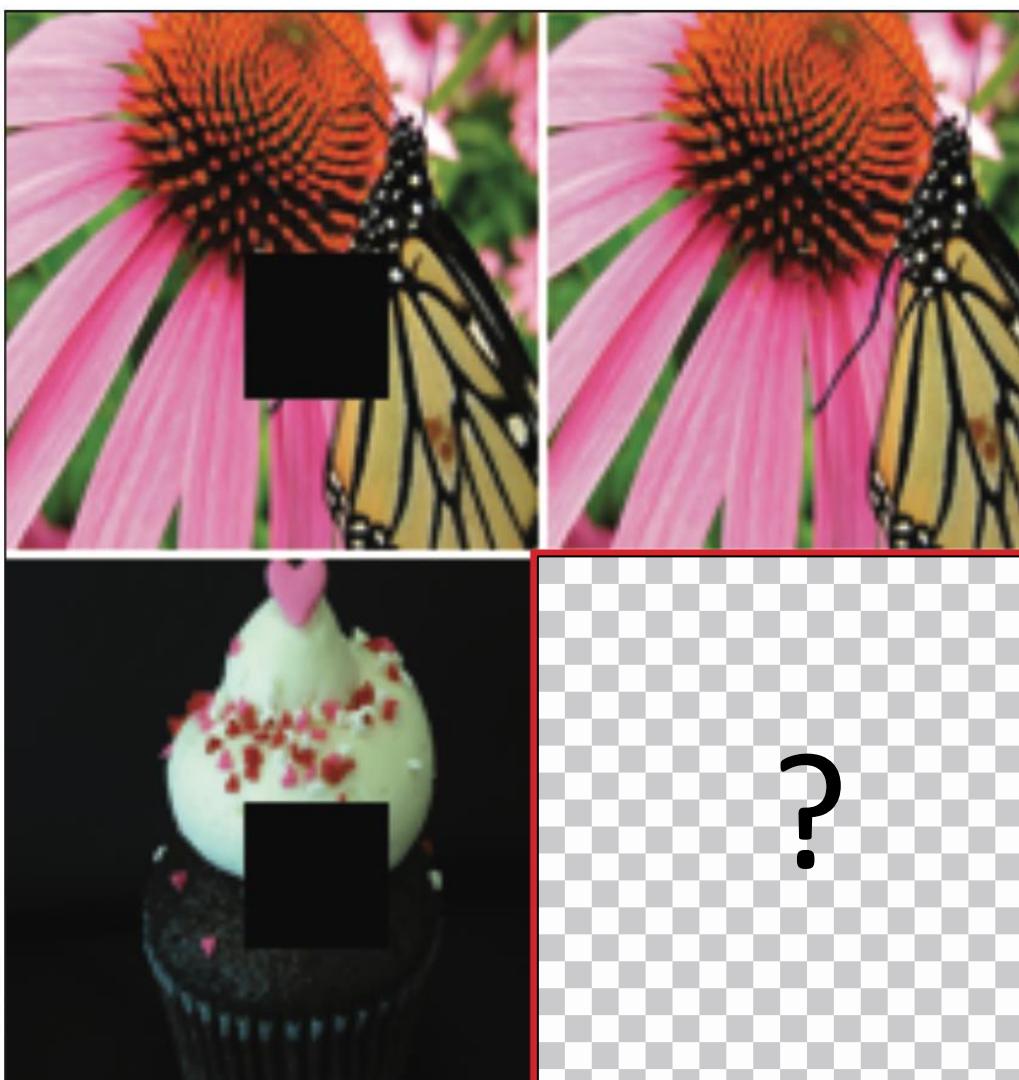
Colorization



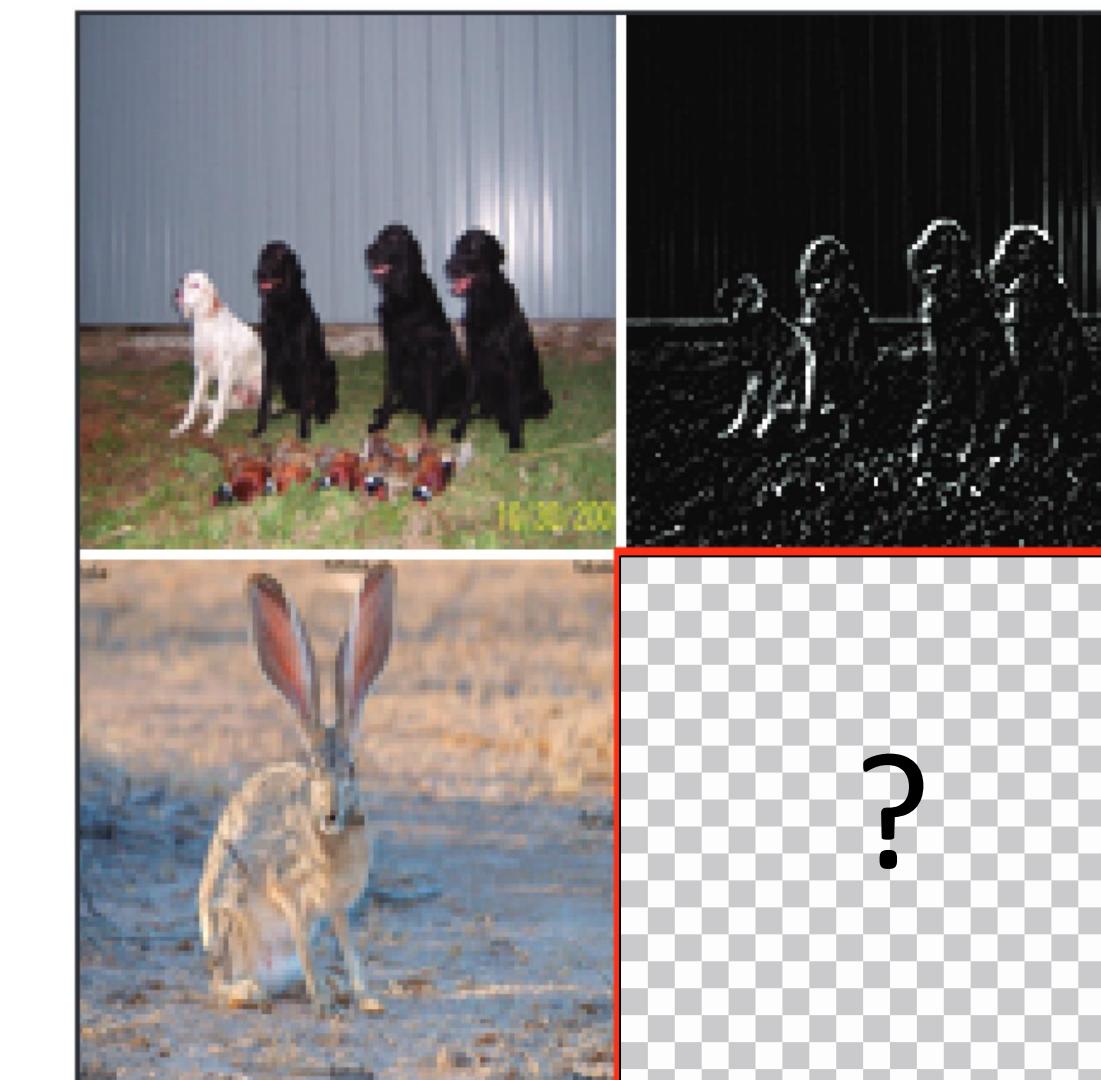
Segmentation



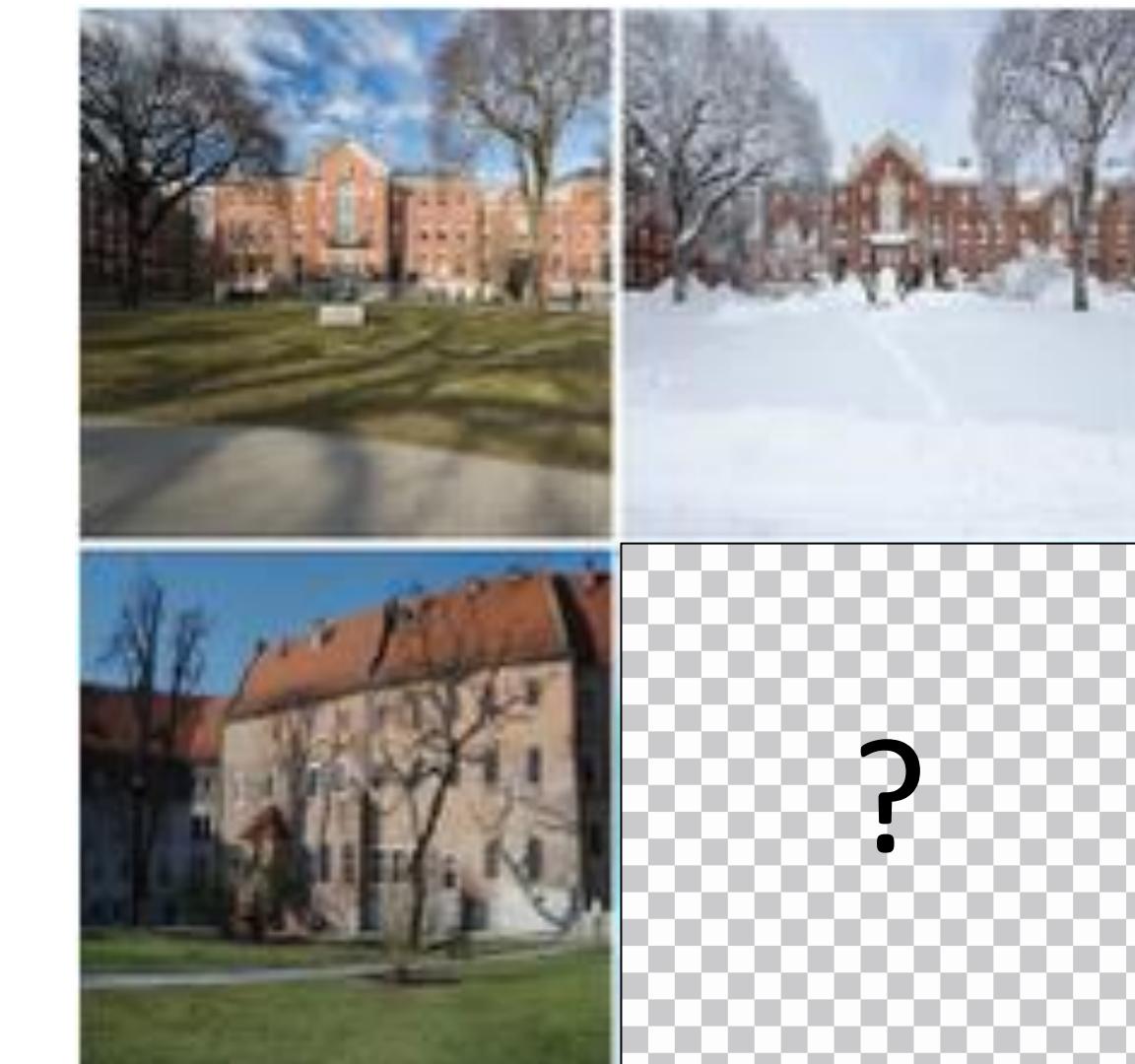
Font Style Transfer



Inpainting

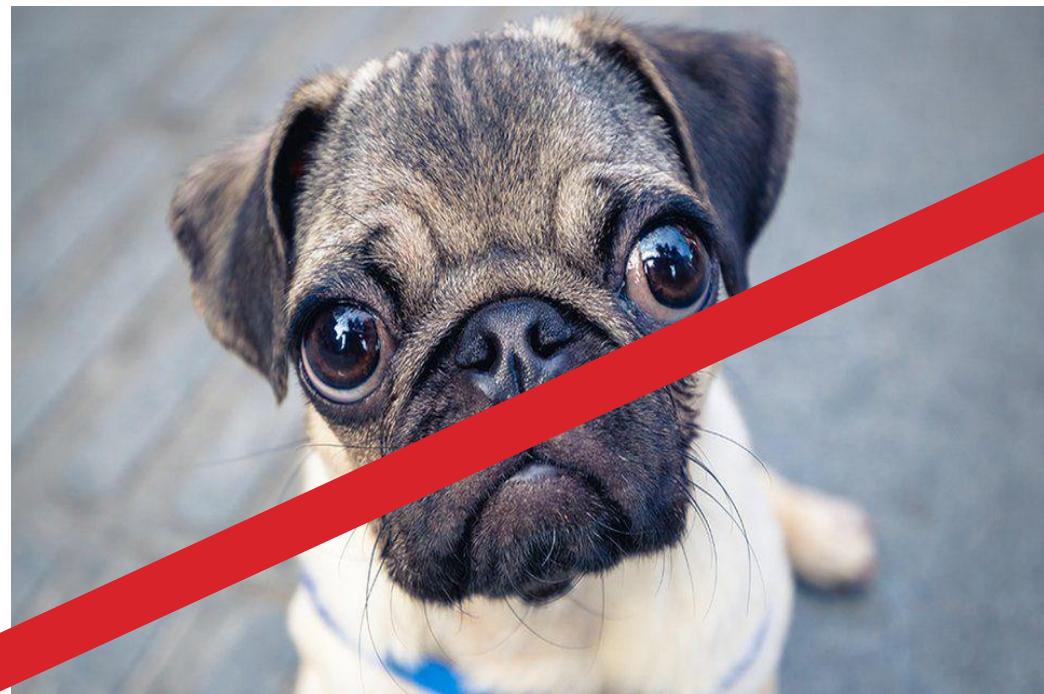


Edge Detection

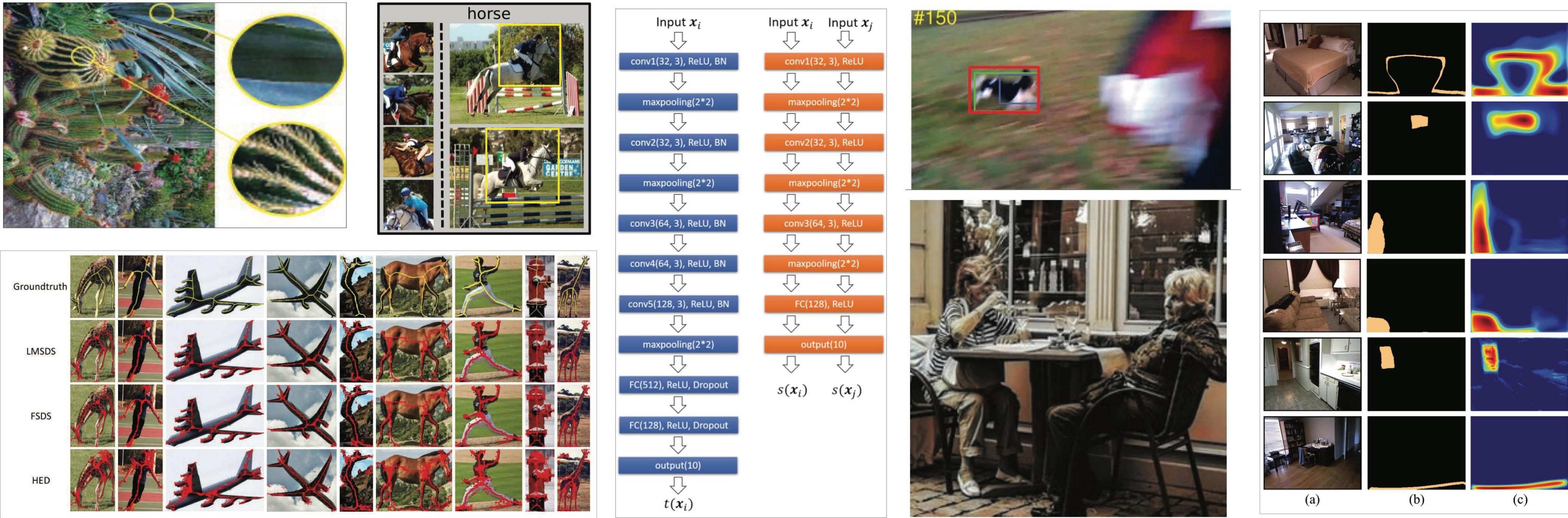


Style Transfer

Training Data

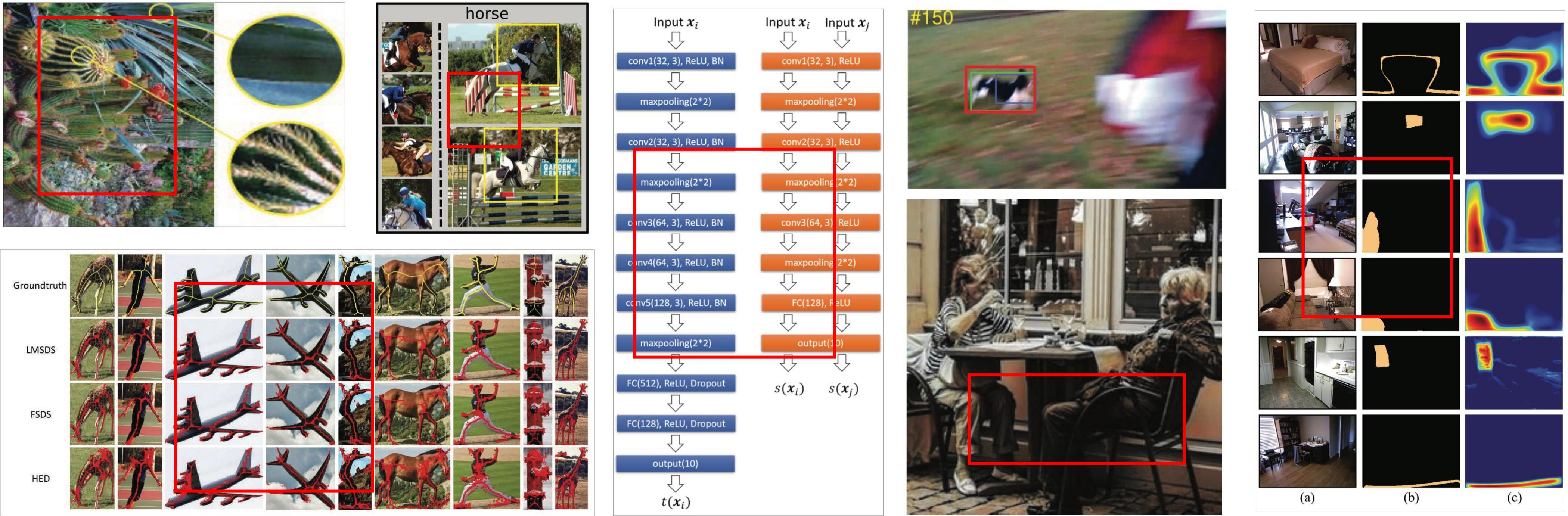


Computer Vision Figures Dataset (CVFD)



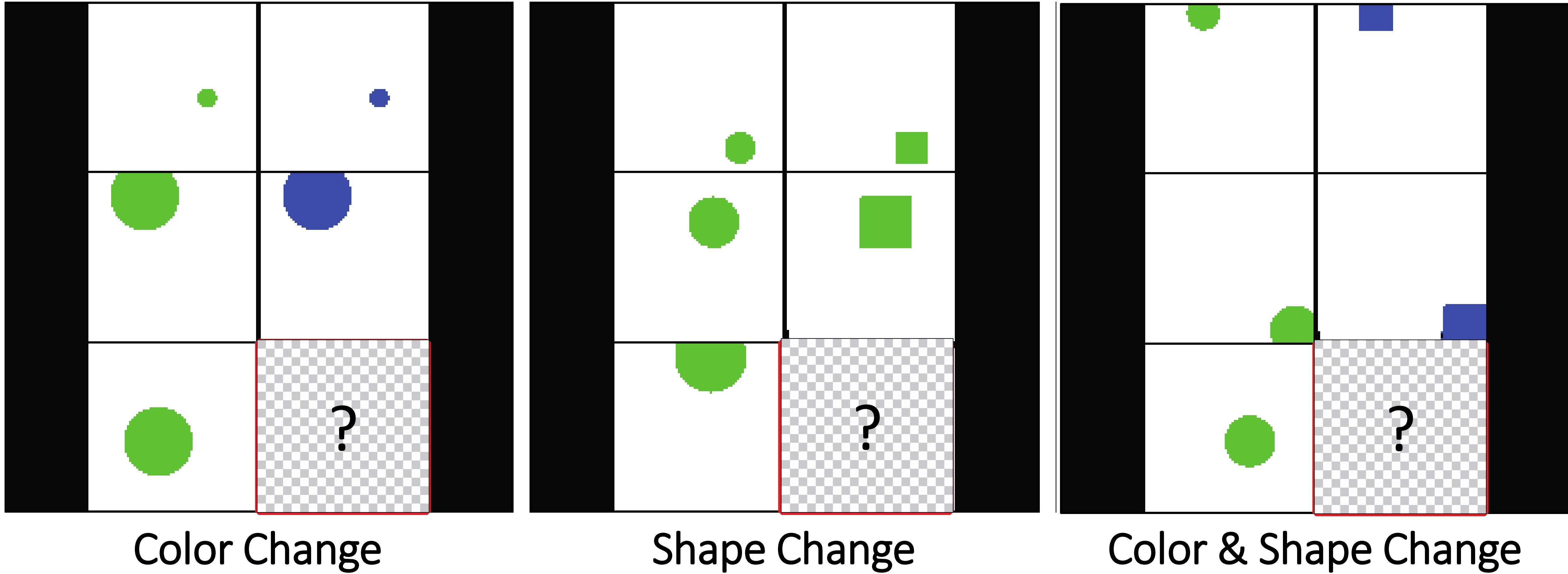
- 88k images from cs.CV arxiv papers (2010 to 2022)
- Many figures have grid-like structure

Training Time

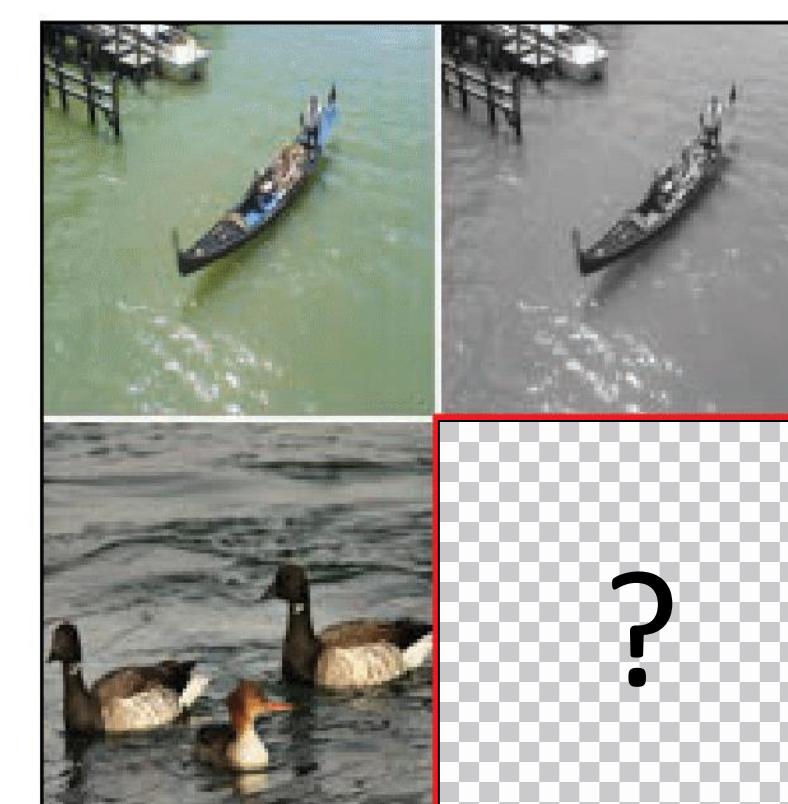
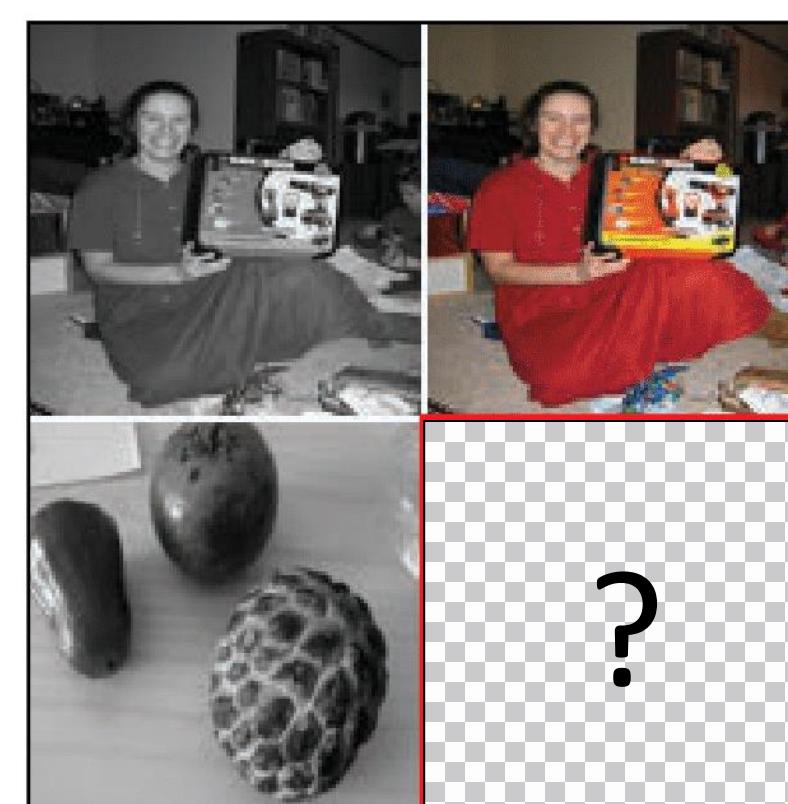
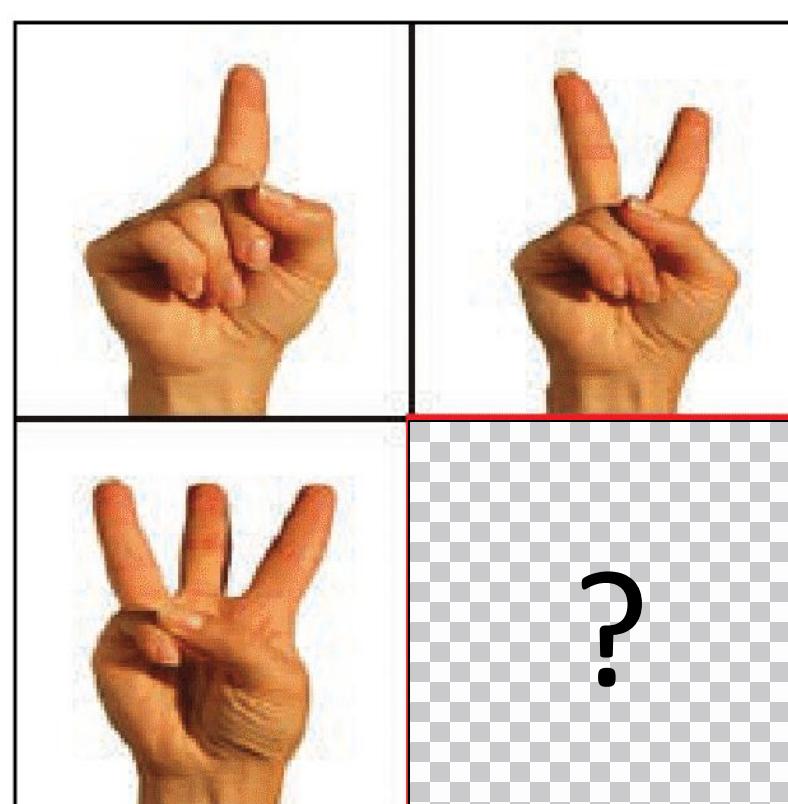
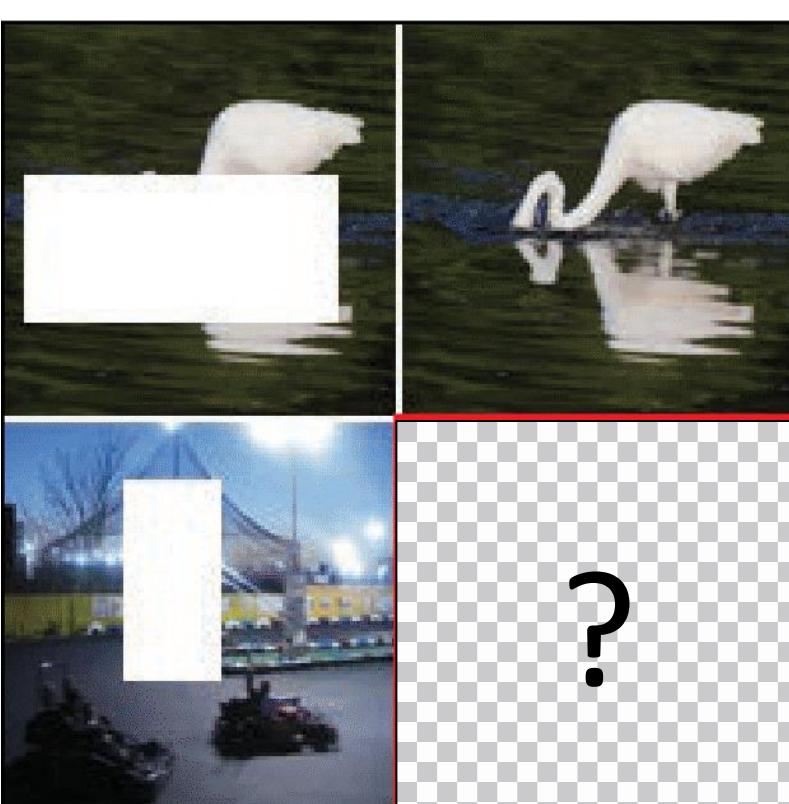
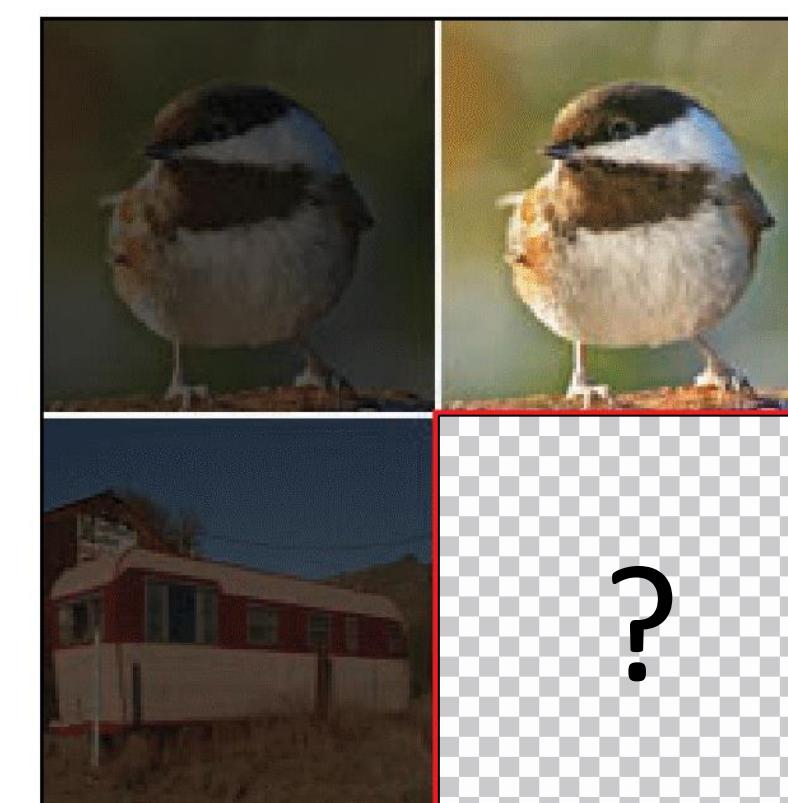
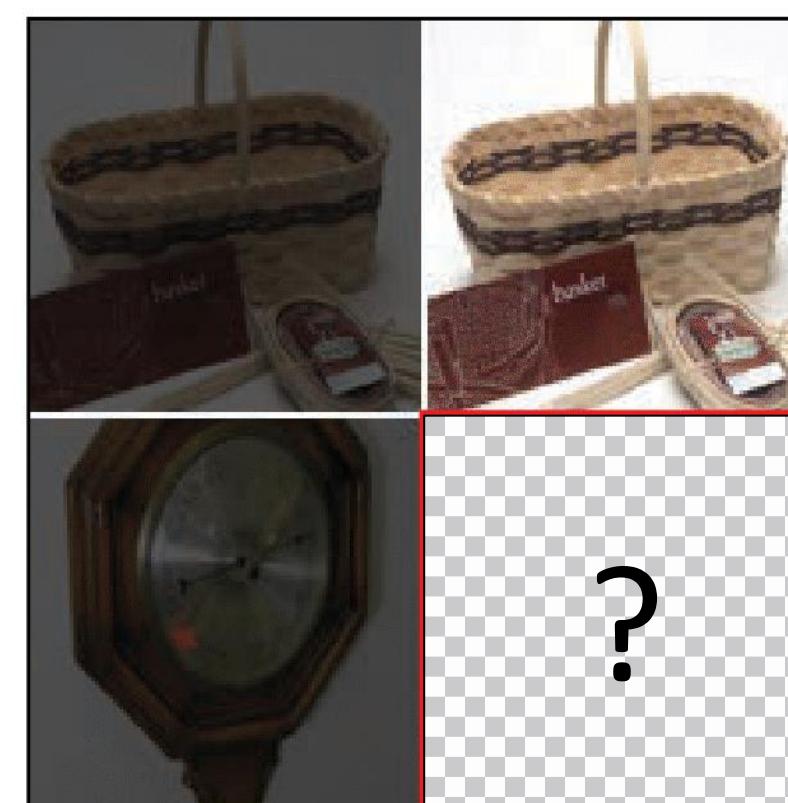
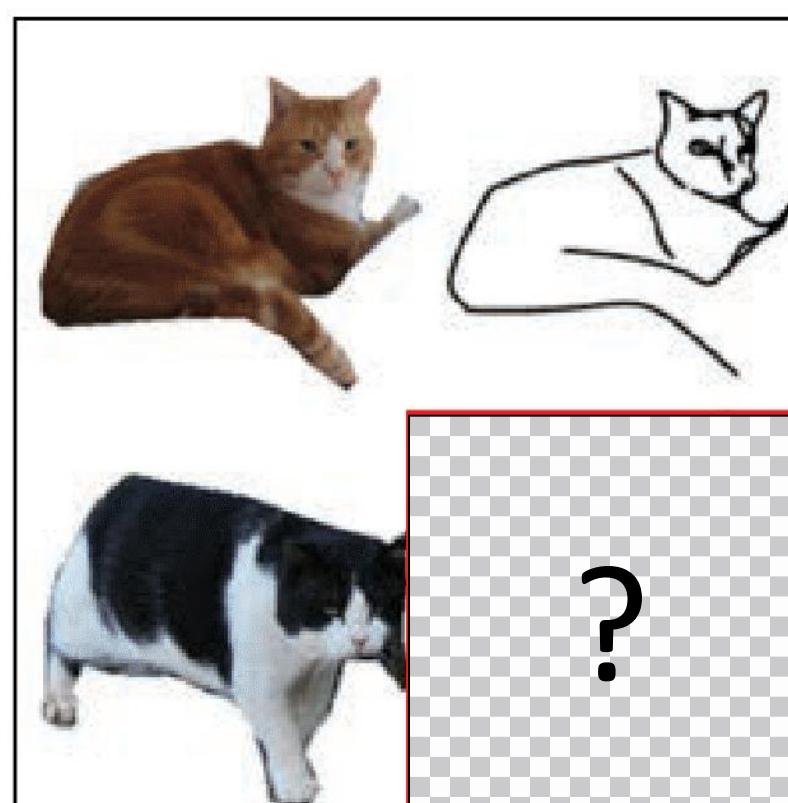
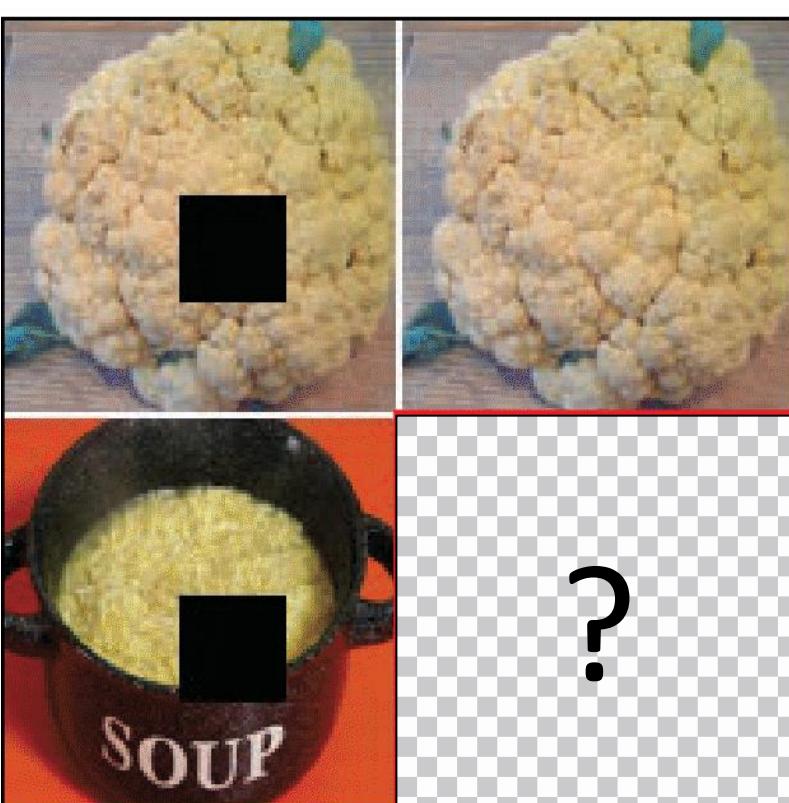
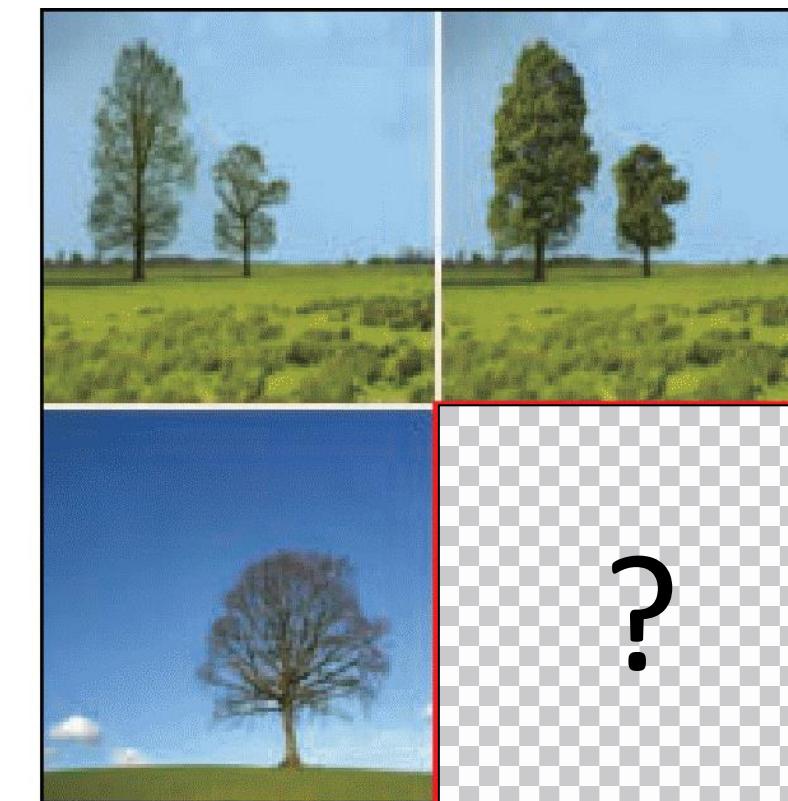
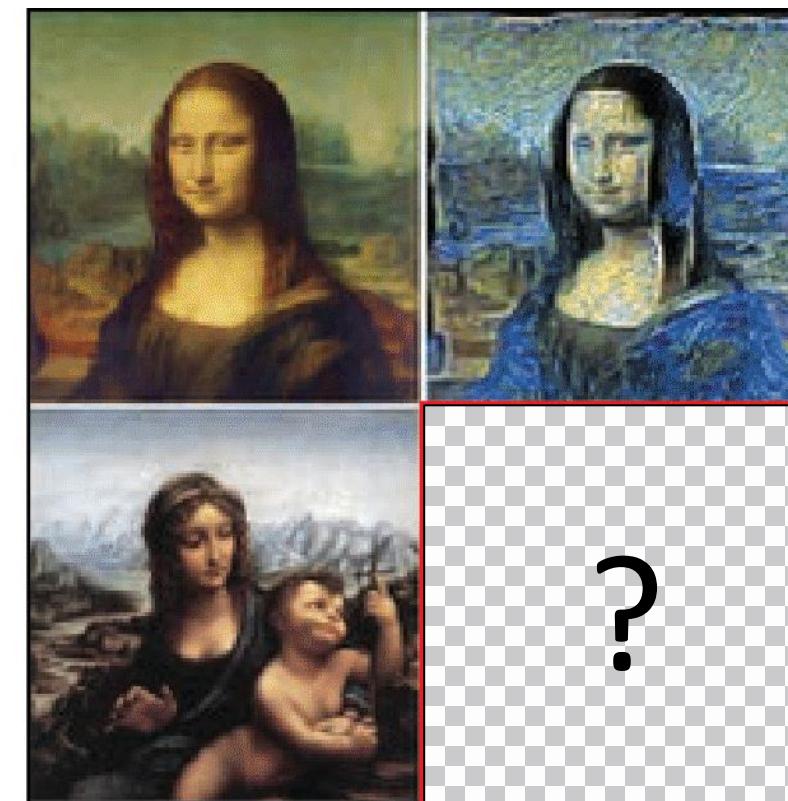
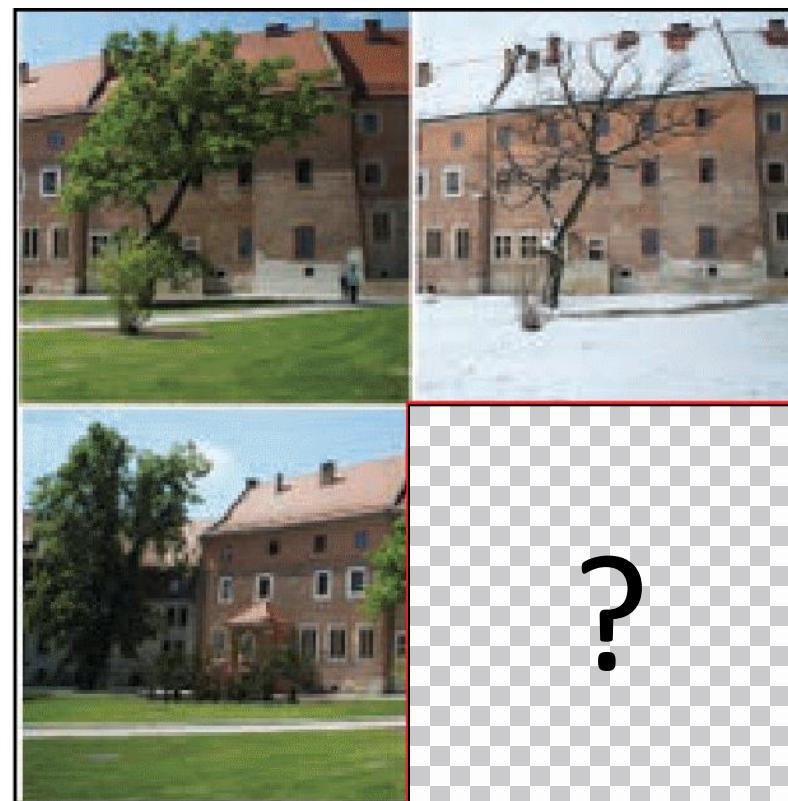


- Random 224x224 crops from figure images
 - No parsing
- We train MAE-VQGAN, a variant of Masked-Autoencoder (MAE)

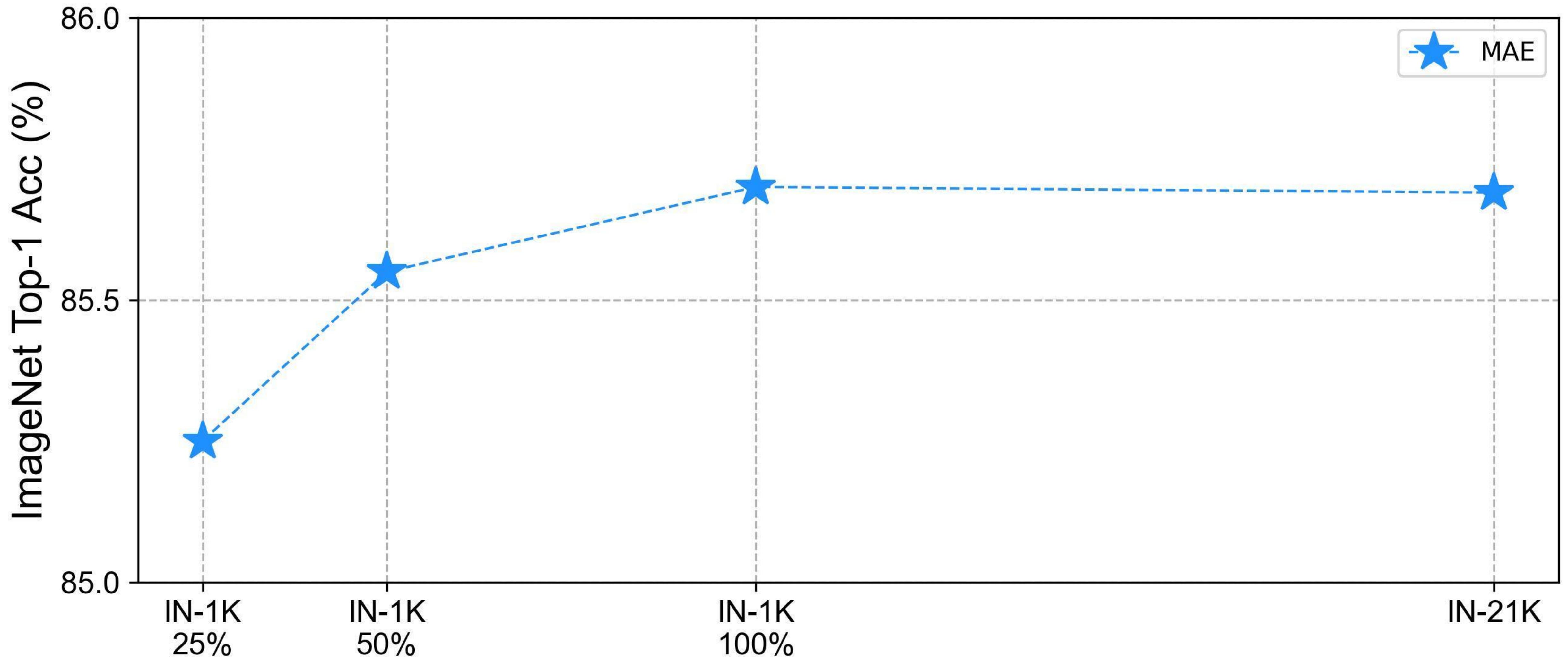
Synthetic Experiments



Various tasks



But MAE doesn't seem to scale 😞



Sequential Modeling Enables Scalable Learning for Large Vision Models

Yutong Bai, Xinyang Geng,
Karttikeya Mangalam, Amir Bar,
Alan Yuille, Trevor Darrell, Jitendra Malik, Alexei A Efros

On arxiv

MAE -> LLM (but without language!)

Data: ImageNet

Architecture: Masked Autoencoders

Loss function: L2 regression loss

Task Specification: Finetune

MAE -> LLM (but without language!)

Data: ~~ImageNet~~ 1.68B of images, 420B tokens, 50 Datasets

Architecture: Masked Autoencoders

Loss function: L2 regression loss

Task Specification: Finetune

MAE -> LLM (but without language!)

Data: ~~ImageNet~~ 1.68B of images, 420B tokens, 50 Datasets

Architecture: ~~Masked Autoencoders~~-Autoregressive Model

Loss function: L2 regression loss

Task Specification: Finetune

MAE -> LLM (but without language!)

Data: ~~ImageNet~~ 1.68B of images, 420B tokens, 50 Datasets

Architecture: ~~Masked Autoencoders~~-Autoregressive Model

Loss function: ~~L2 regression loss~~

Task Specification: Finetune

MAE -> LLM (but without language!)

Data: ~~ImageNet~~ 1.68B of images, 420B tokens, 50 Datasets

Architecture: ~~Masked Autoencoders~~-Autoregressive Model

Loss function: ~~L2 regression loss~~ Cross Entropy for next token

Task Specification: Finetune

MAE -> LLM (but without language!)

Data: ~~ImageNet~~ 1.68 B of images, 420 B tokens, 50 Datasets

Architecture: ~~Masked Autoencoders~~-Autoregressive Model

Loss function: ~~L2 regression loss~~ Cross Entropy for next token

Task Specification: ~~Finetune~~ prompting

across:
images,
videos,
supervised / unsupervised
synthetic / real,
all kinds of tasks
2D / 3D / 4D data etc.

Dataset	Tokens (Millions)	Annotation Type	Annotation Source
Unpaired Image Data			
LAION 5B [71] (1.5B images subset)	380690	-	-
Images with Annotations			
ImageNet 1K [25]	1317.40	Image Classification	Ground Truth
COCO [54]	363	Object Detection	MMDetection [16]
ADE 20K [100], Cityscapes [22]	66.88	Semantic Segmentation	Ground Truth
COCO [54], ImageNet 1K [25]	2078.06	Semantic Segmentation	Mask2Former [19]
COCO [54], lvmhp [51], mpii [4], Unite [49]	950.79	Human Pose	MMPose[21]
COCO [54], ImageNet 1K [25]	1623.85	Depth Map Image	DPT [67]
Subset of InstructPix2Pix [34]	415.46	Style Transfer	InstructPix2Pix [34]
COCO[54], ImageNet 1K[25]	1623.85	Surface Normal Image	NLL-AngMF [7]
COCO [54], ImageNet 1K [25]	1623.85	Edge Detection	DexiNed [79]
DID-MDN [98]	35.06	Rainy and Clean Image Pairs	Ground Truth
SIDD [3]	245.76	Denoised Image	Ground Truth
LOL[89]	0.458	Light Enhanced Image	Ground Truth
ImageNet 1K [25]	1321.07	Grayscale and Colorized Image Pairs	Ground Truth
ImageNet 1K [25]	1321.07	Inpainting	Ground Truth
Kitti [34]	9.21	Stereo	Ground Truth
Videos			
UCF101 [78]	109.11	-	-
DAVIS [65]	0.36	-	-
HMDB [48]	55.41	-	-
ActivityNet [13]	380.63	-	-
Moments in Time [59]	2979.00	-	-
Multi-moments in Time [60]	4124.04	-	-
Co3D [69]	228.75	-	-
Charades v1 [76]	241.53	-	-
Something-something v2 [37]	904.57	-	-
YouCook [23]	3.14	-	-
Kinetics 700 [14]	7092.04	-	-
MSR-VTT [92]	57.34	-	-
Youtube VOS [93]	63.70	-	-
jester [57]	606.47	-	-
diving48 [52]	150.73	-	-
MultiSports [53]	78.44	-	-
CharadesEgo [77]	193.06	-	-
AVA [61]	117.96	-	-
Ego4D [38]	1152.12	-	-
Videos with Annotations			
VIPSeg [58]	64.47	Video Panoptic Segmentation	Ground Truth
Hand14K [32]	1.96	Hand Segmentation	Ground Truth
AVA [61]	122.88	Video Detection	Ground Truth
JHMDB [43]	19.00	Optical Flow	Ground Truth
JHMDB [43]	37.92	Video Human Pose	Ground Truth
Synthetic 3D Views			
Objaverse [24] Rendered Multiviews	217.85	-	-

Sentence -> Visual Sentence

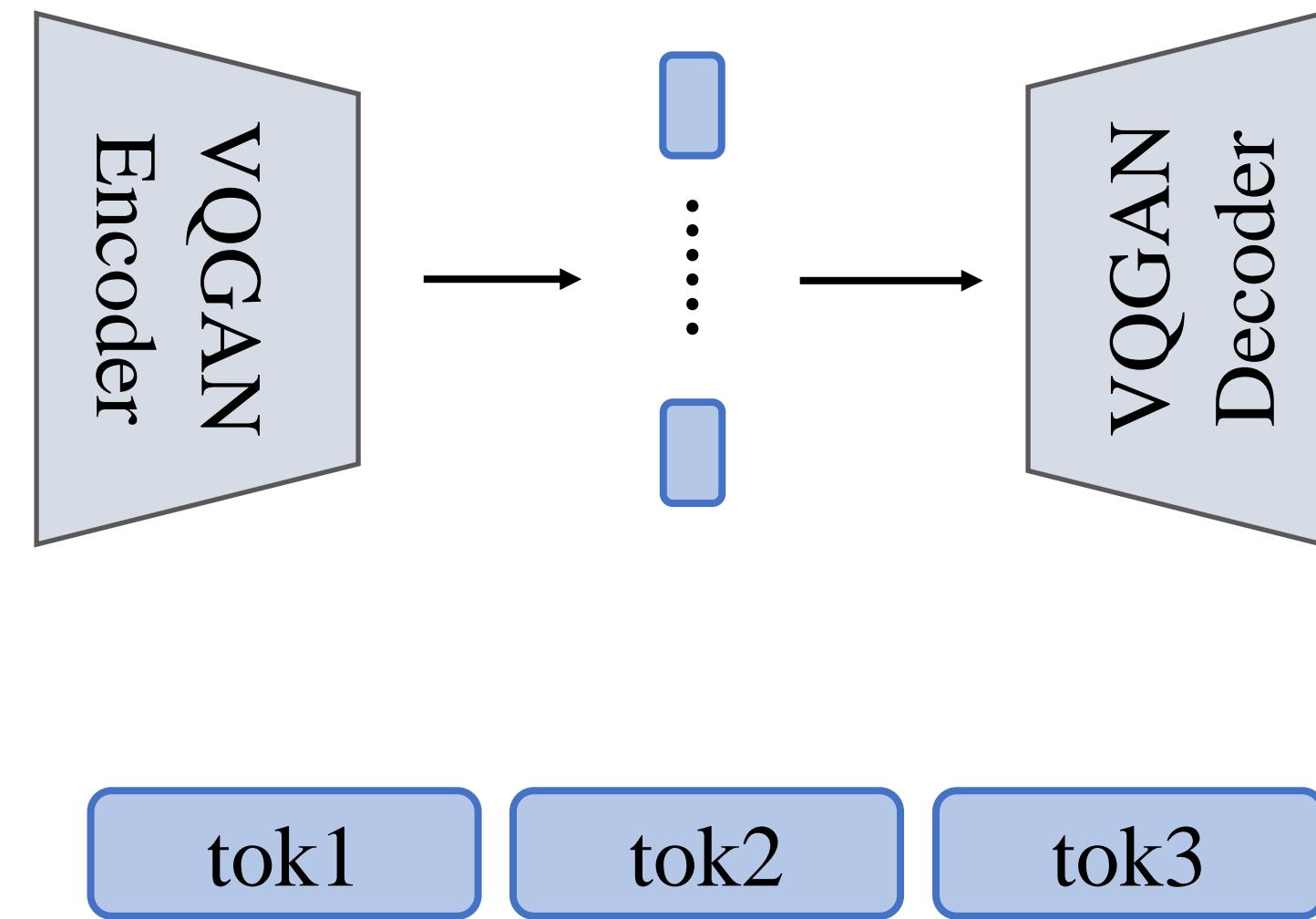
Single images



<BOS>

<EOS>

Tokenizer



• • •

Videos

<BOS>



... <EOS>

Image sequences

<BOS>



... <EOS>

categories

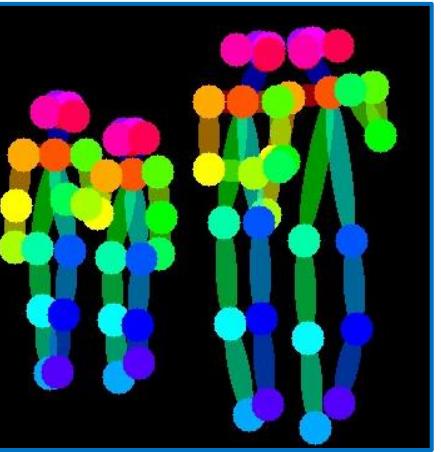
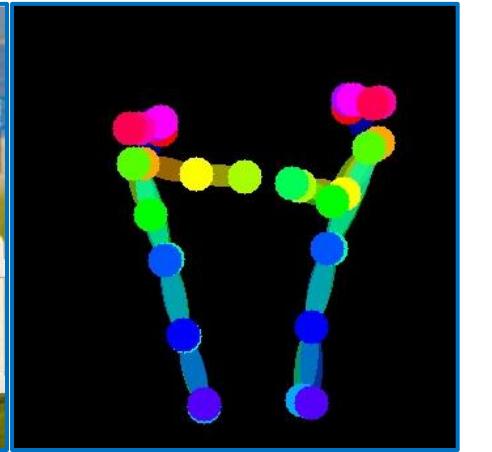
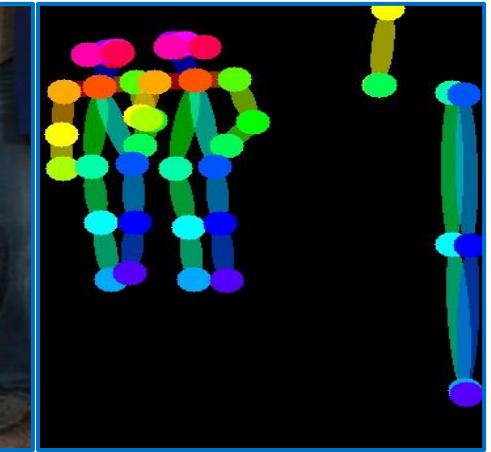
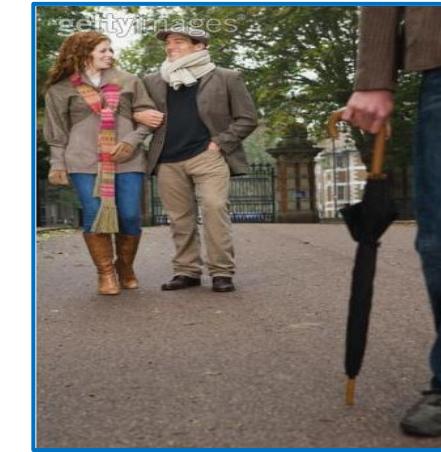
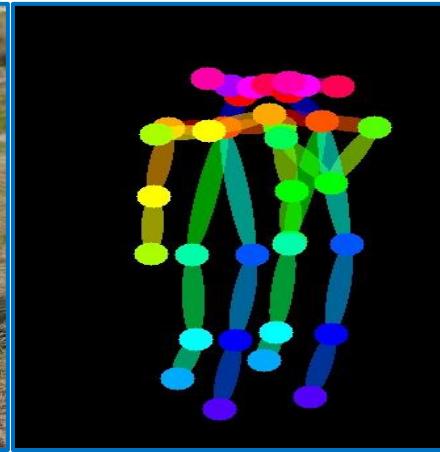
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... <EOS>

Images with annotation

<BOS>

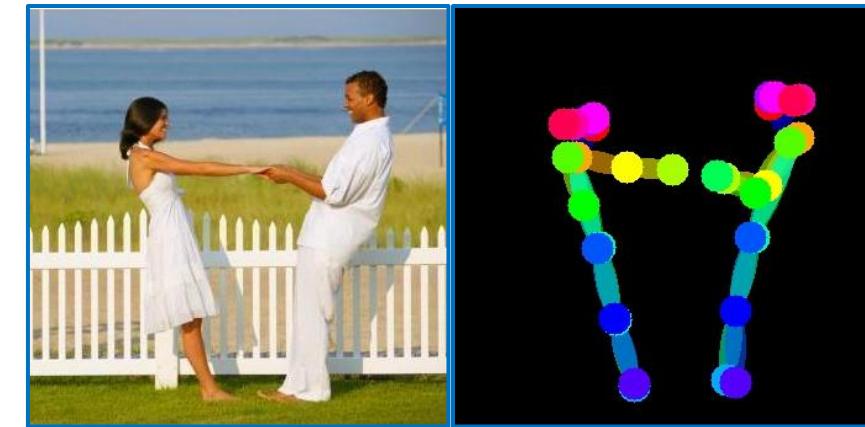


• • • <EOS>

Images with annotation



<BOS>



... <EOS>



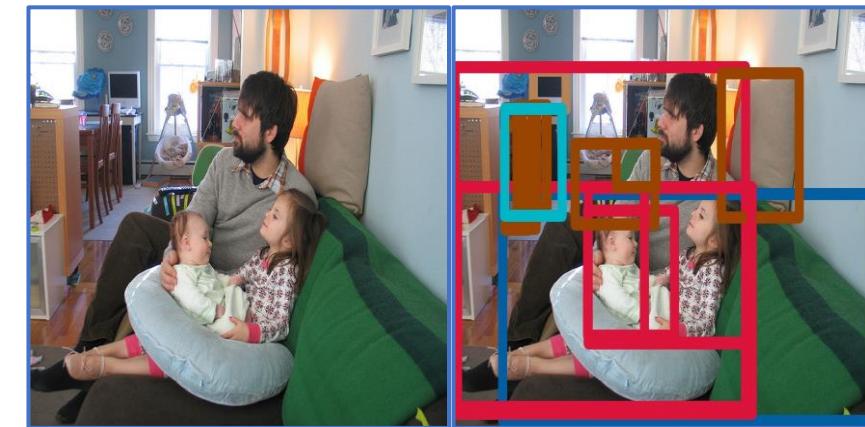
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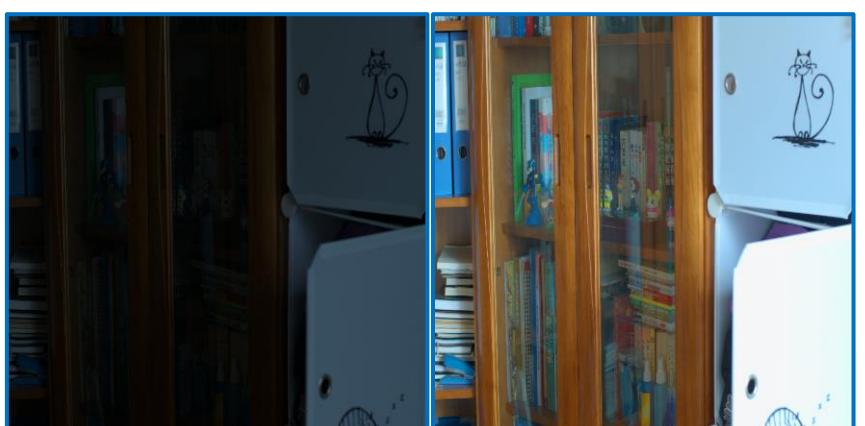
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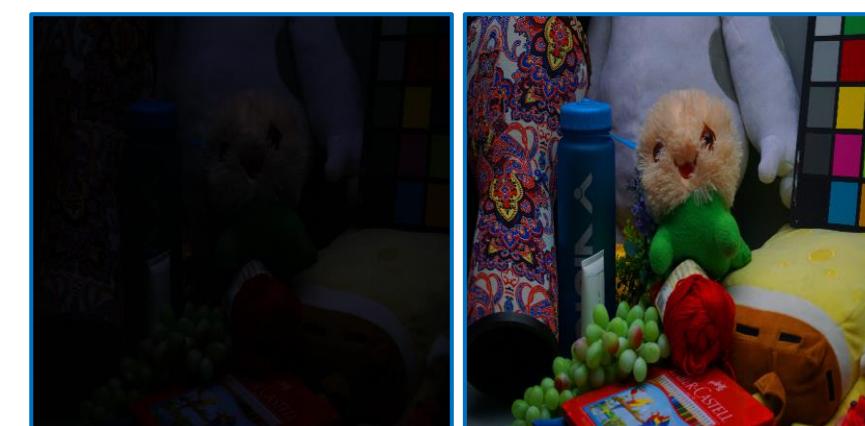
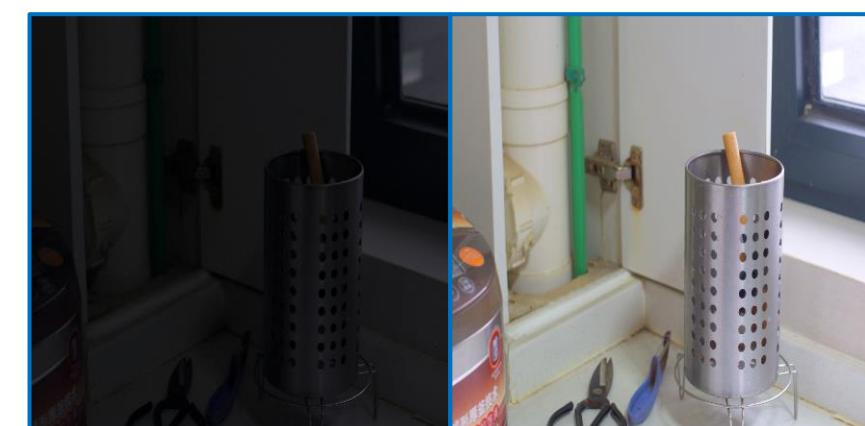
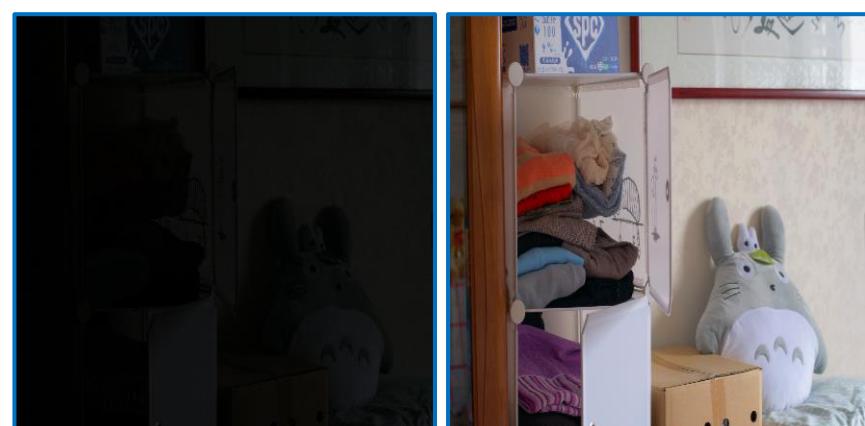
<BOS>



... <EOS>



<BOS>



... <EOS>

Images with free form annotation

<BOS>



• • •

<EOS>

<BOS>



• • • <EOS>

<BOS>



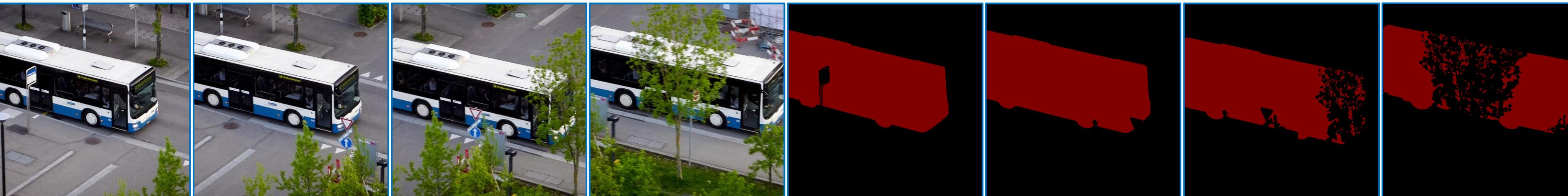
• • • <EOS>

Videos with annotation

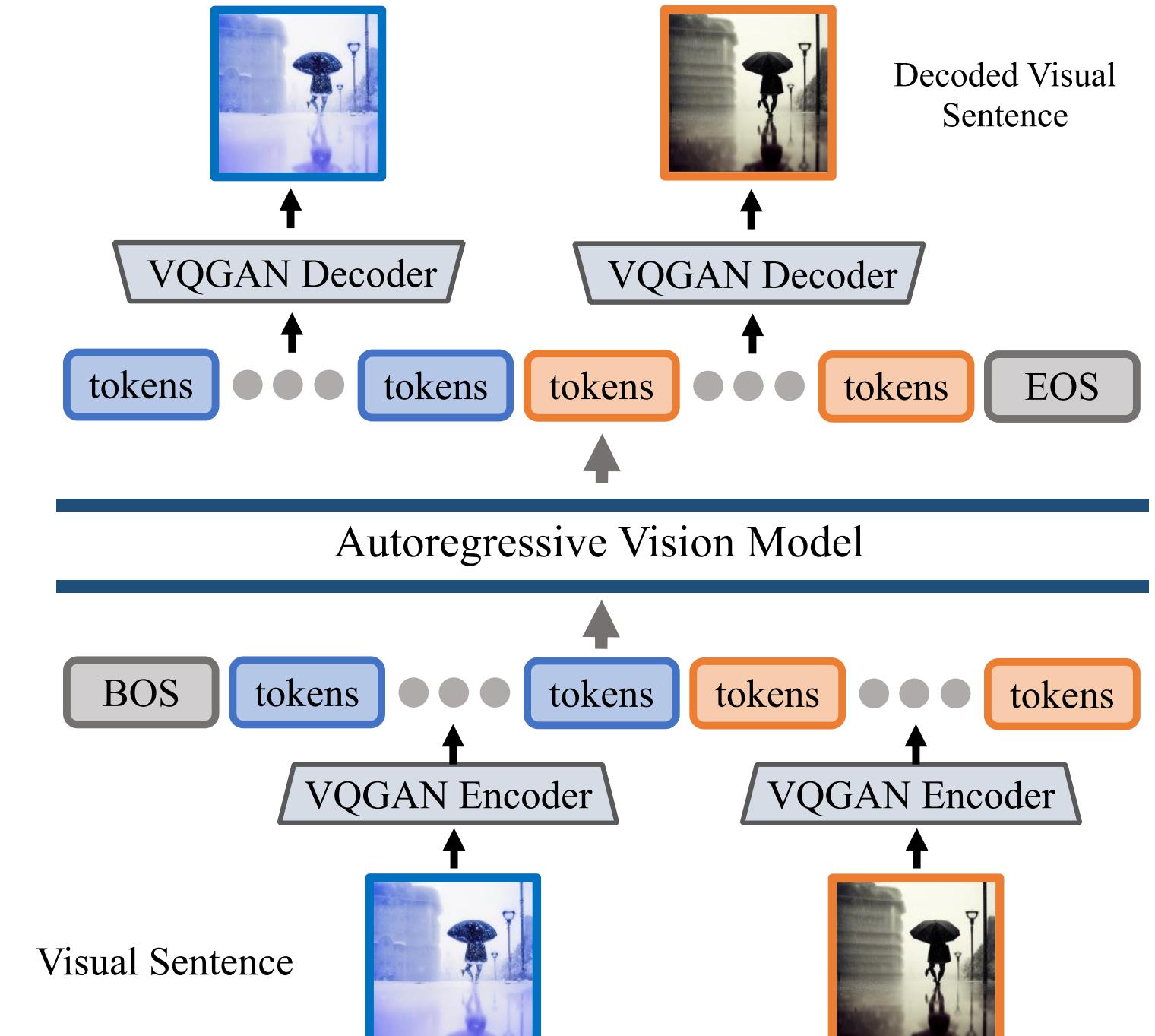
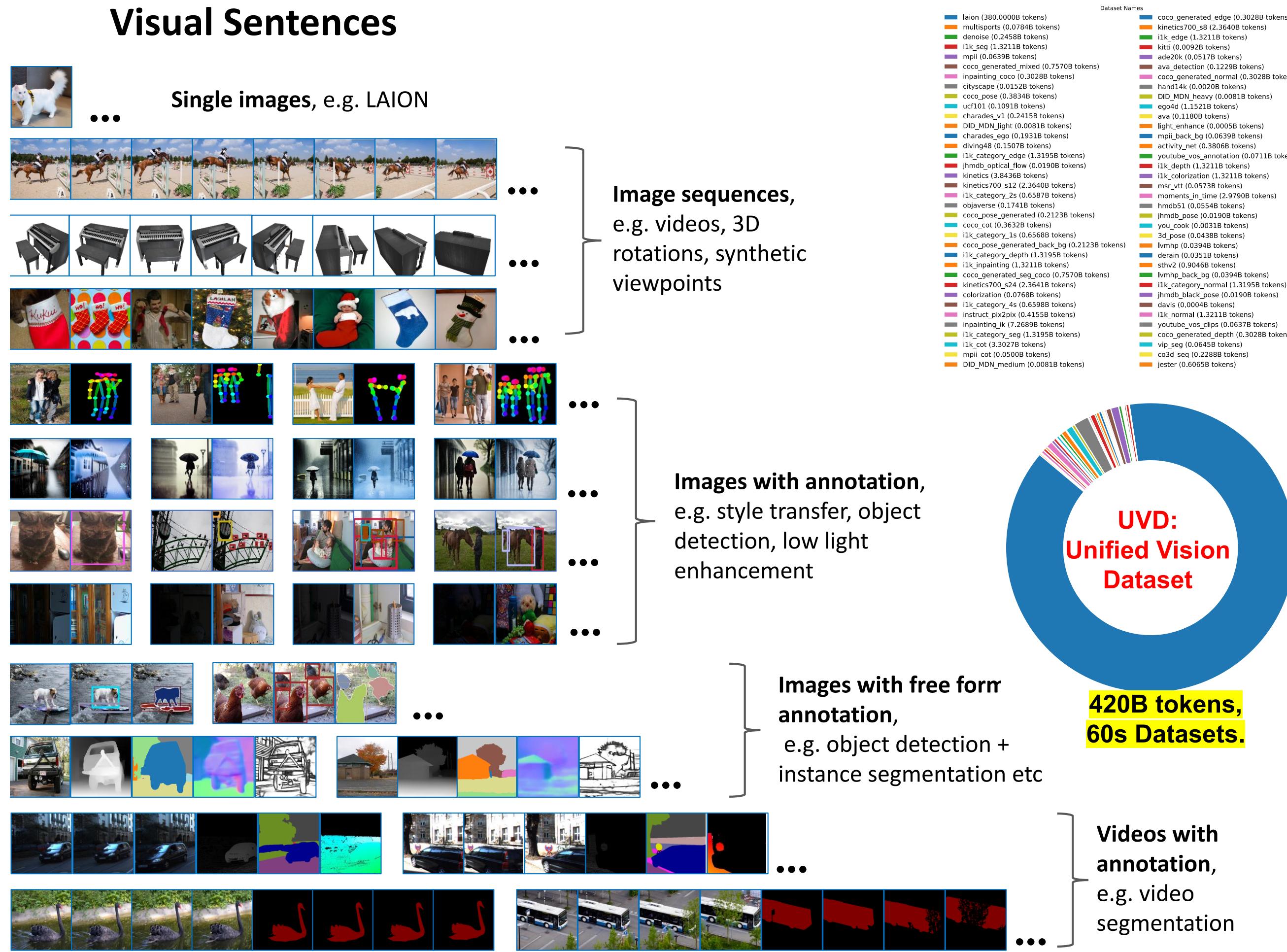
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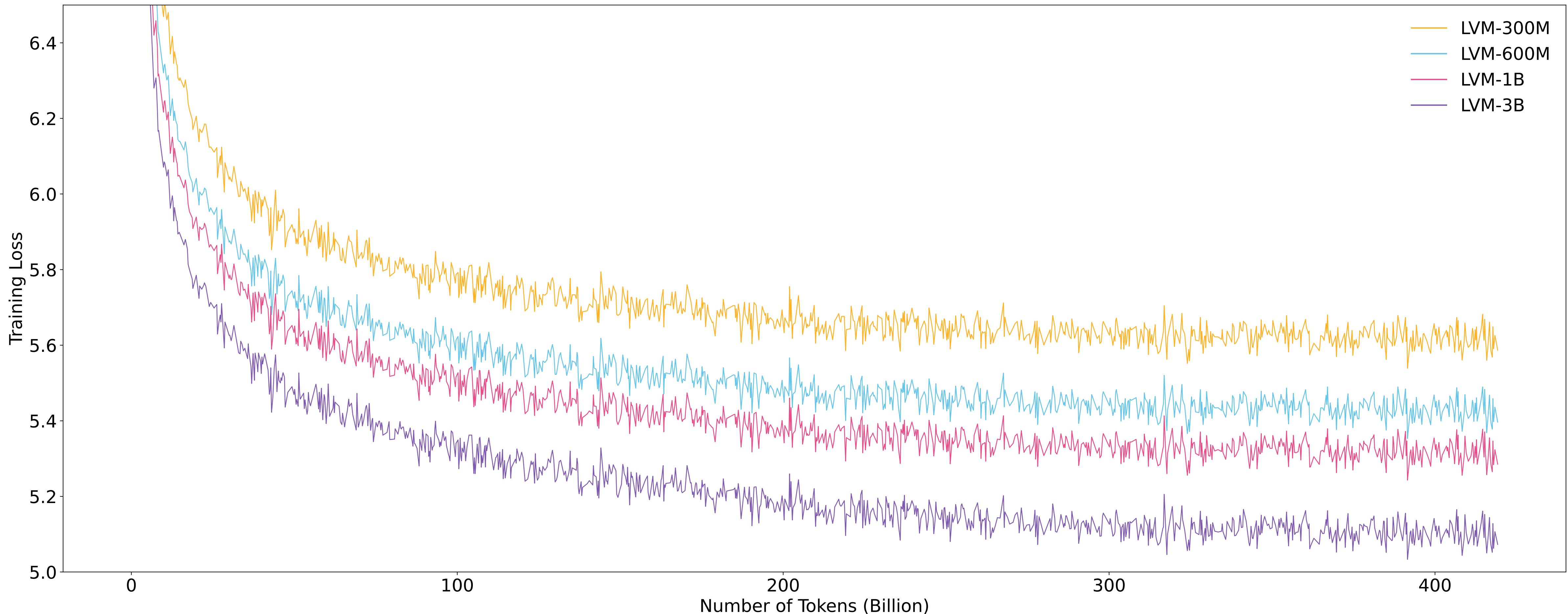
<EOS>



LVM: Large Vision Model

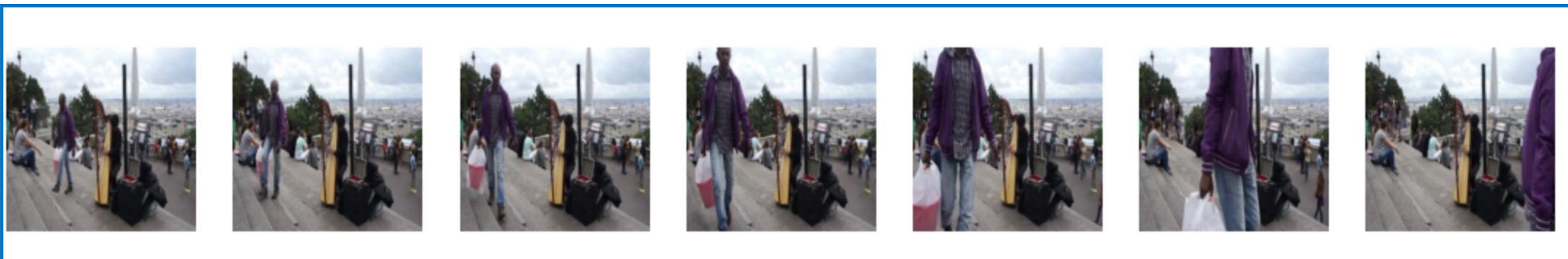


Training Loss (1 epoch) ~ Validation Loss



Sequential Prompting

Prompts



Sequential Prompting

Prompts

Generated



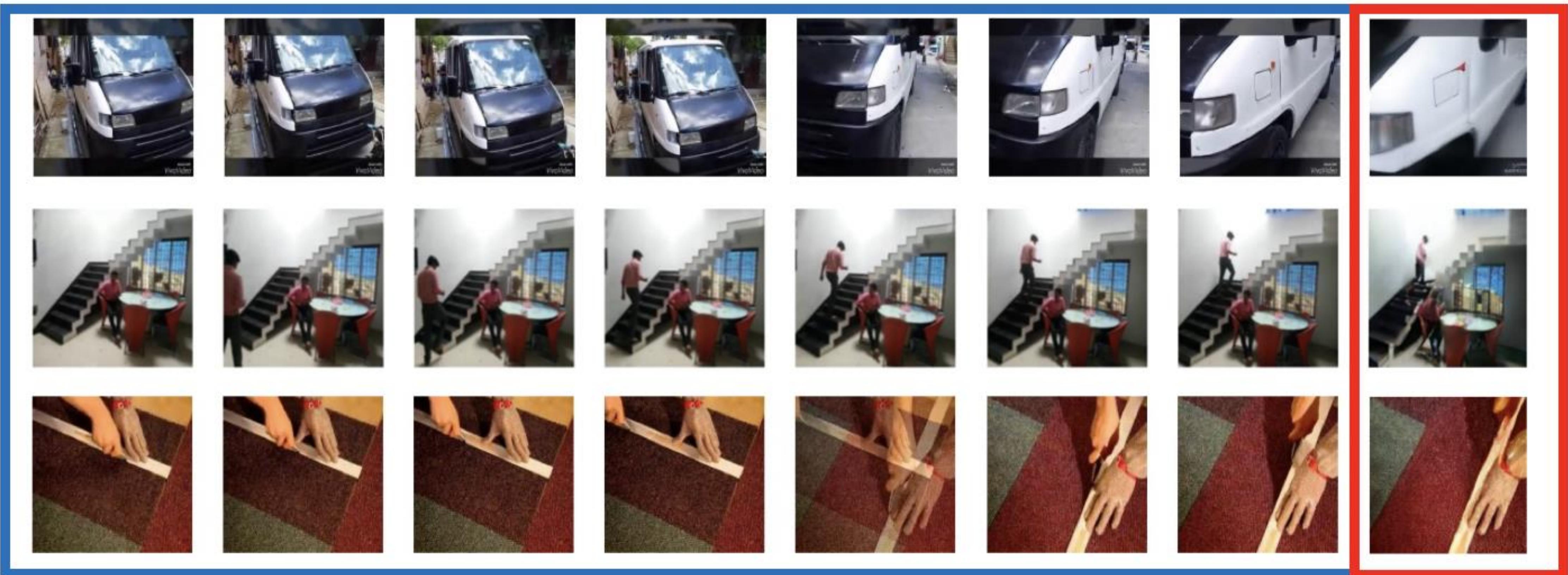
Sequential Prompting



Sequential Prompting

Prompts

Generated

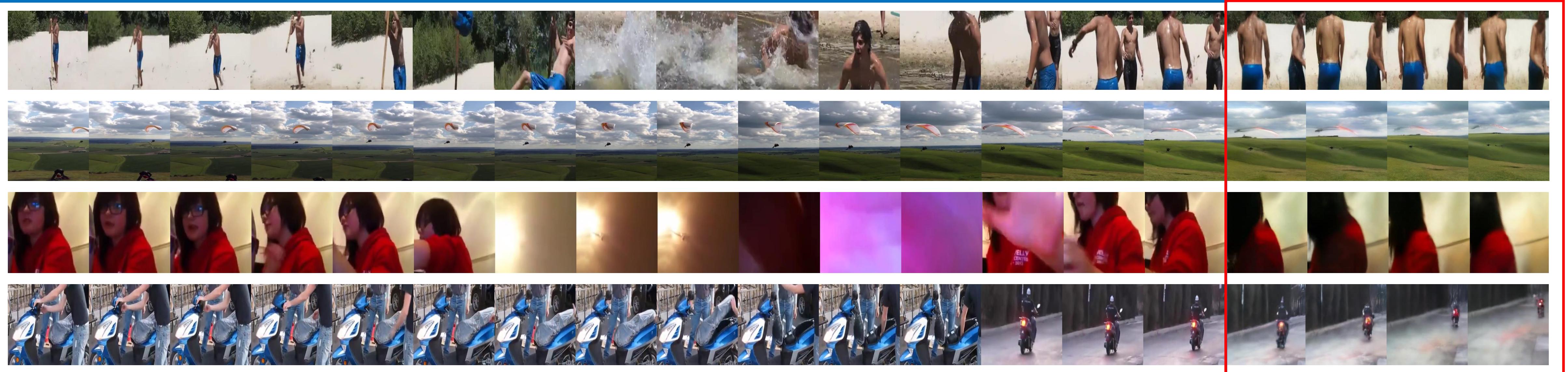


Longer contexts



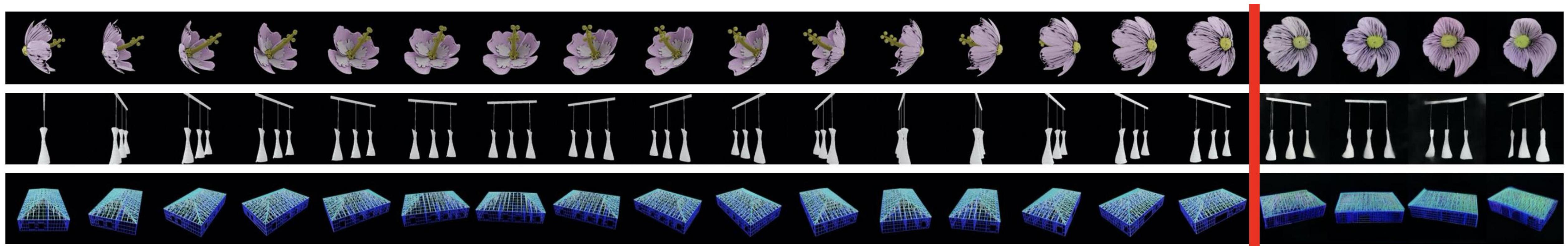
Sequential Prompting

Prompts

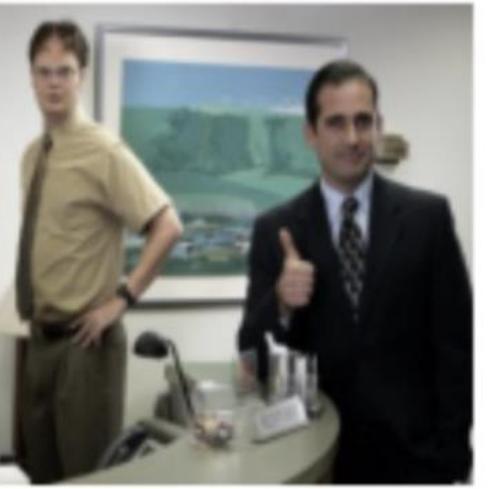
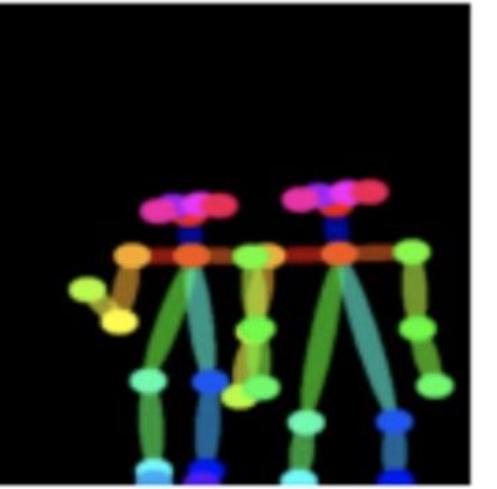
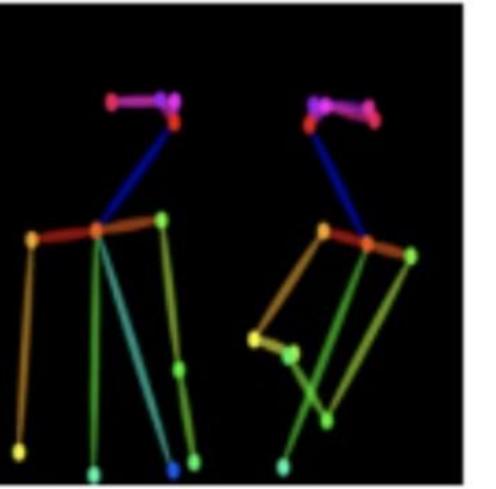
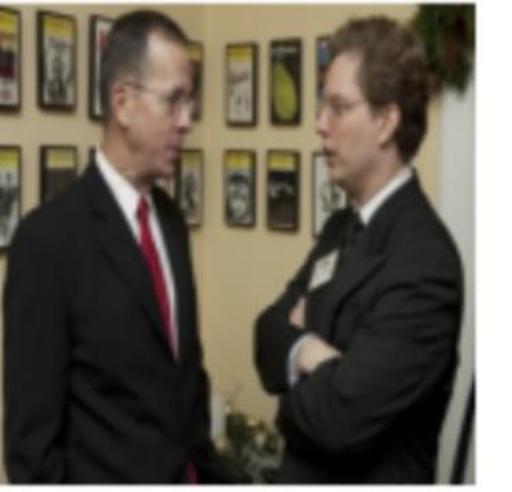
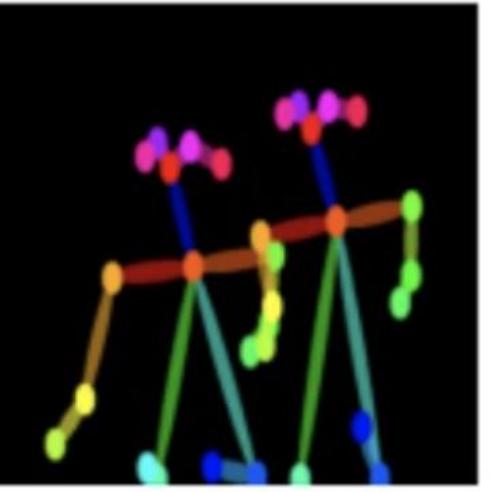


Generated

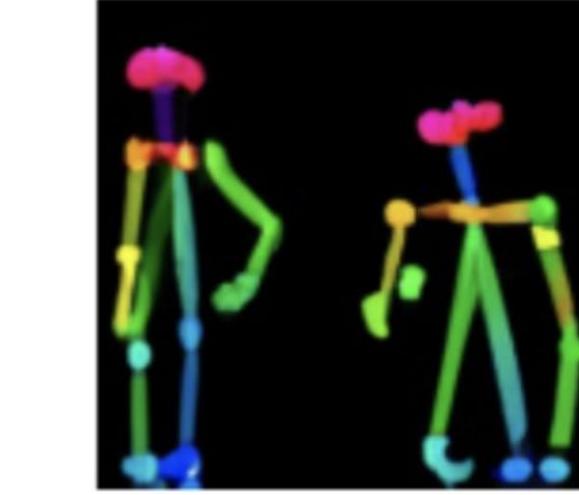
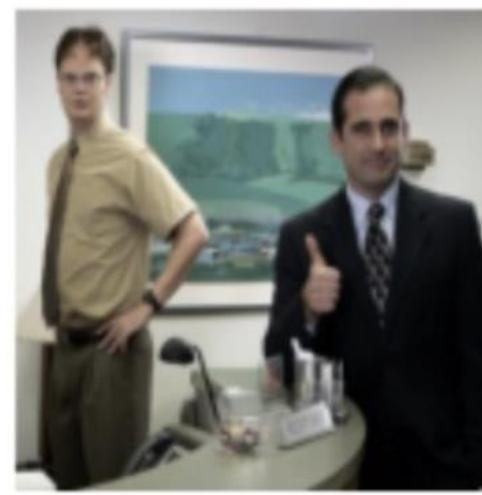
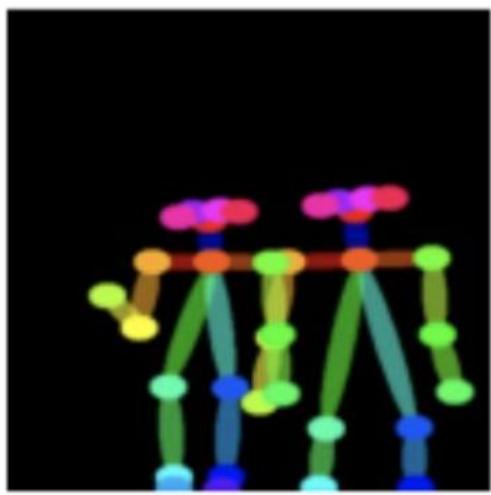
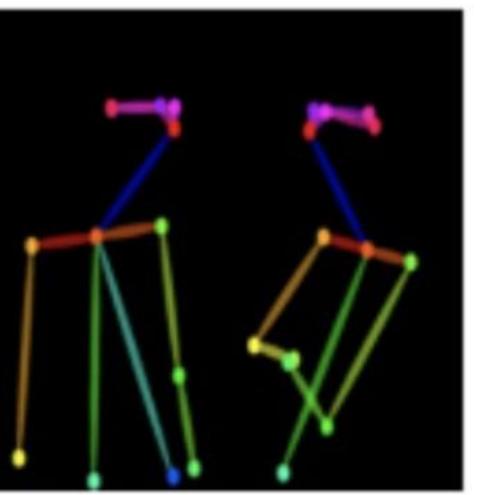
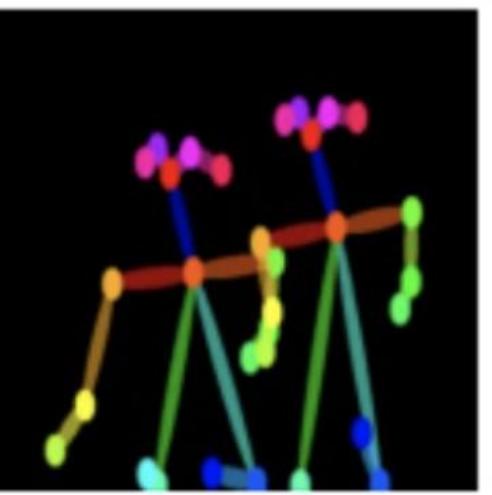
Sequential Prompting



Analogy Prompting

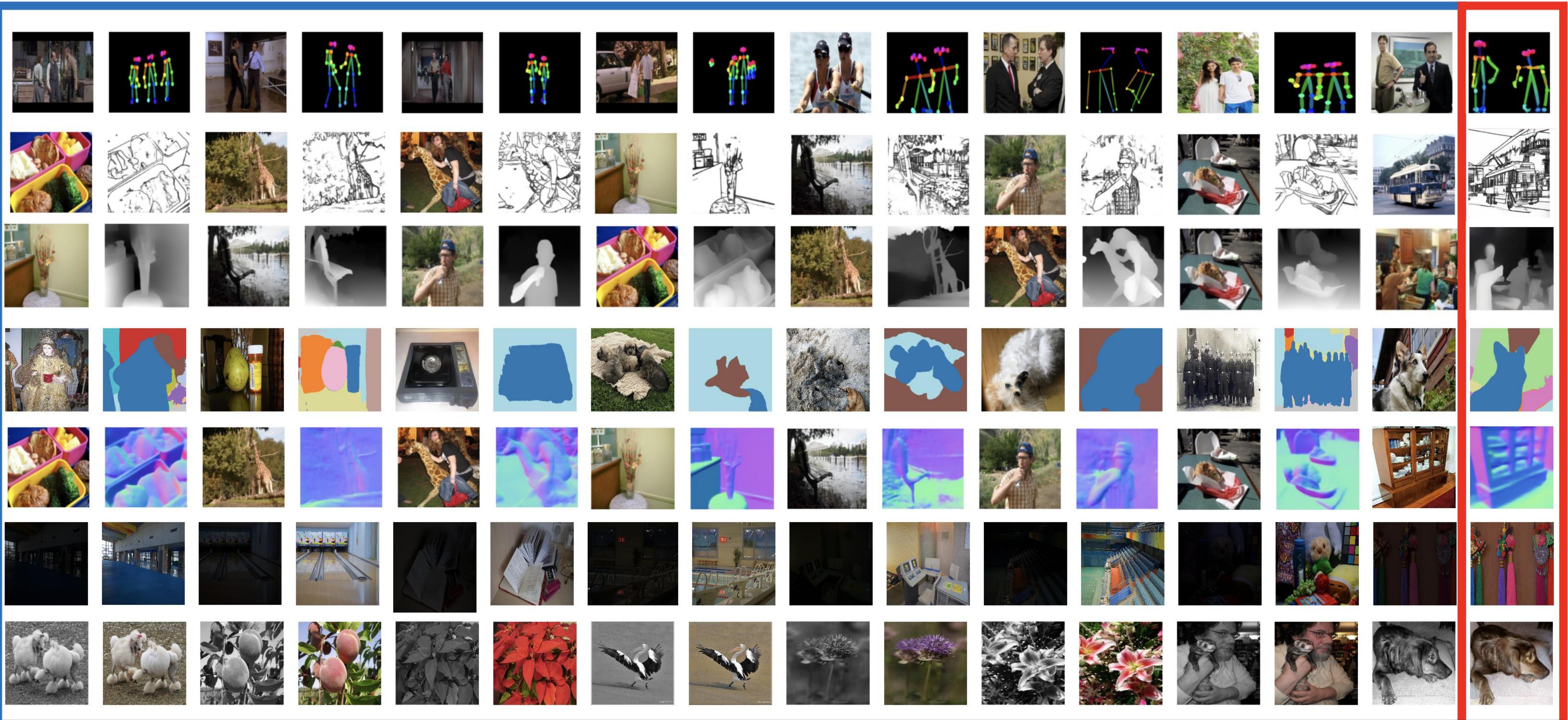


Analogy Prompting



Prompts

Generated



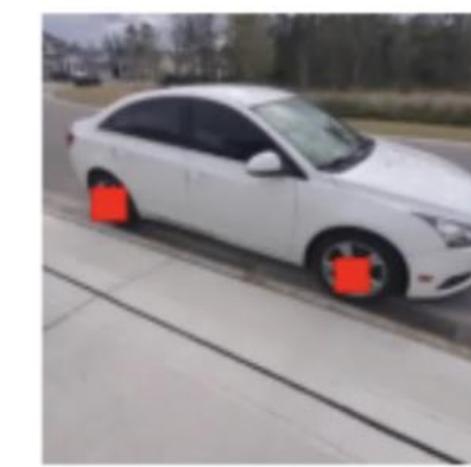
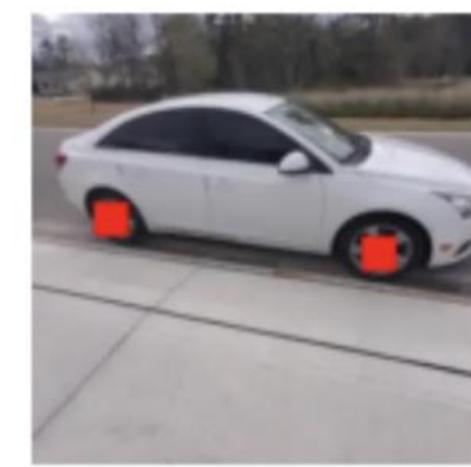
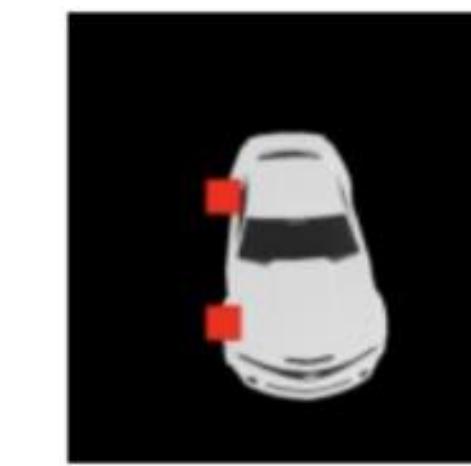
More complicated



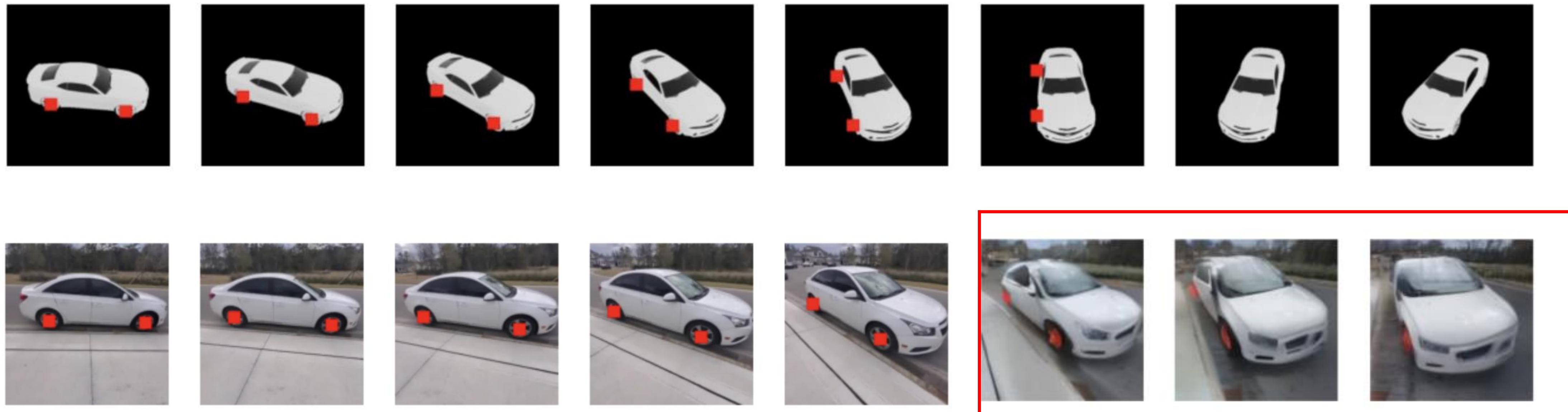
More complicated



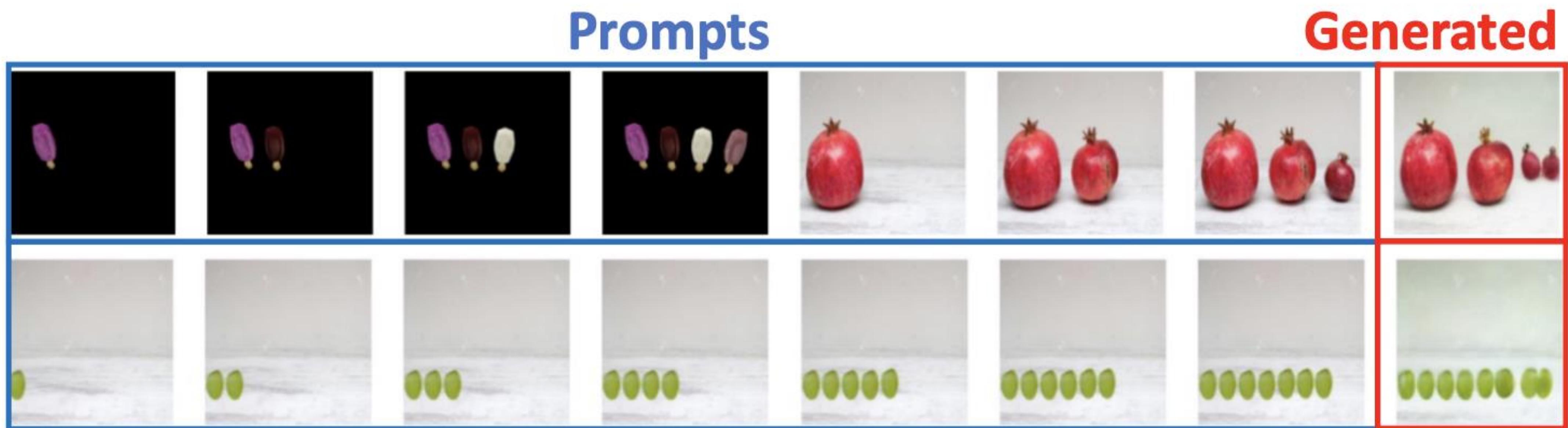
More complicated



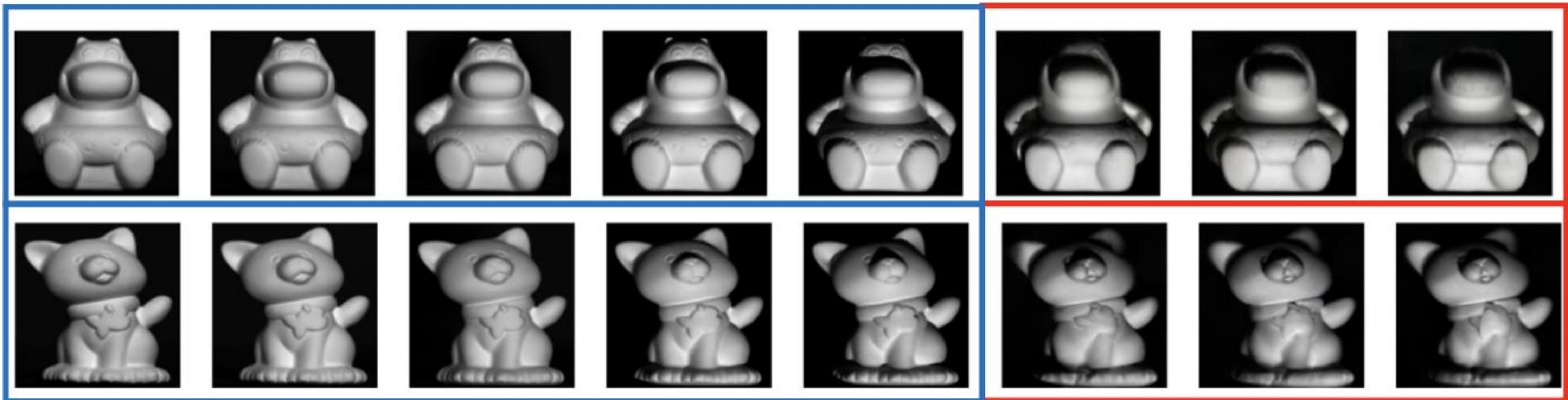
More complicated



Unseen tasks



Unseen tasks



Not easily describable



Not easily describable



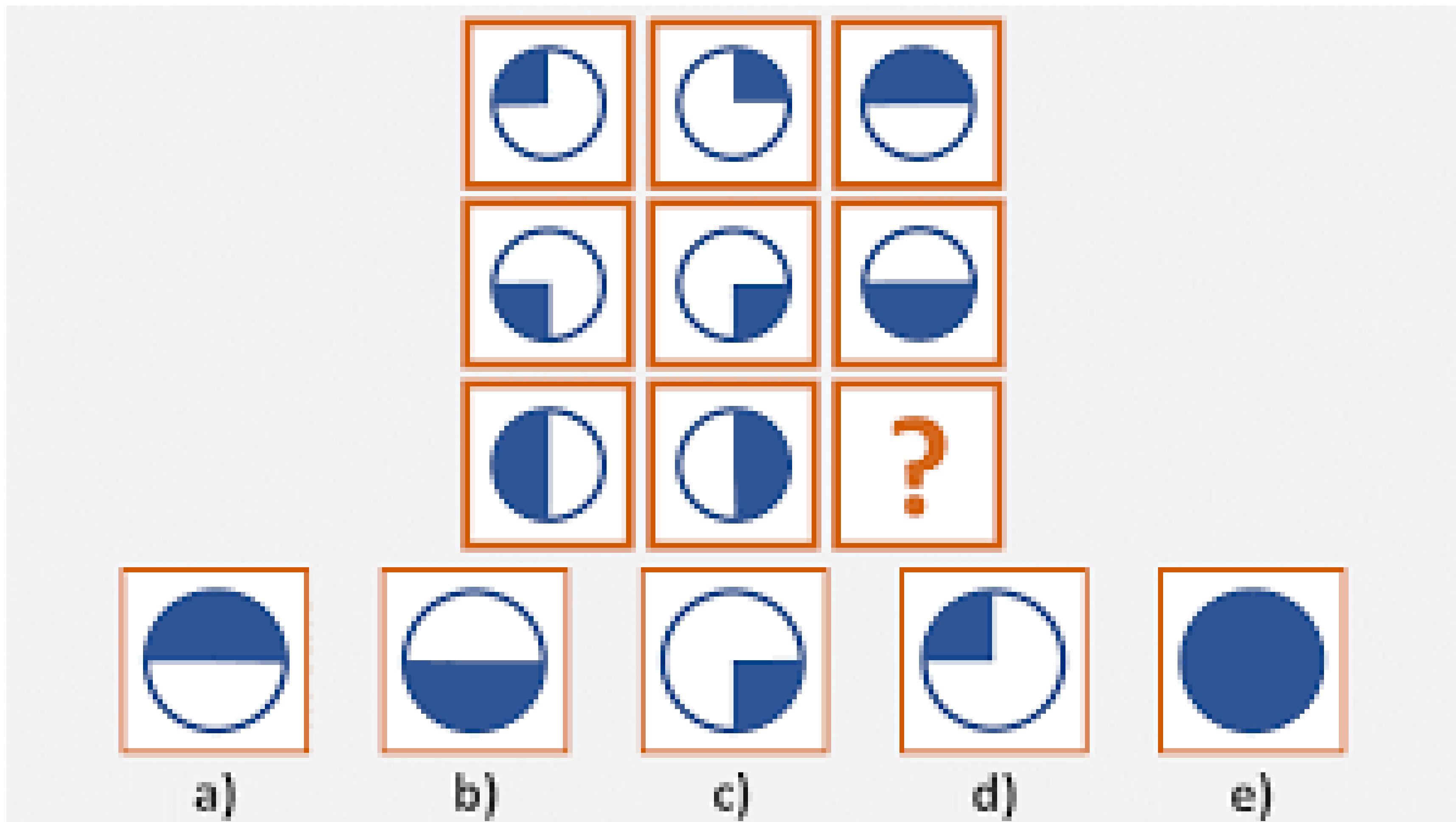
Not easily describable



Not easily describable



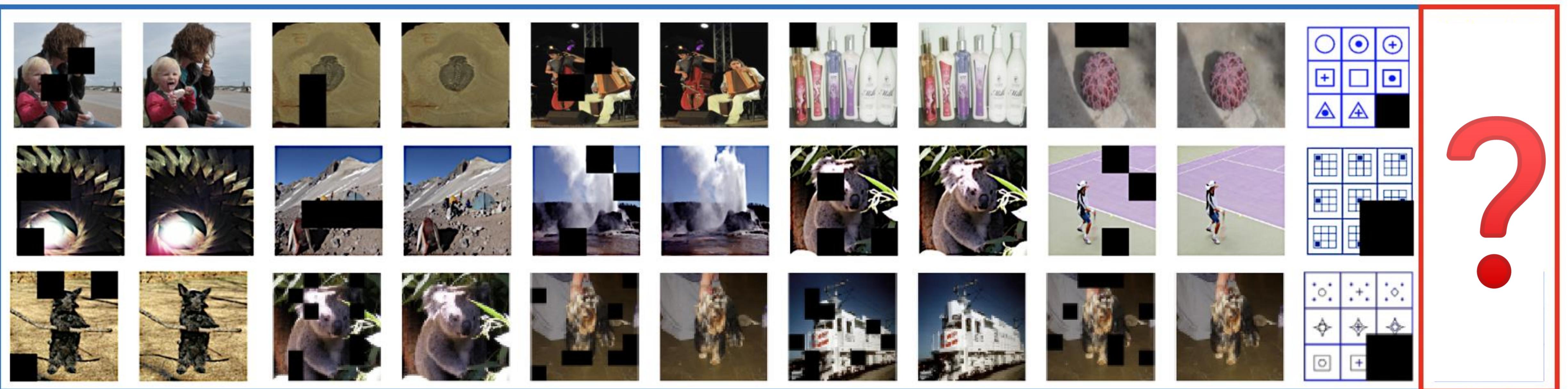
Raven's Progressive Test (Non-verbal IQ test)



Raven, J. C. (1936)

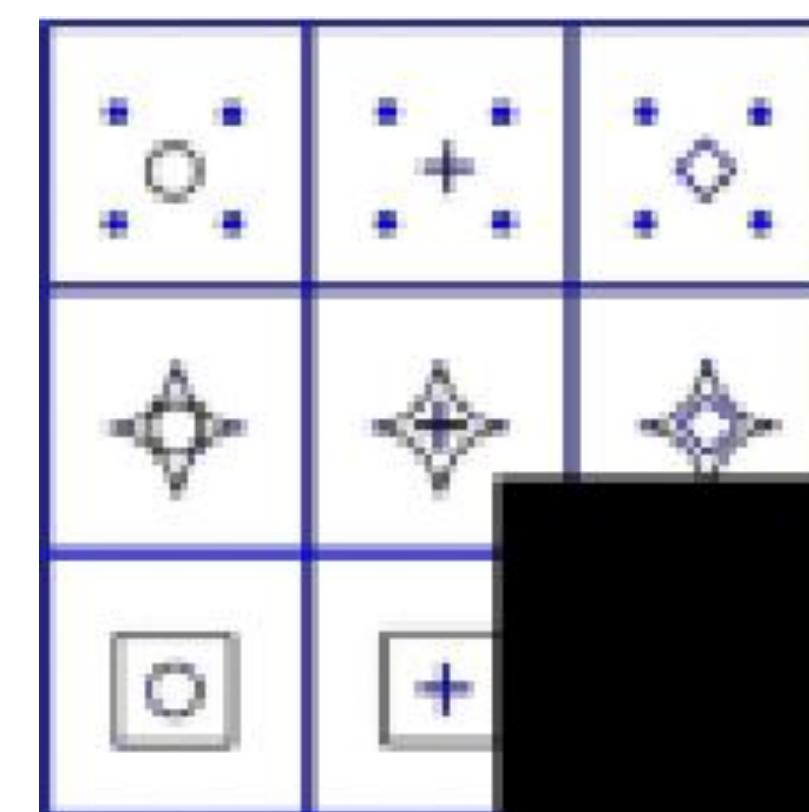
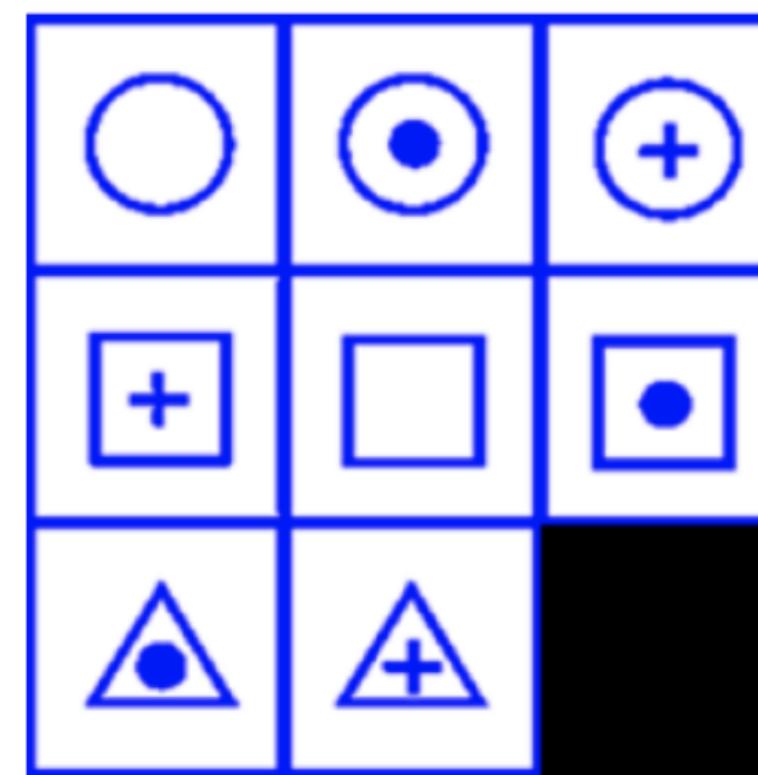
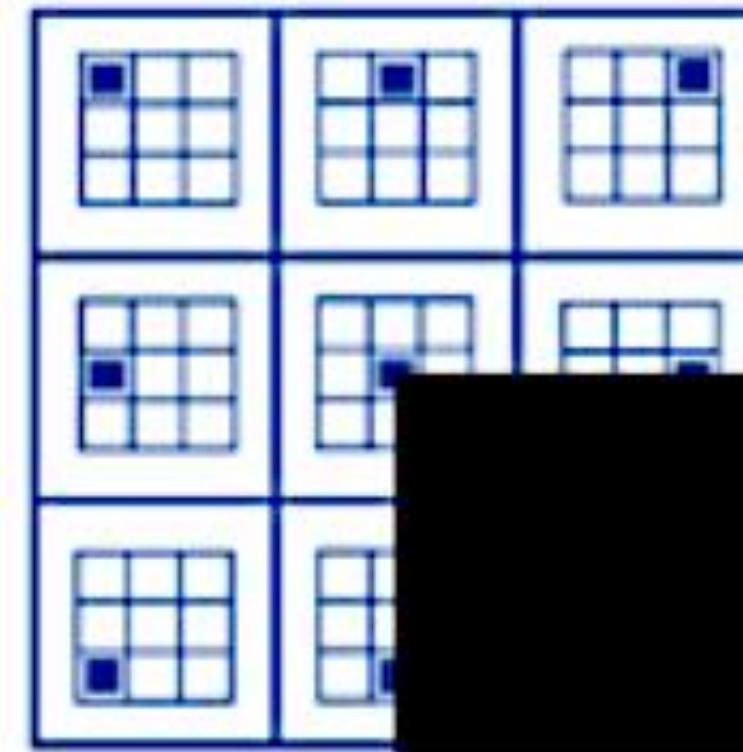
Prompts

Generated

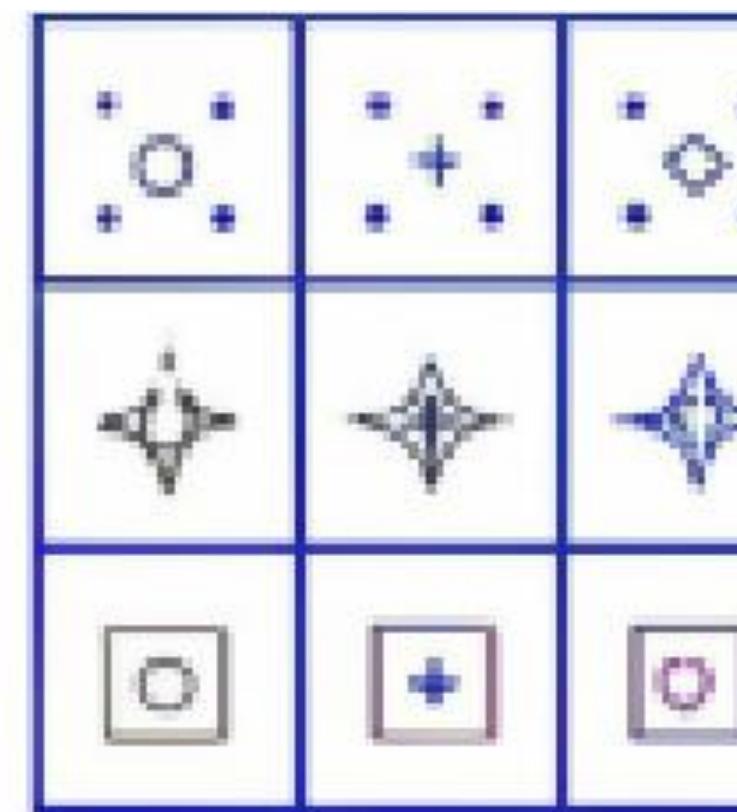
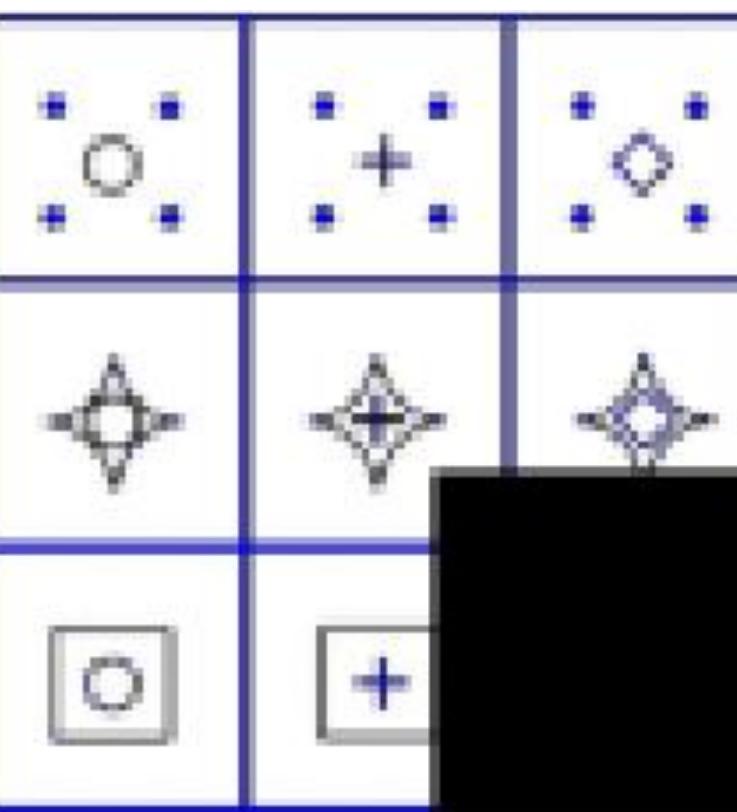
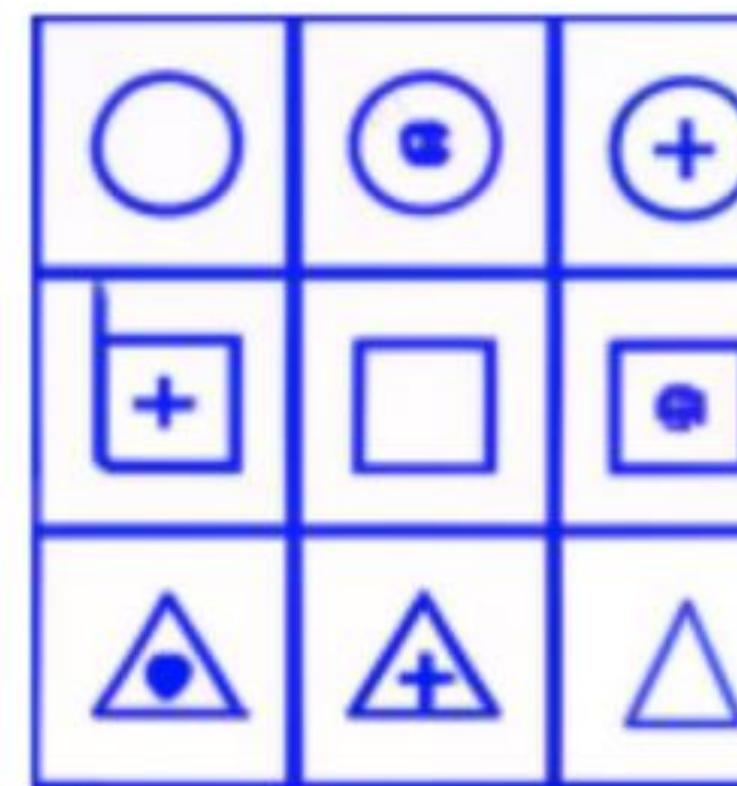
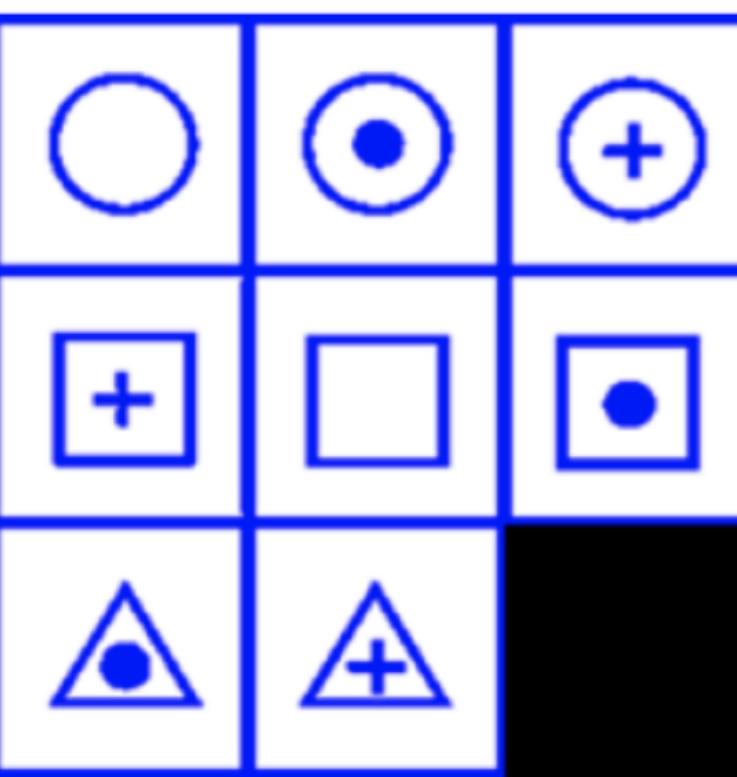
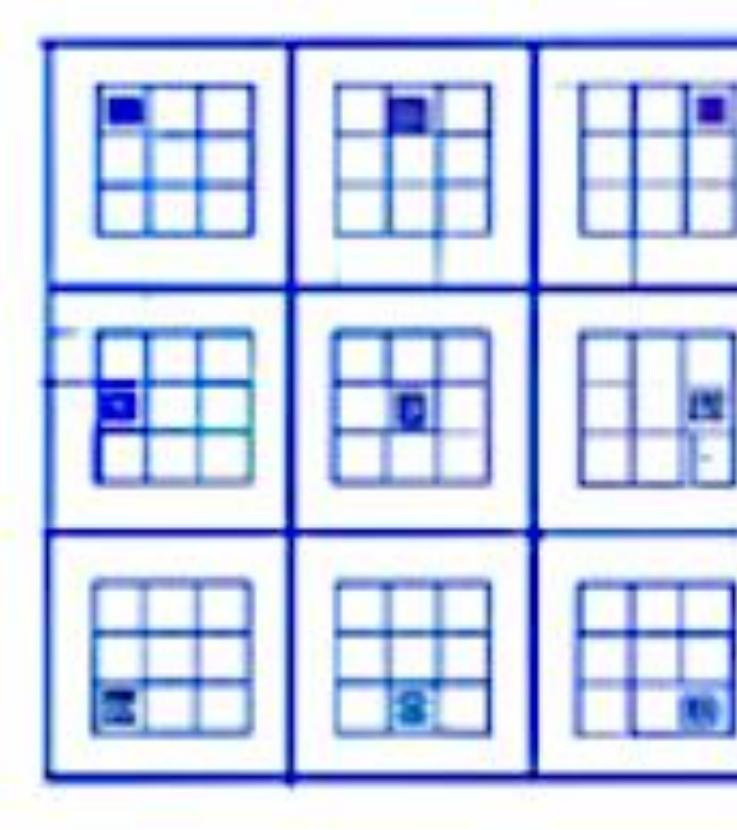
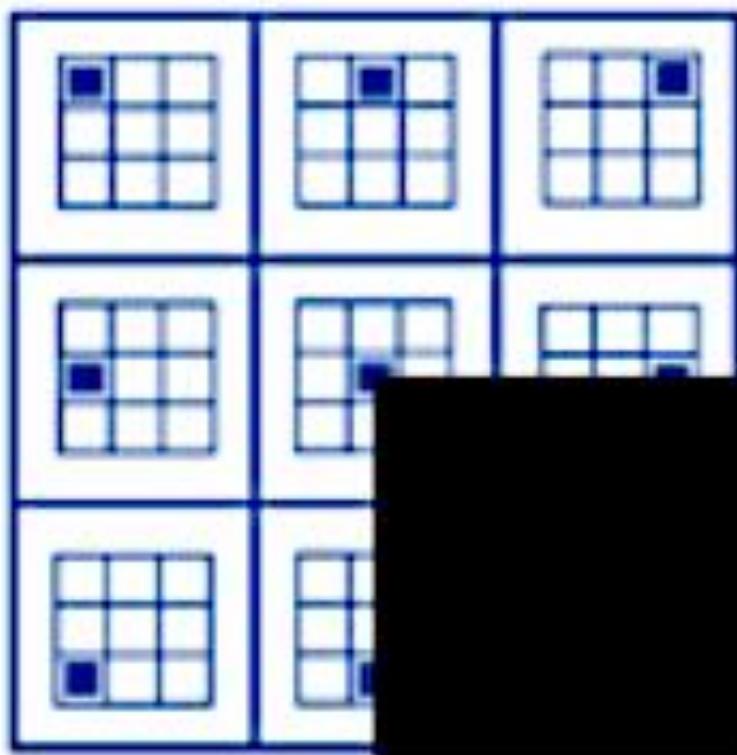


?

Non-verbal IQ test



Non-verbal IQ test



Summary

- The dream of self-supervising ourselves with **natural world data** (rather than text) is alive and well!
- But we are still at the beginning of the journey
- Plenty left to do!

Thank you

